FLOPS AND CLUSTERS IN THE HOMOLOGICAL MINIMAL MODEL PROGRAMME

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ABSTRACT. Suppose that $f: X \to \operatorname{Spec} R$ is a minimal model of a complete local Gorenstein 3-fold, where the fibres of f are at most one dimensional, so by $[\operatorname{VdB}]$ there is a noncommutative ring Λ derived equivalent to X. For any collection of curves above the origin, we show that this collection contracts to a point without contracting a divisor if and only if a certain factor of Λ is finite dimensional, improving a result of [DW2]. We further show that the mutation functor of [IW2, §6] is functorially isomorphic to the inverse of the Bridgeland–Chen flop functor in the case when the factor of Λ is finite dimensional. These results then allow us to jump between all the minimal models of Spec R in an algorithmic way, without having to compute the geometry at each stage. We call this process the Homological MMP.

This has several applications in GIT approaches to derived categories, and also to birational geometry. First, using mutation we are able to compute the full GIT chamber structure by passing to surfaces. We say precisely which chambers give the distinct minimal models, and also say which walls give flops and which do not, enabling us to prove the Craw–Ishii conjecture in this setting. Second, we are able to precisely count the number of minimal models, and also give bounds for both the maximum and the minimum numbers of minimal models based only on the dual graph enriched with scheme theoretic multiplicity. Third, we prove a bijective correspondence between maximal modifying R-module generators and minimal models, and for each such pair in this correspondence give a further correspondence linking the endomorphism ring and the geometry. This lifts the Auslander–McKay correspondence to dimension three.

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1. INTRODUCTION

1.1. Setting. One of the central problems in the birational geometry of 3-folds is to construct, given a suitable singular space $\operatorname{Spec} R$, all its minimal models $X_i \to \operatorname{Spec} R$ and to furthermore pass between them, via flops, in an effective manner.

The classical geometric method of producing minimal models is to take Proj of an appropriate graded ring. It is known that the graded ring is finitely generated, so this method produces a variety equipped with an ample line bundle. However, for many purposes this ample bundle does not tell us much information, and one of the themes of

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this paper, and also other homological approaches in the literature, is that we should be aiming for a much larger (ideally tilting) bundle, one containing many summands, whose determinant bundle recovers the classically obtained ample bundle. These larger bundles, and their noncommutative endomorphism rings, encode much more information about the variety than simply the ample bundle does.

At the same time, passing between minimal models in an effective way is also a rather hard problem in general. There are various approaches to this; one is to hope for some form of GIT chamber decomposition in which wandering around, crashing through appropriate walls, eventually yields all the projective minimal models. Another is just to find a curve, flop, compute all the geometry explicitly, and repeat. Neither is ideal, since both usually require a tremendous amount of calculation. For example the GIT method needs first a calculation of the chamber structure, then second a method to determine what happens when we pass through a wall. Without additional information, and without just computing both sides, standing in any given chamber it is very hard to tell which wall to crash through next in order to obtain a new minimal model.

The purpose of this paper is to demonstrate, in certain cases where we have this larger tilting bundle, that the extra information encoded in the endomorphism ring can be used to produce a very effective homological method to pass between the minimal models, both in detecting which curves are floppable, and also in producing the flop. As a consequence, this then supplies us with the map to navigate the GIT chambers, and the much finer control that this map gives means that our results imply (but are not implied by) many results in derived category approaches to GIT, braiding of flops, and faithful group actions. We outline only some in this paper, as there are a surprising number of other corollaries.

1.2. Overview of the Algorithm. We work over \mathbb{C} . Throughout this introduction, for simplicity of the exposition, the initial geometric input is a crepant projective birational morphism $X \to \operatorname{Spec} R$, with one dimensional fibres, where R is a three dimensional normal Gorenstein complete local ring and X has only Gorenstein terminal singularities. This need not be a flopping contraction, X need not be a minimal model, and R need not have isolated singularities. We remark that many of our arguments work much more generally than this, see §1.5.

Given this input, we associate a noncommutative ring $\Lambda := \operatorname{End}_R(N)$ for some reflexive *R*-module *N*, and a derived equivalence

$$\Psi_X \colon \mathrm{D}^{\mathrm{b}}(\mathrm{coh}\,X) \to \mathrm{D}^{\mathrm{b}}(\mathrm{mod}\,\Lambda) \tag{1.A}$$

as described in [VdB, §3].

It is not strictly necessary, but it is helpful to keep in mind, that a presentation of Λ as a quiver with relations can be obtained by replacing every curve above the origin by a dot (=vertex), and just as in the two-dimensional McKay correspondence we add an additional vertex corresponding to the whole scheme-theoretic fibre. We draw arrows between the vertices if the curves intersect, and there are rules that establish how the additional vertex connects to the others. The loops on vertices correspond to self-extension groups, and so in the case that X is smooth, the loops encode the normal bundle of the curves. This is illustrated in Figure 1, but for details see §2.2.

At its heart, this paper contains two key new ideas. The first is that certain factors of the algebra Λ encode noncommutative deformations of the curves, and thus detects which curves are floppable. The second is that when curves flop we should not view the flop as a variation of GIT, rather we should view the flop as a change in the algebra (via a universal property) whilst keeping the GIT stability constant. See 1.3. Specifically, we prove that the mutation functor of [IW2, §6] is functorially isomorphic to the inverse of the Bridgeland–Chen flop functor [B02, C02] when the curves are floppable. It is viewing the flop via this universal property that gives us the new extra control over the process;

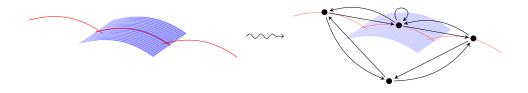


FIGURE 1. From geometry to algebra.

indeed it is the mutated algebra that contains exactly the information needed to iterate, without having to explicitly calculate the geometry at each step.

This new viewpoint, and the control it gives, in fact implies many results in GIT, specifically chamber structures and wall crossing, and also many results in the theory of noncommutative minimal models, in particular producing an Auslander–McKay correspondence in dimension three. We describe the GIT results in §1.3, and the other results in §1.4. In the remainder of this subsection we sketch the algorithm that jumps between the minimal models of Spec R. The process, which we call the Homological MMP, is run as illustrated in Figure 2 on page 5.

The initial input is the crepant morphism $X \to \operatorname{Spec} R$ above, where X has only Gorenstein terminal singularities.

Step 1: Contractions. The first task is to determine which subsets of the curves contract to points without contracting a divisor, and can thus be flopped. Although this is usually obvious at the input stage (we generally understand the initial input), it becomes important after the flop if we are to continue running the programme.

Let C be the scheme-theoretic fibre above the unique closed point of Spec R, so that taking the reduced scheme structure we obtain $\bigcup_{i=1}^{n} C_i$ with each $C_i \cong \mathbb{P}^1$. We pick a subset of the curves, say $I \subseteq \{1, \ldots, n\}$, and ask whether $\bigcup_{i \in I} C_i$ contracts to a point without contracting a divisor. Corresponding to each curve C_i is an idempotent e_i in the algebra $\Lambda := \operatorname{End}_R(N)$ from (1.A), and we set $\Lambda_I := \Lambda/\Lambda(1 - \sum_{i \in I} e_i)\Lambda$. Our first main result, a refinement of [DW2], is the following.

Theorem 1.1 (=3.5). $\bigcup_{i \in I} C_i$ contracts to a point without contracting a divisor if and only if $\dim_{\mathbb{C}} \Lambda_I < \infty$.

In fact 1.1 is true regardless of the singularities on X and Spec R, and needs no assumptions on crepancy. Contracting the curves $\bigcup_{i \in I} C_i$, which we can do at will since R is complete local, yields a diagram

 $\begin{array}{cccc}
X & g \\
& X_{\text{con}} \\
& f & \downarrow h \\
& \text{Spec } R
\end{array}$ (1.B)

By [DW2] there is a contraction algebra A_{con} , constructed with respect to the morphism g, that detects whether the curves in I contract to a point without contracting a divisor. The subtlety in the proof of 1.1 is that Λ and thus Λ_I is constructed with respect to the morphism f, so to establish 1.1 requires us to relate the algebras A_{con} and Λ_I . It turns out that they are isomorphic, but this can only be established by appealing to a universal property. There is not even any obvious morphism between them.

Step 2: Mutation and Flops. We again pick a subset of curves $\{C_i \mid i \in I\}$, but for simplicity in this introduction we assume that there is only one curve C_i (i.e. $I = \{i\}$), although this paper does also cover the general situation, and all of the theorems stated here have multi-curve analogues. The curve C_i corresponds to an indecomposable summand N_i of the *R*-module *N*. By Step 1 the curve C_i flops if and only if $\dim_{\mathbb{C}} \Lambda_i < \infty$. Regardless of whether it flops or not, we can always categorically mutate the module *N* with respect to the summand N_i , in the sense of [IW2, §6], to produce another module $\nu_i N$ (possibly equal to *N*), together with a derived equivalence

$$\Phi_i \colon \mathrm{D}^{\mathrm{b}}(\mathrm{mod}\,\Lambda) \to \mathrm{D}^{\mathrm{b}}(\mathrm{mod}\,\nu_i\Lambda)$$

where $\mathbf{v}_i \Lambda := \operatorname{End}_R(\mathbf{v}_i N)$. See §2.3 for definitions and details. This requires no assumptions on the singularities of X, but does require R to be normal Gorenstein. Note that the categorical mutation used here is inspired by, but in many ways is much different than, the mutation in cluster theory and elsewhere in the literature. The main point is that the mutation here tackles the situation where there are loops, 2-cycles, and no superpotential, which is the level of generality needed to apply the results to possibly singular minimal models. Consequently, this mutation is not just a simple combinatorial rule (unlike, say, Fomin–Zelevinsky mutation from cluster theory), however in practice $\mathbf{v}_i \Lambda$ can still be calculated easily.

The following is our next main result. When C_i flops, we denote the flop by X^+ .

Theorem 1.2 (=4.2, 4.20). With the notation as above,

- (1) The irreducible curve C_i flops if and only if $v_i N \neq N$.
- (2) If Γ denotes the natural algebra associated to the flop X^+ [VdB], then $\Gamma \cong \nu_i \Lambda$.
- (3) If further $X \to \operatorname{Spec} R$ is a minimal model, and $\dim_{\mathbb{C}} \Lambda_i < \infty$, then

$$\Phi_i \cong \Psi_{X^+} \circ \mathsf{Flop} \circ \Psi_X^{-1}$$

where Ψ are the functors in (1.A), and Flop is the inverse of the flop functor of Bridgeland-Chen [B02, C02].

The first part of the theorem allows us later to give a lower bound on the number of minimal models, and it turns out that the third part is one half of a dichotomy, namely

$$\Phi_i \cong \begin{cases} \Psi_{X^+} \circ \mathsf{Flop} \circ \Psi_X^{-1} & \text{if } \dim_{\mathbb{C}} \Lambda_i < \infty \\ \Psi_X \circ \mathsf{Twist} \circ \Psi_X^{-1} & \text{if } \dim_{\mathbb{C}} \Lambda_i = \infty, \end{cases}$$

where Twist is a Fourier–Mukai twist-like functor over a noncommutative one-dimensional scheme. We do not give the details here, as a more general treatment is given in [DW4].

We also remark that the proof of 1.2 does not need or refer to properties of the generic hyperplane section, so there is a good chance that in future we will be able to remove the assumption that X has only Gorenstein terminal singularities, see B.2.

However, of the results in 1.2, it is part two that is the key, since it allows us to iterate. First, 1.2(2) allows us to immediately read off the dual graph of the flop without explicitly calculating it in coordinates, since the dual graph can be read off from the mutated quiver. Second, and most importantly, combining 1.2(2) with 1.1 (applied to $\nu_i \Lambda$) allows us to detect which curves are contractible *after the flop* by inspecting factor algebras of the form $\nu_i \Lambda / \nu_i \Lambda (1 - e) \nu_i \Lambda$. There is no way of seeing this information on the original algebra Λ , which is one of the main reasons why fixing Λ and changing the stability there does not lend itself easily to iterations. Hence we do not change GIT stability, we instead change the algebra by plugging $\nu_i \Lambda$ back in as the new input, and continue the programme in an algorithmic way. This is summarised in Figure 2.

1.3. Applications to GIT. There are various other outputs to the Homological MMP that for clarity have not been included in Figure 2. One such output, when the curve does flop, is obtained by combining 1.2(2) with [Kar, 5.2.5]. This shows that it is possible to output the flop as a fixed, specified, GIT moduli space of the mutated algebra.

As notation, for any algebra $\Gamma := \operatorname{End}_R(N)$ with $\Gamma \in \operatorname{CM} R$, we denote the dimension vector given by the ranks of the summands of N by rk. If N is a generator, that is N contains R as a summand, then the GIT chamber decomposition $\Theta(\Gamma)$ associated to

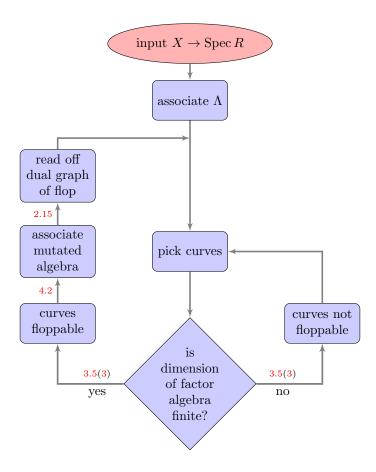


FIGURE 2. The Homological MMP, jumping between minimal models.

 Γ (with dimension vector rk) has co-ordinates ϑ_i for $i \neq 0$, where by convention ϑ_0 corresponds to the summand R of N. We consider the region

$$C_{+}(\Gamma) := \{ \vartheta \in \Theta(\Gamma) \mid \vartheta_i > 0 \text{ for all } i > 0 \}.$$

As usual, we let $\mathcal{M}_{\mathsf{rk},\Phi}(\Lambda)$ denote the moduli space of ϕ -semistable Λ -modules of dimension vector rk.

Corollary 1.3 (=4.19). With setup $X \to \operatorname{Spec} R$ as above, choose C_i and suppose that $\dim_{\mathbb{C}} \Lambda_i < \infty$, so that C_i flops. Then

- (1) $\mathcal{M}_{\mathsf{rk}, \phi}(\Lambda) \cong X \text{ for all } \phi \in C_{+}(\Lambda).$ (2) $\mathcal{M}_{\mathsf{rk}, \phi}(\nu_{i}\Lambda) \cong X^{+} \text{ for all } \phi \in C_{+}(\nu_{i}\Lambda).$

This allows us to view the flop as changing the algebra but keeping the GIT chamber structure fixed, and so since mutation is easier to control than GIT wall crossing, 1.3implies, but is not implied by, results in GIT. Mutation always induces a derived equivalence, and it turns out that it is possible to track the moduli space in 1.3(2) back across the equivalence to obtain the flop as a moduli space on the original algebra. Again, as in Step 1 in $\S1.2$, the subtlety is that the flop of Bridgeland–Chen is constructed as a moduli with respect to the morphism q in (1.B), whereas here we want to establish the flop as a moduli with respect to global information associated to the morphism f.

The following moduli-tracking theorem allows us to do this. Later, we prove it in much greater generality, and with multiple summands.

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Proposition 1.4 (=5.13(1)). Let S be a d-dimensional complete local normal Gorenstein ring, $M \in \operatorname{ref} R$ with $\Lambda := \operatorname{End}_S(M) \in \operatorname{CM} R$, and suppose that $\nu_i M$ satisfies the technical assumptions in 5.12. Consider the minimal left $\operatorname{add}(\oplus_{j\neq i}M_j)$ -approximation of M_i , namely

$$0 \to M_i \to \bigoplus_{j \neq i} M_j^{\oplus b_j}$$

Suppose that β is a dimension vector, and ϑ is a stability condition on Λ with $\vartheta_i > 0$. Then as schemes $\mathcal{M}_{\beta,\vartheta}(\Lambda) \cong \mathcal{M}_{\nu_i\beta,\nu_i\vartheta}(\nu_i\Lambda)$, where the vectors $\nu_i\beta$ and $\nu_i\vartheta$ are given by

$$(\mathbf{v}_i \boldsymbol{\beta})_t = \begin{cases} \boldsymbol{\beta}_t & \text{if } t \neq i \\ \left(\sum_{j \neq i} b_j \boldsymbol{\beta}_j\right) - \boldsymbol{\beta}_i & \text{if } t = i \end{cases} \qquad (\mathbf{v}_i \boldsymbol{\vartheta})_t = \begin{cases} \boldsymbol{\vartheta}_t + b_t \boldsymbol{\vartheta}_i & \text{if } t \neq i \\ -\boldsymbol{\vartheta}_i & \text{if } t = i \end{cases}$$

The technical assumptions in 1.4 hold for flopping contractions, and they also hold automatically for any noncommutative crepant resolution (=NCCR) or maximal modification algebra (=MMA) in dimension three. Thus 1.4 can be applied to situations where the fibre is two-dimensional, and we expect to be able to extend some of the techniques in this paper to cover general minimal models of general Gorenstein 3-folds. We also remark that 1.4 is known in special situations; it generalises [SY, 3.6, 4.20], which dealt with Kleinian singularities, and [NS, 6.12], which dealt with specific examples of smooth 3-folds with mutations of NCCRs given by quivers with potentials at vertices with no loops.

It is also possible to track moduli from $\nu_i \Lambda$ to moduli on Λ , see 5.13(2). This leads to the following corollary.

Corollary 1.5 (=5.23). With the running hypothesis $f: X \to \text{Spec } R$ as above, assume that either f is a flopping contraction, or a minimal model. Let $\Lambda := \text{End}_R(N)$ from (1.A), where N automatically has R as a summand, and consider the GIT chamber decomposition Θ associated to Λ , with co-ordinates ϑ_i for $i \neq 0$ (where ϑ_0 corresponds to the summand R of N). Pick an indecomposable non-free summand N_i , and consider the b_j defined in 1.4 (for the case M := N). Then the region

$$\vartheta_i < 0, \quad \vartheta_j + b_j \vartheta_i > 0 \text{ for all } j \neq i$$

defines a chamber in $\Theta(\Lambda)$, and for any parameter ϑ inside this chamber,

$$\mathcal{M}_{\mathsf{rk},\vartheta}(\Lambda) \cong \begin{cases} X^+ & \text{if } C_i \text{ flops} \\ X & \text{else,} \end{cases}$$

where X^+ denotes the flop of X at C_i . Thus the flop, if it exists, is obtained by crashing through the single wall $\vartheta_i = 0$ in $\Theta(\Lambda)$.

Of course, our viewpoint is that 1.5 should be viewed as a *consequence* of the Homological MMP, since without the extra data the Homological MMP offers, it is hard to say which should be the next wall to crash through, and then which wall to crash through after that. The information in the next chamber needed to iterate is contained in $\nu_i \Lambda$, not the original Λ . Mutation allows us to successfully track this data, and as a consequence we obtain the following corollary.

Corollary 1.6 (=6.2(1)). There exists a connected path in the GIT chamber decomposition of Λ where every minimal model of Spec R can be found, and each wall crossing in this path corresponds to the flop of a single curve.

We remark that 1.6 was verified in specific quotient singularities in [NS, 1.5], and is also implicit in the setting of cA_n singularities in [IW3, §6], but both these papers relied on direct calculations. The Homological MMP removes the need to calculate.

The following conjecture is an extension to singular minimal models of a conjecture posed by Craw–Ishii [CI], originally for quotient singularities and their NCCRs.

Conjecture 1.7 (Craw–Ishii). Suppose that S is an arbitrary complete local normal Gorenstein 3-fold with rational singularities, and $\operatorname{End}_R(N)$ is an MMA where $R \in \operatorname{add} N$. Then every projective minimal model of Spec R can be obtained as a quiver GIT moduli space of $\operatorname{End}_R(N)$.

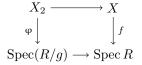
There are versions of the conjecture for rings R that are not complete local, but in the absence of a grading, which for example exists for quotient singularities, there are subtleties due to the failure of Krull–Schmidt. Nevertheless, a direct application of 1.6 gives the following result.

Corollary 1.8 (=6.2(2)). The Craw–Ishii conjecture is true for all compound du Val (=cDV) singularities.

In fact we go further than 1.6 and 1.8, and describe the whole GIT chamber structure. In principle this is hard, since obtaining the numbers b_j needed in 1.4 directly on the 3-fold is difficult without explicit knowledge of Λ or indeed without knowing the explicit equation defining R. However, the next result asserts that mutation is preserved under generic hyperplane sections, and this allows us to obtain the numbers b_j by reducing to the case of Kleinian surface singularities, about which all is known.

Lemma 1.9 (=5.20). With the setup $X \to \operatorname{Spec} R$ as above, if g is a sufficiently generic hyperplane section, then $\Lambda/g\Lambda \cong \operatorname{End}_{R/gR}(N/gN)$, and minimal approximations are preserved under tensoring by R/gR.

For a more precise wording, see 5.20. Now by Reid's general elephant conjecture, true in the setting here by [Re, 1.1, 1.14], cutting by a generic hyperplane section yields



where R/g is an ADE singularity and φ is a partial crepant resolution. Since $N \in CM R$ and g is not a zero-divisor on N, necessarily $N/gN \in CM R/g$, and so any indecomposable summand N_i of N cuts to N_i/gN_i , which must correspond to a vertex in an ADE Dynkin diagram via the Auslander–McKay correspondence. This then allows us to obtain the numbers b_j using Auslander–Reiten (=AR) theory, using the knitting–type constructions on the known AR quivers, as in [IW1]. We refer the reader to §5.4 for details, in particular the example 5.26.

Once we have obtained the b_j for all exchange sequences, which in particular depends only on the curves which appear in the partial resolution X_2 , we are able to use this data to do two things. First, we are able to compute the full GIT chamber structure.

Corollary 1.10 (=5.18, 5.24, 5.25). In the setup $X \to \text{Spec } R$ above, suppose that f is a minimal model, or a flopping contraction. Set $\Lambda := \text{End}_R(N)$ from (1.A). Then

- (1) $C_{+}(\Lambda)$ is a chamber in Θ .
- (2) For sufficiently generic $g \in R$, the chamber structure of Θ for Λ is the same as the chamber structure for $\operatorname{End}_{R/gR}(N/gN)$. There are a finite number of chambers, and the walls are given by a finite collection of hyperplanes containing the origin. The co-ordinate hyperplanes $\vartheta_i = 0$ are included in this collection.
- (3) Tracking all the chambers $C_+(\mathbf{v}_{i_t} \dots \mathbf{v}_{i_1} \Lambda)$ through mutation, via knitting combinatorics, gives the full chamber structure of Θ .

We list and draw some examples in 5.26 and §7. In the course of the proof of 1.10, if Π denotes the preprojective algebra of an extended Dynkin diagram and e is an idempotent containing the extending vertex, then in 5.24 we describe the chamber structure of $\Theta(e\Pi e)$ by intersecting hyperplanes with a certain subspace in a root system, a result which may be of independent interest. It may come as a surprise that the resulting chamber structures

are *not* in general the root system of a Weyl group, even up to an appropriate change of parameters, and this has implications to the braiding of flops [DW3] and faithful group actions [HW]. It also means, for example, that any naive extension of [T1] or [BIKR, DH] is not possible, since root systems and Weyl groups do not necessarily appear. However, this phenomenon will come as no surprise to Pinkham [P, p366].

Second, we are able to give minimal as well as maximal bounds on the number of minimal models, based only on the curves which appear in the partial resolution X_2 . The Homological MMP enriches the GIT chamber structure not only with the mutated quiver (allowing us to iterate), but by 1.9 it also enriches it with the information of the curves appearing after cutting by a generic hyperplane. Certainly if two minimal models X and Y cut under generic hyperplane section to two different curve configurations, then X and Y must be different minimal models. The surface curve configurations obtained via mutation can be calculated very easily using knitting combinatorics, so keeping track of this extra information (see e.g. 7.3) allows us to enhance the chamber structure, and to improve upon the results of [P] as follows.

Corollary 1.11 (=5.28). Suppose that R is a cDV singularity, with a minimal model $X \to \operatorname{Spec} R$. Set $\Lambda := \operatorname{End}_R(N)$ as in (1.A). By passing to a general hyperplane section g as in 1.10, the number of minimal models of $\operatorname{Spec} R$ is bounded below by the number of different curve configurations obtained in the enhanced chamber structure of $\Theta(\Lambda/q\Lambda)$.

A closer analysis (see e.g. 5.27) reveals that it is possible to obtain better lower bounds, also by tracking mutation, but we do not detail this here. See $\S5.4$ and $\S7.1$.

1.4. Auslander–McKay Correspondence. There are also purely algebraic outputs of the Homological MMP. One such output is that we are able to lift the Auslander–McKay correspondence from dimension two [A86] to 3-fold compound du Val singularities. One feature is that for 3-folds, unlike for surfaces, there are two correspondences. First, there is a correspondence (1.C) between maximal modifying (=MM) R-module generators and minimal models, and then for each such pair there is a further correspondence (in parts (1) and (2) below) along the lines of the classical Auslander–McKay Correspondence. Parts (3) and (4), the relationship between flops and mutation, describe how these two correspondences relate.

Corollary 1.12 (=4.10, 4.24). Let R be a complete local cDV singularity. Then there exists a one-to-one correspondence

 $\{basic MM R\text{-module generators}\} \longleftrightarrow \{minimal models f_i: X_i \to \operatorname{Spec} R\}$ (1.C)

where the left-hand side is taken up to isomorphism, and the right-hand side is taken up to isomorphism of the X_i compatible with the morphisms f_i . Under this correspondence

- (1) For any fixed MM generator, its non-free indecomposable summands are in oneto-one correspondence with the exceptional curves in the corresponding minimal model.
- (2) For any fixed MM generator N, the quiver of $\underline{\operatorname{End}}_R(N)$ (for definition see 4.9) encodes the dual graph of the corresponding minimal model.
- (3) The full mutation graph of the MM generators coincides with the full flops graph of the minimal models.
- (4) The derived mutation groupoid of the MM generators is functorially isomorphic to the derived flops groupoid of the minimal models.

For all undefined terminology, and the detailed description of the bijection maps in (1.C), we refer the reader to §2.1, §4.2 and §6.2. We remark that the graphs in (3) are simply the framework to express the relationship between flops and mutation on a combinatorial level, and the derived groupoids in (4) are the language to express the relationship on the level of functors.

In addition to 1.12, we also establish the following. For unexplained terminology, we again refer the reader to §6.2.

Corollary 1.13 (=4.10, 6.4, 6.9). Let R be a complete local cDV singularity. Then

- (1) R admits only finitely many MM generators, and any two such modules are connected by a finite sequence of mutations.
- (2) The mutation graph of MM generators can be viewed as a subgraph of the skeleton of the GIT chamber decomposition of $\Theta(\Lambda)$.

If further R is isolated, then

(3) The mutation graph of MM generators coincides with the skeleton of the GIT chamber decomposition. In particular, the number of basic MM generators equals the number of chambers.

Although (3) is simply a special case, the setting when R has only isolated singularities is particularly interesting since it relates maximal rigid and cluster tilting objects in certain Krull–Schmidt Hom-finite 2-CY triangulated categories to birational geometry.

We also remark that the above greatly generalises and simplifies [BIKR, DH], which considered isolated cA_n singularities with smooth minimal models and observed the connection to the Weyl group S_n , [NS] which considered specific quotient singularities, again with smooth minimal models, and [IW3] which considered general cA_n singularities. All these previous works relied heavily on direct calculation, manipulating explicit forms.

Based on the above results, we offer the following conjecture.

Conjecture 1.14. Let R be a Gorenstein 3-fold with only rational singularities. Then R admits only a finite number of basic MM generators if and only if the minimal models of Spec R have one-dimensional fibres (equivalently, R is cDV).

The direction (\Leftarrow) is true by 1.13. Although we cannot yet prove (\Rightarrow), by strengthening some results in [B13] to cover non-isolated singularities, we do show the following as a corollary of a more general *d*-dimensional result.

Proposition 1.15 (=6.12). Suppose that R is a complete local 3-dimensional normal Gorenstein ring, and suppose that R admits an NCCR (which by [VdB2] implies that the minimal models of Spec R are smooth). If R admits only finitely many basic MM generators up to isomorphism, then R is a hypersurface singularity.

1.5. Generalities. In this paper we work over an affine base, restrict to complete local rings, work over one-dimensional fibres and sometimes restrict to minimal models. Often these assumptions are not necessary, and are mainly made just for technical simplification of the notation and exposition. In Appendix B we outline questions and conjectures for when R is not Gorenstein, including flips and other aspects of the MMP.

1.6. Notation and Conventions. Everything in this paper takes place over the complex numbers \mathbb{C} , or any algebraically closed field of characteristic zero. All complete local rings appearing are the completions of finitely generated \mathbb{C} -algebras at some maximal ideal. Throughout modules will be left modules, and for a ring A, mod A denotes the category of finitely generated left A-modules, and fdmod A denotes the category of finite length left A-modules. For $M \in \mod A$ we denote by add M the full subcategory consisting of summands of finite direct sums of copies of M. We say that M is a generator if $R \in \operatorname{add} M$, and we denote by proj $A := \operatorname{add} A$ the category of finitely generated projective A-modules. Throughout we use the letters R and S to denote commutative noetherian rings, whereas Greek letters Λ and Γ will denote noncommutative noetherian rings.

We use the convention that when composing maps fg, or $f \cdot g$, will mean f then g, and similarly for quivers ab will mean a then b. Note that with this convention $\operatorname{Hom}_R(M, X)$ is a $\operatorname{End}_R(M)$ -module and $\operatorname{Hom}_R(X, M)$ is a $\operatorname{End}_R(M)^{\operatorname{op}}$ -module. Functors will use the opposite convention, but this will always be notated by the composition symbol \circ , so throughout $F \circ G$ will mean G then F. 1.7. Acknowledgements. It is a pleasure to thank Alastair Craw and Alastair King for many discussions and comments over the eight years since this work began, and to thank Will Donovan and Osamu Iyama for many discussions and ideas, some of which are included here, and for collaborating on the foundational aspects [IW2, IW3, IW4, DW1, DW2, DW3]. It is also a pleasure to thank the referee for many helpful comments and suggestions. Thanks are also due to Gavin Brown, Alvaro Nolla de Celis, Hailong Dao, Eleonore Faber, Martin Kalck, Joe Karmazyn, Miles Reid and Yuhi Sekiya.

2. General Preliminaries

We begin by outlining the necessary preliminaries on aspects of the MMP, MM modules, MMAs, perverse sheaves, and mutation. With the exception of 2.15, 2.21, 2.22, 2.25 and 2.26 nothing in this section is original to this paper, and so the confident reader can skip to §3.

2.1. General Background. If (R, \mathfrak{m}) is a commutative noetherian local ring and $M \in \text{mod } R$, recall that the *depth* of M is defined to be

$$\operatorname{depth}_{R} M := \inf\{i \ge 0 \mid \operatorname{Ext}_{R}^{i}(R/\mathfrak{m}, M) \neq 0\}.$$

We say that $M \in \text{mod } R$ is maximal Cohen-Macaulay (=CM) if depth_R $M = \dim R$. In the non-local setting, if R is an arbitrary commutative noetherian ring we say that $M \in \text{mod } R$ is CM if M_p is CM for all prime ideals \mathfrak{p} in R, and we denote the category of CM R-modules by CM R. We say that R is a CM ring if $R \in \text{CM } R$, and if further inj.dim_R $R < \infty$, we say that R is Gorenstein. Throughout, we denote $(-)^* := \text{Hom}_R(-, R)$ and let ref R denote the category of reflexive R-modules, that is those $M \in \text{mod } R$ for which the natural morphism $M \to M^{**}$ is an isomorphism.

Singular *d*-CY algebras are a convenient language that unify the commutative Gorenstein algebras and the mildly noncommutative algebras under consideration.

Definition 2.1. Let Λ be a module finite *R*-algebra, then for $d \in \mathbb{Z}$ we call Λ *d*-Calabi–Yau (=*d*-CY) if there is a functorial isomorphism

$$\operatorname{Hom}_{\mathcal{D}(\operatorname{Mod}\Lambda)}(x, y[d]) \cong D \operatorname{Hom}_{\mathcal{D}(\operatorname{Mod}\Lambda)}(y, x)$$

for all $x \in D^{b}(\operatorname{fdmod} \Lambda)$, $y \in D^{b}(\operatorname{mod} \Lambda)$, where $D = \operatorname{Hom}_{\mathbb{C}}(-,\mathbb{C})$. Similarly we call Λ singular d-Calabi-Yau (=d-sCY) if the above functorial isomorphism holds for all $x \in D^{b}(\operatorname{fdmod} \Lambda)$ and $y \in K^{b}(\operatorname{proj} \Lambda)$, where $K^{b}(\operatorname{proj} \Lambda)$ denotes the subcategory of $D^{b}(\operatorname{mod} \Lambda)$ consisting of perfect complexes.

When $\Lambda = R$, it is known [IR, 3.10] that R is d-sCY if and only if R is Gorenstein and equi-codimensional with dim R = d. One noncommutative source of d-sCY algebras are maximal modification algebras, introduced in [IW2] as the notion of a noncommutative minimal model.

Definition 2.2. Suppose that R is a normal d-sCY algebra. We call $N \in \operatorname{ref} R$ a modifying module if $\operatorname{End}_R(N) \in \operatorname{CM} R$, and we say that $N \in \operatorname{ref} R$ is a maximal modifying (MM) module if it is modifying and it is maximal with respect to this property. Equivalently, $N \in \operatorname{ref} R$ is an MM module if and only if

add
$$N = \{ X \in \operatorname{ref} R \mid \operatorname{End}_R(N \oplus X) \in \operatorname{CM} R \}.$$

If N is an MM module, we call $\operatorname{End}_{R}(N)$ a maximal modification algebra (=MMA).

The notion of a smooth noncommutative minimal model, called a noncommutative crepant resolution, is due to Van den Bergh [VdB2].

Definition 2.3. Suppose that R is a normal d-sCY algebra. By a noncommutative crepant resolution (NCCR) of R we mean $\Lambda := \operatorname{End}_R(N)$ where $N \in \operatorname{ref} R$ is such that $\Lambda \in \operatorname{CM} R$ and $\operatorname{gl.dim} \Lambda = d$.

In the setting of the definition, provided that N is nonzero, it is equivalent to ask for $\Lambda \in CM R$ and $gl.dim \Lambda < \infty$ [VdB2, 4.2]. Note that any modifying module N gives rise to a d-sCY algebra $End_R(N)$ by [IW2, 2.22(2)], and $End_R(N)$ is d-CY if and only if $End_R(N)$ is an NCCR [IW2, 2.23]. Further, an NCCR is precisely an MMA with finite global dimension, that is, a smooth noncommutative minimal model. On the base R, those NCCRs where $N \in CM R$ can be characterised in terms of CT modules [IW2, 5.9(1)].

Definition 2.4. Suppose that R is a normal d-sCY algebra. We say that $N \in CMR$ is a CT module if

add
$$N = \{X \in CM R \mid Hom_R(N, X) \in CM R\}.$$

Throughout this paper we will freely use the language of terminal, canonical and compound Du Val (=cDV) singularities in the MMP, for which we refer the reader to [CKM, Re, KoM] for a general overview. Recall that a normal scheme X is defined to be \mathbb{Q} -factorial if for every Weil divisor D, there exists $n \in \mathbb{N}$ for which nD is Cartier. Also, if X and X_{con} are normal, then recall that a projective birational morphism $f: X \to X_{\text{con}}$ is called *crepant* if $f^*\omega_{X_{\text{con}}} = \omega_X$. A \mathbb{Q} -factorial terminalisation, or minimal model, of X_{con} is a crepant projective birational morphism $f: X \to X_{\text{con}}$ such that X has only \mathbb{Q} -factorial terminal singularities. When X is furthermore smooth, we call f a crepant resolution.

The following theorem, linking commutative and noncommutative minimal models, will be used implicitly throughout.

Theorem 2.5. [IW3, 4.16, 4.17] Let $f: X \to \text{Spec } R$ be a projective birational morphism, where X and R are both Gorenstein normal varieties of dimension three, and X has at worst terminal singularities. If X is derived equivalent to some ring Λ , then the following are equivalent.

- (1) $X \to \operatorname{Spec} R$ is a minimal model.
- (2) Λ is an MMA of R.

The result is also true when R is complete local, see [IW3, 4.19].

Throughout this paper, we require the ability to contract curves. Suppose that $f: X \to \operatorname{Spec} R$ is a projective birational morphism where R is complete local, such that $\mathbf{R}f_*\mathcal{O}_X = \mathcal{O}_R$, with at most one-dimensional fibres. Choose a subset of curves $\bigcup_{i \in I} C_i$ in X above the unique closed point of $\operatorname{Spec} R$, then since R is complete local we may factorise f into

$$X \xrightarrow{g} X_{\operatorname{con}} \xrightarrow{h} \operatorname{Spec} R$$

where g contracts C_j to a closed point if and only if $j \in I$, and further $g_*\mathcal{O}_X = \mathcal{O}_{X_{\text{con}}}$, see e.g. [Ko1, p25] or [S, §2]. Further, by the vanishing theorem [KMM, 1-2-5] $\mathbf{R}g_*\mathcal{O}_X = \mathcal{O}_{X_{\text{con}}}$, which since $\mathbf{R}f_*\mathcal{O}_X = \mathcal{O}_R$ in turn implies that $\mathbf{R}h_*\mathcal{O}_{X_{\text{con}}} = \mathcal{O}_R$.

Recall that a Q-Cartier divisor D is called g-nef if $D \cdot C \ge 0$ for all curves contracted by g, and D is called g-ample if $D \cdot C > 0$ for all curves contracted by g. There are many (equivalent) definitions of flops in the literature, see e.g. [Ko2]. We will use the following.

Definition 2.6. Suppose that $f: X \to \text{Spec } R$ is a crepant projective birational morphism, where R is complete local, with at most one-dimensional fibres. Choose $\bigcup_{i \in I} C_i$ in X, contract them to give $g: X \to X_{\text{con}}$, and suppose that g is an isomorphism away from $\bigcup_{i \in I} C_i$. Then we say that $g^+: X^+ \to X_{\text{con}}$ is the flop of g if for every line bundle $\mathcal{L} = \mathcal{O}_X(D)$ on X such that -D is g-nef, then the proper transform of D is \mathbb{Q} -Cartier, and g^+ -nef.

The following is obvious, and will be used later.

Lemma 2.7. With the setup in 2.6, suppose that D_i is a Cartier divisor on X such that $D_i \cdot C_j = \delta_{ij}$ for all $i, j \in I$ (such a D_i exists since R is complete local), let D'_i denote the proper transform of $-D_i$ to X^+ . Then if D'_i is Cartier and there is an ordering of the

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exceptional curves C_i^+ of g^+ such that $D'_i \cdot C_j^+ = \delta_{ij}$, then $g^+ \colon X^+ \to X_{\text{con}}$ is the flop of g.

2.2. Perverse Sheaves and Tilting. Some of the arguments in this paper are not specific to dimension three, and are not specific to crepant morphisms. Consequently, at times we will refer to the following setup.

Setup 2.8. (General Setup). Suppose that $f: X \to \operatorname{Spec} R$ is a projective birational morphism, where R is complete local, X and R are noetherian and normal, such that $\mathbf{R}f_*\mathcal{O}_X = \mathcal{O}_R$ and the fibres of f have dimension at most one.

However, some parts will require the following restriction.

Setup 2.9. (Crepant Setup). Suppose that $f: X \to \operatorname{Spec} R$ is a crepant projective birational morphism between d < 3 dimensional schemes, where R is complete local normal Gorenstein, and the fibres of f have dimension at most one. Further

- (1) If d = 2 we allow X to have canonical Gorenstein singularities, so $X \to \operatorname{Spec} R$ is a partial crepant resolution of a Kleinian singularity.
- (2) If d = 3 we further assume that X has only Gorenstein terminal singularities.

By Kawamata vanishing, it is automatic that $\mathbf{R}f_*\mathcal{O}_X = \mathcal{O}_R$. We will not assume that X is Q-factorial unless explicitly stated.

Now if $g: X \to X_{\text{con}}$ is a projective birational morphism satisfying $\mathbf{R}g_*\mathcal{O}_X = \mathcal{O}_{X_{\text{con}}}$, the category of perverse sheaves relative to g, denoted ${}^{0}\mathfrak{Per}(X, X_{con})$, is defined to be

$${}^{0}\mathfrak{Per}(X, X_{\text{con}}) := \left\{ a \in \mathrm{D^{b}}(\mathrm{coh}\, X) \middle| \begin{array}{c} H^{i}(a) = 0 \text{ if } i \neq 0, -1 \\ g_{*}H^{-1}(a) = 0, \ \mathbf{R}g_{*}H^{0}(a) = 0 \\ \mathrm{Hom}(c, H^{-1}(a)) = 0 \text{ for all } c \in \mathcal{C}_{g} \end{array} \right\}$$

where $C_q := \{c \in \operatorname{coh} X \mid \mathbf{R}_{g*}c = 0\}$. In the setup of 2.8, it is well-known [VdB, 3.2.8] that there is a vector bundle \mathcal{V}_X , described below, inducing a derived equivalence

The bundle \mathcal{V}_X is constructed as follows. Consider $C = \pi^{-1}(\mathfrak{m})$ where \mathfrak{m} is the unique closed point of Spec R, then giving C the reduced scheme structure, write $C^{\text{red}} = \bigcup_{i=1}^{n} C_i$ where each $C_i \cong \mathbb{P}^1$. Since R is complete local, we can find Cartier divisors D_i with the property that $D_i \cdot C_j = \delta_{ij}$, and set $\mathcal{L}_i := \mathcal{O}_X(D_i)$. If the multiplicity of C_i is equal to one, set $\mathcal{M}_i := \mathcal{L}_i$, else define \mathcal{M}_i to be given by the maximal extension

$$0 \to \mathcal{O}_X^{\oplus (r-1)} \to \mathcal{M}_i \to \mathcal{L}_i \to 0 \tag{2.B}$$

associated to a minimal set of r-1 generators of $H^1(X, \mathcal{L}_i^*)$ [VdB, 3.5.4].

Notation 2.10. With notation as above, in the general setting of 2.8,

- (1) Set $\mathcal{N}_i := \mathcal{M}_i^*$, and $\mathcal{V}_X := \mathcal{O}_X \oplus \bigoplus_{i=1}^n \mathcal{N}_i$. (2) Set $N_i := H^0(\mathcal{N}_i)$ and $N := H^0(\mathcal{V}_X)$.

By [VdB, 3.5.5], \mathcal{V}_X is a basic progenerator of ${}^{0}\mathfrak{Per}(X, R)$, and furthermore is a tilting bundle on X. Note that $\operatorname{rank}_{R} N_{i}$ is equal to the scheme-theoretic multiplicity of the curve C_i [VdB, 3.5.4].

Remark 2.11. Under the derived equivalence Ψ_X in (2.A), the coherent sheaves $\mathcal{O}_{C_i}(-1)$ belong to ${}^{0}\mathfrak{Per}(X,R)$ and correspond to simple left $\operatorname{End}_{X}(\mathcal{V}_{X})$ -modules S_{i} .

Unfortunately, at this level of generality $\operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$ (see e.g. [DW2, §2]). However, in the crepant setup of 2.9, this does hold, which later will allow us to reduce many problems to the base $\operatorname{Spec} R$.

Lemma 2.12 ([VdB, 3.2.10]). In the setup of 2.9, $\operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$.

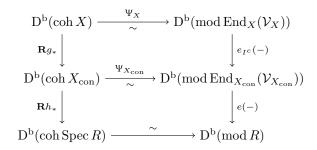
Notation 2.13. In the setup of 2.8, pick a subset $\bigcup_{i \in I} C_i$ of curves above the origin, indexed by a (finite) set *I*. We set

(1) $\mathcal{N}_I := \bigoplus_{i \in I} \mathcal{N}_i$ and $\mathcal{N}_{I^c} := \mathcal{O}_X \oplus \bigoplus_{j \notin I} \mathcal{N}_j$, so that $\mathcal{V}_X = \mathcal{N}_I \oplus \mathcal{N}_{I^c}$. (2) $N_I := \bigoplus_{i \in I} N_i$ and $N_{I^c} := R \oplus \bigoplus_{j \notin I} N_j$, so that $N = N_I \oplus N_{I^c}$.

The following result is implicit in the literature.

Proposition 2.14. Under the general setup of 2.8, choose a subset of curves $\bigcup_{i \in I} C_i$ and contract them to obtain $X \to X_{\text{con}} \to \text{Spec } R$. Let e_{I^c} be the idempotent in $\text{End}_X(\mathcal{V}_X)$ corresponding to the summand \mathcal{N}_{I^c} , and let e be the idempotent in $\text{End}_{X_{\text{con}}}(\mathcal{V}_{X_{\text{con}}})$ corresponding to the summand $\mathcal{O}_{X_{\text{con}}}$. Then

- (1) $\mathcal{V}_{X_{\mathrm{con}}} \cong g_* \mathcal{N}_{I^c} \cong \mathbf{R} g_* \mathcal{N}_{I^c}$, and $\mathrm{End}_X(\mathcal{N}_{I^c}) \cong \mathrm{End}_{X_{\mathrm{con}}}(\mathcal{V}_{X_{\mathrm{con}}})$.
- (2) The following diagram commutes



Further, under the crepant setup of 2.9, $\operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$ and $\operatorname{End}_{X_{\operatorname{con}}}(\mathcal{V}_{X_{\operatorname{con}}}) \cong \operatorname{End}_R(N_{I^c})$, so $\operatorname{End}_R(N_{I^c})$ is derived equivalent to X_{con} via the tilting bundle $\mathcal{V}_{X_{\operatorname{con}}}$.

Proof. (1) As in §2.1, by the vanishing theorem $\mathbf{R}g_*\mathcal{O}_X \cong \mathcal{O}_{X_{\text{con}}}$. Given this, the proof of [KIWY, 4.6] (which considered surfaces and $^{-1}\mathfrak{Per}$ instead) shows that $g^*(\mathcal{V}^*_{X_{\text{con}}}) \cong \mathcal{O}_X \oplus_{j \notin I} \mathcal{M}_j$. Thus

$$\mathcal{H}om_X(g^*\mathcal{V}_{X_{\mathrm{con}}},\mathcal{O}_X) \cong g^*\mathcal{H}om_X(\mathcal{V}_{X_{\mathrm{con}}},\mathcal{O}_{X_{\mathrm{con}}}) \cong \mathcal{O}_X \oplus_{j \notin I} \mathcal{M}_j$$

and so dualizing gives $g^* \mathcal{V}_{X_{\text{con}}} \cong \mathcal{O}_X \oplus_{j \notin I} \mathcal{N}_j := \mathcal{N}_{I^c}$, where the right-hand side is a summand of \mathcal{V}_X . Applying $\mathbf{R}g_*$ and using the projection formula

$$\mathcal{V}_{X_{\rm con}} \cong \mathbf{R}g_*g^*\mathcal{V}_{X_{\rm con}} \cong \mathbf{R}g_*\mathcal{N}_I$$

and so inspecting cohomology shows that $g_* \mathcal{N}_{I^c} \cong \mathbf{R} g_* \mathcal{N}_{I^c} \cong \mathcal{V}_{X_{\text{con}}}$. It follows that

$$\operatorname{End}_{X_{\operatorname{con}}}(\mathcal{V}_{X_{\operatorname{con}}}) = \operatorname{End}_{X_{\operatorname{con}}}(g_*\mathcal{N}_{I^c}) \cong \operatorname{Hom}_X(g^*g_*\mathcal{N}_{I^c}, \mathcal{N}_{I^c}) \cong \operatorname{End}_X(\mathcal{N}_{I^c}),$$

and chasing through shows this isomorphism is a ring isomorphism.

(2) The commutativity of the top diagram follows from the functorial isomorphisms

$$\mathbf{R}\mathrm{Hom}_{X_{\mathrm{con}}}(\mathcal{V}_{X_{\mathrm{con}}}, \mathbf{R}g_{*}(-)) \cong \mathbf{R}\mathrm{Hom}_{X}(g^{*}\mathcal{V}_{X_{\mathrm{con}}}, -)$$
$$\cong \mathbf{R}\mathrm{Hom}_{X}(\mathcal{N}_{I^{c}}, -)$$
$$\cong e_{I^{c}}\mathbf{R}\mathrm{Hom}_{X}(\mathcal{V}_{X}, -).$$

with the bottom diagram being similar. The last statements then follow from 2.12. \Box

The following is an easy extension of [Wem, 3.2], and will be needed later to read off the dual graph after the flop.

Theorem 2.15. In the general setup of 2.8, set $\Lambda := \operatorname{End}_X(\mathcal{V}_X)$. Then $\Lambda^{\operatorname{op}}$ can be written as a quiver with relations, where the quiver is given as follows: for every exceptional curve C_i associate a vertex labelled *i*, and also associate a vertex \star corresponding to \mathcal{O}_X . Then the number of arrows between the vertices is precisely

	Number of arrows	If setup 2.9 , $d = 3$ and X is smooth
$i \to \star$	$\dim_{\mathbb{C}} \operatorname{Ext}_{X}^{1}(\omega_{C}, \omega_{C}).$ $\dim_{\mathbb{C}} \operatorname{Hom}_{X}(\mathcal{O}_{C_{i}}(-1), \omega_{C})$ $\dim_{\mathbb{C}} \operatorname{Ext}_{X}^{2}(\omega_{C}, \mathcal{O}_{C_{i}}(-1))$	
	$\dim_{\mathbb{C}} \operatorname{Ext}^{1}_{X}(\mathcal{O}_{C_{i}}, \mathcal{O}_{C_{i}})$	$= \begin{cases} 0 & if (-1, -1) \text{-} curve \\ 1 & if (-2, 0) \text{-} curve \\ 2 & if (-3, 1) \text{-} curve \end{cases}$
$i \rightarrow j$	$\begin{cases} 1 & if C_i \cap C_j = \{ pt \} \\ 0 & else \end{cases}$	(2 % (8, 2) earle

where in the bottom row $i \neq j$.

2.3. Mutation. Throughout this subsection R denotes a normal d-sCY complete local commutative algebra, with $d \ge 2$, and $M \in \operatorname{ref} R$ denotes a basic modifying module M. We summarise and extend the theory of mutation from [IW2, §6] and [DW1, §5].

Setup 2.16. With assumptions as above, given the basic modifying *R*-module *M*, set $\Lambda := \operatorname{End}_R(M)$ and pick a summand M_I of *M*.

(1) Denote M_{I^c} to be the complement of M_I , so that

 $M = M_I \oplus M_{I^c}.$

(2) We define $[M_{I^c}]$ to be the two-sided ideal of Λ consisting of morphisms $M \to M$ which factor through a member of add M_{I^c} . We define $\Lambda_I := \Lambda/[M_{I^c}]$. Equivalently, if e_I denotes the idempotent of $\Lambda = \operatorname{End}_R(M)$ corresponding to the summand M_I of M, then $\Lambda_I = \Lambda/\Lambda(1 - e_I)\Lambda$.

Given our choice of summand M_I , we then mutate. In the theory of mutation, the complement submodule M_{I^c} is fixed, and the summand M_I changes in a universal way. Recall from §2.1 that $(-)^* := \text{Hom}_R(-, R)$.

Setup 2.17. With the setup as in 2.16, write $M_I = \bigoplus_{i \in I} M_i$ as a direct sum of indecomposables. For each $i \in I$, consider a minimal right (add M_{I^c})-approximation

$$V_i \xrightarrow{a_i} M_i$$

of M_i , which by definition means that

- (1) $V_i \in \text{add } M_{I^c}$ and $(\cdot a_i)$: $\text{Hom}_R(M_{I^c}, V_i) \to \text{Hom}_R(M_{I^c}, M_i)$ is surjective,
- (2) If $g \in \text{End}_R(V_i)$ satisfies $a_i = ga_i$, then g is an automorphism.

Since R is complete, such an a_i exists and is unique up to isomorphism. Denote $K_i := \text{Ker } a_i$, so there is an exact sequence

$$0 \to K_i \xrightarrow{c_i} V_i \xrightarrow{a_i} M_i \tag{2.C}$$

such that

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}, K_{i}) \xrightarrow{\cdot c_{i}} \operatorname{Hom}_{R}(M_{I^{c}}, V_{i}) \xrightarrow{\cdot a_{i}} \operatorname{Hom}_{R}(M_{I^{c}}, M_{i}) \to 0$$
(2.D)

is exact. Summing the sequences (2.C) over all $i \in I$ gives an exact sequence

$$0 \to K_I \xrightarrow{c} V_I \xrightarrow{a} M_I \tag{2.E}$$

such that

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}, K_{I}) \xrightarrow{\cdot c} \operatorname{Hom}_{R}(M_{I^{c}}, V_{I}) \xrightarrow{\cdot a} \operatorname{Hom}_{R}(M_{I^{c}}, M_{I}) \to 0$$
(2.F)

is exact.

Dually, for each $i \in I$, consider a minimal right (add $M_{I^c}^*$)-approximation

$$U_i^* \xrightarrow{b_i} M_i^*$$

of M_i^* , and denote $J_i := \operatorname{Ker} b_i$. Thus

$$0 \to J_i \xrightarrow{d_i} U_i^* \xrightarrow{b_i} M_i^* \tag{2.G}$$

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, J_{i}) \xrightarrow{\cdot d_{i}} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, U_{i}^{*}) \xrightarrow{\cdot b_{i}} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, M_{i}^{*}) \to 0$$
(2.H)

are exact. Summing over all $i \in I$ gives exact sequences

$$0 \to J_I \xrightarrow{a} U_I^* \xrightarrow{b} M_I^* \tag{2.I}$$

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, J_{I}) \xrightarrow{\cdot a} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, U_{I}^{*}) \xrightarrow{\cdot b} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, M_{I}^{*}) \to 0.$$
(2.J)

Definition 2.18. With notation as above,

(1) We define the right mutation of M at M_I as

$$\mu_I M := M_{I^c} \oplus K_I,$$

that is we remove the summand M_I and replace it with K_I .

(2) We define the left mutation of M at M_I as

$$\mathsf{v}_I M := M_{I^c} \oplus (J_I)^*.$$

In this level of generality, $\nu_I M$ is not necessarily isomorphic to $\mu_I M$.

Remark 2.19. Even if $M_I = M_i$ is indecomposable, when we view $\operatorname{End}_R(M)$ as a quiver with relations, with arrows a, and left projective $\operatorname{End}_R(M)$ -modules P_j corresponding to the indecomposable summands M_j , it is a common misconception that mutation can be defined using simply the arrows into (respectively, out of) the vertex i. Indeed, we could consider the combinatorially defined morphisms

$$\bigoplus_{\substack{\text{head}(a)=i\\\text{tail}(a)\neq i}} P_{\text{tail}(a)} \to P_i \quad \text{and} \quad P_i \to \bigoplus_{\substack{\text{tail}(a)=i\\\text{head}(a)\neq i}} P_{\text{head}(a)}$$

which by reflexive equivalence arise from morphisms

$$\bigoplus_{\substack{\text{head}(a)=i\\\text{tail}(a)\neq i}} M_{\text{tail}(a)} \to M_i \text{ and } M_i \to \bigoplus_{\substack{\text{tail}(a)=i\\\text{head}(a)\neq i}} M_{\text{head}(a)}.$$

However these morphisms are not approximations in general. In other words, the mutation defined in 2.18 above is *not* in general a vertex tilt in the sense of Bridgeland–Stern [BS], and in full generality there is no simple combinatorial description of the decomposition of U_I or V_I . In the case of cDV singularities, we do give a combinatorial description later in §5.3 and §5.4 by relating the problem to partial crepant resolutions of ADE singularities.

One of the key properties of mutation is that it always gives rise to a derived equivalence. With the setup as above, for the case of left mutation $\nu_I M$, the derived equivalence between $\operatorname{End}_R(M)$ and $\operatorname{End}_R(\nu_I M)$ is given by a tilting $\operatorname{End}_R(M)$ -module T_I constructed as follows. By (A.A) there is an exact sequence

$$0 \to M_I \xrightarrow{b^*} U_I \to J_I^*$$

obtained by dualizing (2.1). Applying $\operatorname{Hom}_R(M, -)$ induces $(\cdot b^*)$: $\operatorname{Hom}_R(M, M_I) \to \operatorname{Hom}_R(M, U_I)$, so denoting the cokernel by C_I we obtain an exact sequence

$$0 \to \operatorname{Hom}_{R}(M, M_{I}) \xrightarrow{\cdot b^{*}} \operatorname{Hom}_{R}(M, U_{I}) \to C_{I} \to 0.$$

$$(2.K)$$

The tilting $\operatorname{End}_R(M)$ -module T_I is defined to be $T_I := \operatorname{Hom}_R(M, M_{I^c}) \oplus C_I$. It turns out that $\operatorname{End}_{\Lambda}(T_I) \cong \operatorname{End}_R(\mathbf{v}_I M)$ [IW2, 6.7, 6.8], and there is always an equivalence

$$\Phi_I := \mathbf{R} \operatorname{Hom}(T_I, -) \colon \operatorname{D^b}(\operatorname{mod} \operatorname{End}_R(M)) \to \operatorname{D^b}(\operatorname{mod} \operatorname{End}_R(\mathbf{v}_I M)), \qquad (2.L)$$

which is called the *mutation functor* [IW2, 6.8]. It is never the identity functor. On the other hand $v_I M = M$ can happen (see e.g. A.2). Note that, by construction, T_I has the

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structure of a Λ - Γ bimodule, where $\Gamma := \nu_I \Lambda := \operatorname{End}_{\Lambda}(T_I) \cong \operatorname{End}_R(\nu_I M)$. The following is elementary.

Lemma 2.20. With notation as above, the following statements hold.

- (1) T_I is a tilting Λ -module with $pd_{\Lambda}T_I = 1$.
- (2) T_I is a tilting $\Gamma^{\text{op}} \cong \text{End}_R((\mathbf{v}_I M)^*)$ -module, with $T_I \cong \text{Hom}_R((\mathbf{v}_I M)^*, M_{I^c}^*) \oplus D_I$ where D_I arises from the exact sequence

$$0 \to \operatorname{Hom}_R((\mathbf{v}_I M)^*, J_I) \xrightarrow{\cdot d} \operatorname{Hom}_R((\mathbf{v}_I M)^*, U_I^*) \to D_I \to 0$$

of Γ^{op} -modules. Thus $\mathrm{pd}_{\Gamma^{\mathrm{op}}}T_I = 1$ and $\mathrm{End}_{\Gamma^{\mathrm{op}}}(T_I) \cong \Lambda^{\mathrm{op}}$.

Proof. (1) is [IW2, 6.8], and (2) follows from (1), see for example [SY, 2.2] or [Ke, 4.1], [BB, 2.6]. As a sketch proof, by (2.K)

$$0 \to \operatorname{Hom}_R(M, M) \to \operatorname{Hom}_R(M, U_I \oplus M_{I^c}) \to C_I \to 0.$$

is exact, and applying $\operatorname{Hom}_{\Lambda}(-, T_I)$ gives an exact sequence

$$0 \to \operatorname{Hom}_{\Lambda}(C_{I}, T_{I}) \to \operatorname{Hom}_{\Lambda}(\operatorname{Hom}_{R}(M, U_{I} \oplus M_{I^{c}}), T_{I}) \to T_{I} \to 0$$

$$(2.M)$$

of Γ^{op} -modules. Under the isomorphism $\operatorname{End}_{\Lambda}(T_I) \cong \operatorname{End}_R(\mathbf{v}_I M)$,

$$\operatorname{Hom}_{\Lambda}(C_{I}, T_{I}) \cong \operatorname{Hom}_{R}(J_{I}^{*}, \nu_{I}M) \cong \operatorname{Hom}_{R}((\nu_{I}M)^{*}, J_{I}),$$

 $\operatorname{Hom}_{\Lambda}(\operatorname{Hom}_{R}(M, U_{I} \oplus M_{I^{c}}), T_{I}) \cong \operatorname{Hom}_{R}(U_{I} \oplus M_{I^{c}}, \mathbf{v}_{I}M) \cong \operatorname{Hom}_{R}((\mathbf{v}_{I}M)^{*}, U_{I}^{*} \oplus M_{I^{c}}^{*}),$

so (2.M) is isomorphic to

$$0 \to \operatorname{Hom}_{R}((\nu_{I}M)^{*}, J_{I}) \xrightarrow{\binom{\cdot d}{0}} \operatorname{Hom}_{R}((\nu_{I}M)^{*}, U_{I}^{*} \oplus M_{I^{c}}^{*}) \to T_{I} \to 0,$$

proving the statements by applying the analysis in (1) to $\operatorname{End}_R((\nu_I M)^*)$.

For our purposes later we will require the finer information encoded in the following two key technical results. They are both an extension of [IW2, §6] and [DW1, §4], and are proved using similar techniques, so we postpone the proofs until Appendix A.

Theorem 2.21 (=A.5). Suppose that $v_I M \cong M$. Then

- (1) $T_I = \Lambda (1 e_I) \Lambda$ and $\Gamma := \operatorname{End}_{\Lambda}(T_I) \cong \Lambda$.
- (2) $\Omega_{\Lambda}\Lambda_I = T_I$, thus $\mathrm{pd}_{\Lambda}\Lambda_I = 2$ and $\mathrm{Ext}^1_{\Lambda}(T_I, -) \cong \mathrm{Ext}^2_{\Lambda}(\Lambda_I, -)$.

Theorem 2.22 (=A.8). Suppose that d = 3, $\nu_I \nu_I M \cong M$ and $\dim_{\mathbb{C}} \Lambda_I < \infty$. As above, set $\Gamma := \operatorname{End}_{\Lambda}(T_I) \cong \operatorname{End}_R(\nu_I M)$. Then

- (1) $T_I \cong \operatorname{Hom}_R(M, \mathbf{v}_I M).$
- (2) $\Omega_{\Lambda}^2 \Lambda_I = T_I$, thus $\mathrm{pd}_{\Lambda} \Lambda_I = 3$ and $\mathrm{Ext}_{\Lambda}^1(T_I, -) \cong \mathrm{Ext}_{\Lambda}^3(\Lambda_I, -)$.

The following, one of the main results in [IW2], will allow us to establish properties non-explicitly when we restrict to minimal models and mutate at single curves.

Theorem 2.23. Suppose that d = 3, and M is a maximal modifying R-module with indecomposable summand M_j . Set $\Lambda := \operatorname{End}_R(M)$. Then

- (1) We have $\mu_i(M) \cong \mathbf{v}_i(M)$.
- (2) Always $\mathbf{v}_i \mathbf{v}_j (M) \cong M$.
- (3) $\mathbf{v}_j(M) \ncong M$ if and only if $\dim_{\mathbb{C}} \Lambda_j < \infty$.
- (4) $\mathbf{v}_j(M) \cong M$ if and only if $\dim_{\mathbb{C}} \Lambda_j = \infty$.

Proof. (1) and (2) are special cases of [IW2, 6.25]. (3)(\Rightarrow) is [IW2, 6.25(2)], and (4)(\Rightarrow) is [IW2, 6.25(1)]. (3)(\Leftarrow) is the contrapositive of (4)(\Rightarrow), and (4)(\Leftarrow) is the contrapositive of (3)(\Rightarrow).

Remark 2.24. Theorem 2.23(3)(4) shows that there is a dichotomy in the theory of mutation depending on whether the dimension of Λ_j is finite or not. In the flops setting, this dichotomy will correspond to the fact that in a 3-fold, an irreducible curve may or may not be floppable. In either case we will obtain a derived equivalence from mutation, and the results 2.21 and 2.22 will allow us to control it.

The above 2.23 will allow us to easily relate flops and mutations in the case when d = 3 and the singularities of X are Q-factorial. When we want to drop the Q-factorial assumption, or consider d = 2 with canonical singularities, we will need the following.

Proposition 2.25. With the crepant setup of 2.9, and notation from 2.13, choose a subset $\bigcup_{i \in I} C_i$ of curves above the origin and contract them to obtain $X \to X_{con} \to \text{Spec } R$. If X_{con} has only isolated hypersurface singularities, then $v_I v_I N \cong N$ in such a way that N_i mutates to J_i^* mutates to N_i .

Proof. Denote $\mathbb{F} := \operatorname{Hom}_R(N_{I^c}^*, -)$. The choice of curves gives us a summand N_I such that N_{I^c} is a generator. This being the case, the right-hand morphisms in all the exchange sequences are all surjective. By (2.H)

$$0 \to \mathbb{F}J_i \to \mathbb{F}U_i^* \to \mathbb{F}N_i^* \to 0$$

is exact. Denoting $\Delta := \operatorname{End}_R(N_{I^c}^*)$, since $\mathbb{F}U_i^*$ is a projective Δ -module, this shows that $\Omega_{\Delta}(\mathbb{F}N_i^*) \cong \mathbb{F}J_i$. If we denote the minimal add $N_{I^c}^*$ -approximation of J_i by

$$0 \to L_i \to W_i \to J_i \to 0,$$

then $\nu_I \nu_I$ takes N_i to J_i^* to L_i^* . We claim that $L_i^* \cong N_i$, so by reflexive equivalence it suffices to prove that $\mathbb{F}L_i \cong \mathbb{F}N_i^*$. Since

$$0 \to \mathbb{F}L_i \to \mathbb{F}W_i \to \mathbb{F}J_i \to 0$$

is exact and $\mathbb{F}W_i$ is a projective Δ -module, $\Omega_{\Delta}(\mathbb{F}J_i) \cong \mathbb{F}L_i$, so the result follows if we can establish that $\Omega_{\Delta}^2(\mathbb{F}N_i^*) \cong \mathbb{F}N_i^*$. Since $\mathbb{F}N_i^* \in CM \Delta$ has no Δ -projective summands, and $\Omega_{\Delta} = [-1]$ on the category $\underline{CM} \Delta$, it suffices to show that $[2] = \mathrm{Id}$ on $\underline{CM} \Delta$.

But by 2.14 Δ is derived equivalent to $X_{\rm con}$ and so

$$\underline{\mathrm{CM}}\,\Delta\simeq\mathrm{D}_{\mathsf{sg}}(\Delta)\simeq\mathrm{D}_{\mathsf{sg}}(X_{\mathrm{con}})\simeq\bigoplus_{x\in\mathrm{Sing}\,X_{\mathrm{con}}}\underline{\mathrm{CM}}\,\widehat{\mathcal{O}}_{X_{\mathrm{con}},x}$$

by Orlov [O09], since all categories under consideration are idempotent complete. Since each of $\widehat{\mathcal{O}}_{X_{\text{con},x}}$ are hypersurfaces, [2] = Id for each of the categories on the right-hand side, so since the above are triangle equivalences, [2] = Id for the left-hand category. \Box

In the study of terminal (and even smooth) 3-folds, canonical surfaces appear naturally via hyperplane sections, and in this setting $pd_{\Lambda}\Lambda_i$ can be infinite, which is very different to 2.21 and 2.22. The next result will allow us to bypass this problem.

Proposition 2.26. Suppose that R is a normal complete local 2-sCY commutative algebra, and $M \in CM R$ is basic. Choose a summand M_I , set $\Lambda := End_R(M)$ and denote the simple Λ -modules by S_j . Assume that $\nu_I \nu_I M \cong M$. If $x \in fdmod \Lambda$ with $Hom_{\Lambda}(x, S_i) = 0$ for all $i \in I$, then $Ext^{\Lambda}_{\Lambda}(T_I, x) = 0$.

Proof. Since Λ is 2-sCY, x has finite length and C_I has finite projective dimension,

$$\operatorname{Ext}^{1}_{\Lambda}(T_{I}, x) \cong \operatorname{Ext}^{1}_{\Lambda}(C_{I}, x) \cong D \operatorname{Ext}^{1}_{\Lambda}(x, C_{I}),$$

so it suffices to show that $\operatorname{Ext}^{1}_{\Lambda}(x, C_{I}) = 0$. By the assumption $\nu_{I}\nu_{I}M \cong M$, it follows that $J_{I}^{*} \cong K_{I}$. Since $0 \to \operatorname{Hom}_{R}(M, M_{I}) \to \operatorname{Hom}_{R}(M, U_{I}) \to \operatorname{Hom}_{R}(M, K_{I})$ is exact, splicing we obtain exact sequences

$$0 \to \operatorname{Hom}_{R}(M, M_{I}) \to \operatorname{Hom}_{R}(M, U_{I}) \to C_{I} \to 0$$
(2.N)

$$0 \to C_I \to \operatorname{Hom}_R(M, K_I) \to F_I \to 0 \tag{2.0}$$

But by (A.C)

$$0 \to \operatorname{Hom}_R(M_{I^c}, M_I) \to \operatorname{Hom}_R(M_{I^c}, U_I) \to \operatorname{Hom}_R(M_{I^c}, K_I) \to 0$$

is exact, so F_I is a finitely generated Λ_I -module. But since d = 2 and R is normal, necessarily Λ_I has finite length, hence so too has F_I . Thus the assumptions then imply that $\operatorname{Hom}_{\Lambda}(x, F_I) = 0$, so $\operatorname{Ext}^1_{\Lambda}(x, C_I) \hookrightarrow \operatorname{Ext}^1_{\Lambda}(x, \operatorname{Hom}_R(M, K_I))$.

Hence it suffices to show that $\operatorname{Ext}^{1}_{\Lambda}(x, \operatorname{Hom}_{R}(M, K_{I})) = 0$. But

$$0 \to \operatorname{Hom}_R(M, K_I) \xrightarrow{\cdot c} \operatorname{Hom}_R(M, V_I) \to \operatorname{Hom}_R(M, M_I) \to \Lambda_I \to 0$$

is exact, so denoting $E_I := \operatorname{Cok}(\cdot c)$, then $\operatorname{Hom}_{\Lambda}(x, E_I)$ embeds inside

$$\operatorname{Hom}_{\Lambda}(x, \operatorname{Hom}_{R}(M, M_{I})) \cong D\operatorname{Ext}^{2}_{\Lambda}(\operatorname{Hom}_{R}(M, M_{I}), x) = 0,$$

so $\operatorname{Hom}_{\Lambda}(x, E_I) = 0$. This in turns implies that $\operatorname{Ext}^{1}_{\Lambda}(x, \operatorname{Hom}_{R}(M, K_I))$ embeds inside $\operatorname{Ext}^{1}_{\Lambda}(x, \operatorname{Hom}_{R}(M, V_I))$, which is zero. Thus $\operatorname{Ext}^{1}_{\Lambda}(x, \operatorname{Hom}_{R}(M, K_I)) = 0$, as required. \Box

3. Contractions and Deformation Theory

The purpose of this section is use noncommutative deformations to detect whether a divisor has been contracted to a curve, in such a manner that is useful for iterations, improving [DW2]. This part of the Homological MMP does not need any restriction on singularities, so throughout this section we adopt the general setup of 2.8.

3.1. Background on Noncommutative Deformations. With the setup $f: X \to$ Spec R of 2.8, set $\Lambda := \text{End}_X(\mathcal{V}_X)$. Given any $E \in \text{coh } X$, there is an associated classical commutative deformation functor

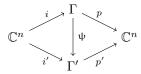
$$c\mathcal{D}ef_E$$
: cart₁ \rightarrow Sets

where cart_1 denotes the category of local commutative artinian \mathbb{C} -algebras. The definition of this functor, which we do not state here, involves a flatness condition over the test object $R \in \operatorname{cart}_1$.

Noncommutative deformations add two new features to this classical picture. First, the test objects are enlarged from commutative artinian rings to allow certain (basic) noncommutative artinian \mathbb{C} -algebras. This thickens the universal sheaf. Second, they allow us to deform a finite collection $\{E_i \mid i \in I\}$ of objects whilst remembering Ext information between them.

For the purposes of this paper, we will not deform coherent sheaves, but rather their images under the derived equivalence in §2.2. Deforming on either side of the derived equivalence turns out to give the same answer [DW2], but the noncommutative side is slightly easier to formulate. Thus we input a finite collection $\{S_i \mid i \in I\}$ of simple Λ -modules, and define the associated noncommutative deformation functor as follows.

As preparation, recall that an *n*-pointed \mathbb{C} -algebra Γ is an associative \mathbb{C} -algebra, together with \mathbb{C} -algebra morphisms $p: \Gamma \to \mathbb{C}^n$ and $i: \mathbb{C}^n \to \Gamma$ such that ip = Id. A morphism of *n*-pointed \mathbb{C} -algebras $\psi: (\Gamma, p, i) \to (\Gamma', p', i')$ is a ring homomorphism $\psi: \Gamma \to \Gamma'$ such that



commutes. We denote the category of *n*-pointed \mathbb{C} -algebras by Alg_n , and denote the full subcategory consisting of those objects that are commutative rings by CAlg_n . Furthermore, denote by art_n the full subcategory of Alg_n consisting of objects (Γ, p, i) for which $\dim_{\mathbb{C}} \Gamma < \infty$ and the augmentation ideal $\mathfrak{n} := \operatorname{Ker}(p)$ is nilpotent. The full subcategory of art_n consisting of those objects that are commutative rings is denoted cart_n .

Given $\Gamma \in \operatorname{art}_n$, the morphism *i* produces *n* idempotents $e_1, \ldots, e_n \in \Gamma$, and we denote $\Gamma_{ij} := e_i \Gamma e_j$.

Definition 3.1. [L02] Fix a finite collection $S := \{S_i \mid i \in I\}$ of left Λ -modules. Then

(1) For $\Gamma \in \operatorname{art}_{|I|}$, we say that $M \in \operatorname{Mod} \Lambda \otimes_{\mathbb{C}} \Gamma^{\operatorname{op}}$ (i.e. a Λ - Γ bimodule) is Γ -matric-free if

$$M \cong (S_i \otimes_{\mathbb{C}} \Gamma_{ij})$$

as Γ^{op} -modules, where the right-hand side is the matrix built by varying $i, j \in \{1, \ldots, n\}$, which has an obvious Γ^{op} -module structure.

(2) The noncommutative deformation functor

$$Def_{\mathcal{S}}$$
: art_n \rightarrow Sets

is defined by sending

$$(\Gamma, \mathfrak{n}) \mapsto \left\{ (M, \delta) \middle| \begin{array}{l} M \in \operatorname{Mod} \Lambda \otimes_{\mathbb{C}} \Gamma^{\operatorname{op}} \\ M \text{ is } \Gamma \text{-matric-free} \\ \delta = (\delta_i) \text{ with } \delta_i \colon M \otimes_{\Gamma} (\Gamma/\mathfrak{n}) e_i \xrightarrow{\sim} S_i \end{array} \right\} \middle/ \sim$$

where $(M, \delta) \sim (M', \delta')$ if there exists an isomorphism $\tau \colon M \to M'$ of bimodules such that

$$\begin{array}{c} M \otimes_{\Gamma} (\Gamma/\mathfrak{n}) e_i \xrightarrow{\tau \otimes 1} M' \otimes_{\Gamma} (\Gamma/\mathfrak{n}) e_i \\ \swarrow \\ S_i \swarrow \\ S_i \swarrow \\ \end{array}$$

commutes, for all i.

(3) The commutative deformation functor is defined to be the restriction of $\mathcal{D}ef_{\mathcal{S}}$ to $\operatorname{cart}_{|I|}$, and is denoted $c\mathcal{D}ef_{\mathcal{S}}$.

Given the general setup $f: X \to \operatorname{Spec} R$ of 2.8, choose a subset of curves $\bigcup_{i \in I} C_i$ above the unique closed point and contract them as in §2.1 to factorise f as

$$X \xrightarrow{g} X_{\operatorname{con}} \xrightarrow{h} \operatorname{Spec} R$$

with $\mathbf{R}g_*\mathcal{O}_X = \mathcal{O}_{X_{\text{con}}}$ and $\mathbf{R}h_*\mathcal{O}_{X_{\text{con}}} = \mathcal{O}_R$. By 2.11, across the derived equivalence the coherent sheaves $\mathcal{O}_{C_i}(-1) \in \operatorname{coh} X$ $(i \in I)$ correspond to simple left Λ -modules S_i . The following is the d = 3 special case of the main result of [DW2].

Theorem 3.2 (Contraction Theorem). With the general setup in 2.8, if d = 3 then f contracts $\bigcup_{i \in I} C_i$ to a point without contracting a divisor if and only if $\mathcal{D}ef_{\mathcal{S}}$ is representable.

3.2. Global and Local Contraction Algebras. We maintain the notation from the general setup of the previous subsection. In this subsection we detect whether g contracts a curve without contracting a divisor by using the algebra $\Lambda = \text{End}_X(\mathcal{V}_X)$, constructed in §2.2 using the morphism f. This will allow us to iterate.

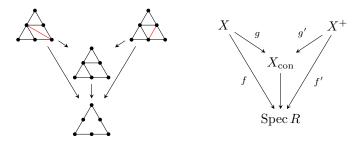
Definition 3.3. For $\Lambda = \operatorname{End}_X(\mathcal{V}_X)$, with notation from 2.13 define $[\mathcal{N}_{I^c}]$ to be the 2-sided ideal of Λ consisting of morphisms that factor through add \mathcal{N}_{I^c} , and set $\Lambda_I := \Lambda/[\mathcal{N}_{I^c}]$.

In [DW2] the prorepresenting object of $\mathcal{D}ef_{\mathcal{S}}$ was constructed locally with respect to the morphism g, using the following method. Let $x \in X_{\text{con}}$ be the closed point above which sits $\bigcup_{i \in I} C_i$. Choose an affine neighbourhood $U_{\text{con}} := \operatorname{Spec} R'$ containing x, set $U := g^{-1}(U_{\text{con}})$, let \mathfrak{R}' be the completion of R' at x, and consider the formal fibre $\mathfrak{U} \to \operatorname{Spec} \mathfrak{R}'$. This morphism satisfies all the assumptions of the general setup of 2.8, and we define the *contraction algebra* to be $A^I_{\text{con}} := \operatorname{End}_{\mathfrak{U}}(\mathcal{V}_{\mathfrak{U}})/[\mathcal{O}_{\mathfrak{U}}]$. By [DW1, DW2] the contraction algebra is independent of choice of U, and

$$\mathcal{D}ef_{\mathcal{S}}(-) \cong \operatorname{Hom}_{\operatorname{Alg}_{|I|}}(\mathcal{A}^{I}_{\operatorname{con}}, -).$$
 (3.A)

Even in the case |I| = 1, comparing Λ_I and A_{con}^I directly is a subtle problem. If |I| = 1 and the scheme-theoretic multiplicity of C_i with respect to g is n, then we can view $\mathcal{A}_{\text{con}}^{\{i\}}$ as factor of an endomorphism ring of an indecomposable rank n bundle on \mathfrak{U} . On the other hand, Λ_i can be viewed as a factor of an endomorphism ring of an indecomposable rank m bundle on X, where m is the scheme theoretic multiplicity of C_i with respect to the morphism f. The next example demonstrates that $m \neq n$ in general.

Example 3.4. Consider the cD_4 singularity $R := \mathbb{C}[[u, x, y, z]]/(u^2 - xyz)$, which is isomorphic to the toric quotient singularity \mathbb{C}^3/G where $G = \mathbb{Z}_2 \times \mathbb{Z}_2 \leq \mathrm{SL}(3,\mathbb{C})$. We consider $X^+ = G - \text{Hilb}(\mathbb{C}^3)$, and one of its flops



Locally, being the Atiyah flop, the scheme theoretic multiplicity of the flopping curve with respect to g is one, but with respect to f the scheme theoretic multiplicity is two. This can be calculated directly, but it also follows from the example 7.6 later, once we have proved 4.6.

The following is the main result of this section.

Theorem 3.5. With the general setup in 2.8, suppose that d = 3 and pick a subset $\bigcup_{i \in I} C_i$ of curves above the origin. Then

- (1) $\mathcal{D}ef_{\mathcal{S}} \cong \operatorname{Hom}_{\operatorname{Alg}_{|I|}}(\Lambda_{I}, -).$
- (2) $\Lambda_I \cong \mathcal{A}_{\operatorname{con}}^I$. (3) $\bigcup_{i \in I} C_i$ contracts to point without contracting a divisor $\Leftrightarrow \dim_{\mathbb{C}} \Lambda_I < \infty$.

Proof. (1) Arguing exactly as in [DW1, 3.1], since $S_i = \mathbb{C}$ as Λ -modules, if we denote the natural homomorphisms $\Lambda \to S_i$ by q_i , then for $(\Gamma, \mathfrak{n}) \in \operatorname{art}_{|I|}$,

$$\mathcal{D}ef_{\mathcal{S}}(\Gamma) \cong \left\{ \begin{array}{l} \bullet \quad \text{A left } \Lambda \text{-module structure on } (S_i \otimes_{\mathbb{C}} \Gamma_{ij}) \text{ such that} \\ (S_i \otimes_{\mathbb{C}} \Gamma_{ij}) \text{ becomes a } \Lambda \text{-} \Gamma \text{ bimodule.} \\ \bullet \quad \delta = (\delta_i) \text{ such that } \delta_i \colon (S_i \otimes_{\mathbb{C}} \Gamma_{ij}) \otimes_{\Gamma} (\Gamma/\mathfrak{n}) e_i \xrightarrow{\sim} S_i \\ \text{ as } \Lambda \text{-modules} \end{array} \right\} \middle/ \sim \\ \cong \left\{ \begin{array}{l} \Lambda \ \mathbb{C}\text{-algebra homomorphism } \Lambda \to \Gamma \text{ such that the} \\ \text{ composition } \Lambda \to \Gamma \to (\Gamma/\mathfrak{n}) e_i = S_i \text{ is } q_i \text{ for all } i \in I \end{array} \right\} \middle/ \sim \\ \cong \operatorname{Hom}_{\mathsf{Alg}_{I/I}}(\Lambda_I, \Gamma). \end{array} \right.$$

(2) Since R is complete, both A_{con}^I and Λ_I belong to the pro-category of $\operatorname{art}_{|I|}$, so $\mathcal{D}ef_{\mathcal{S}}$ is prorepresented by both Λ_I and A_{con}^I . Hence by uniqueness of prorepresenting object, $A_{con}^I \cong \Lambda_I.$

(3) This follows by combining (1) and 3.2.

4. MUTATION, FLOPS AND TWISTS

4.1. Flops and Mutation. We now consider the crepant setup of 2.9 with d = 3, namely $f: X \to \operatorname{Spec} R$ is a crepant projective birational morphism, with one dimensional fibres, where R is a complete local Gorenstein algebra, and X has at worst Gorenstein terminal singularities. As in §2.2, we consider \mathcal{V}_X , the basic progenerator of ${}^0\mathfrak{Per}(X, R)$, set N := $H^0(\mathcal{V}_X)$ and by 2.12 denote $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$.

Remark 4.1. It also follows from 2.12 that $\operatorname{End}_X(\mathcal{V}_X)/[\mathcal{N}_{I^c}] \cong \operatorname{End}_R(N)/[N_{I^c}]$ and so the Λ_I defined in 3.3 and 2.16 coincide. This allows us to link the previous contraction section to mutation.

We aim to prove the following theorem.

Theorem 4.2. With the crepant setup as above, with d = 3, pick a subset of curves $\bigcup_{i \in I} C_i$ above the origin, and suppose that $\dim_{\mathbb{C}} \Lambda_I < \infty$ (equivalently, by 3.5, the curves flop). Denote the flop by X^+ , then

- (1) $\nu_I N \cong H^0(\mathcal{V}_{X^+})$, where \mathcal{V}_{X^+} is the basic progenerator of ${}^0\mathfrak{Per}(X^+, R)$.
- (2) The following diagram of equivalences is naturally commutative

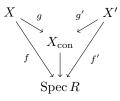
$$\begin{array}{ccc} \mathrm{D}(\operatorname{coh} X) & \xrightarrow{\mathsf{Flop}} & \mathrm{D}(\operatorname{coh} X^+) \\ \Psi_X & & & \downarrow \Psi_{X^+} \\ \mathrm{D}(\operatorname{mod} \Lambda) & \xrightarrow{\Phi_I} & \mathrm{D}(\operatorname{mod} \nu_I \Lambda) \end{array}$$

where Flop is the inverse of the Bridgeland–Chen flop functor, Ψ_X and Ψ_{X^+} are the tilting equivalences in (1.A), and Φ_I is the mutation functor in (2.L).

The proof of 4.2 will be split into two stages. Stage one, proved in this subsection, is to establish 4.2(1) in the case where X is a minimal model and $I = \{i\}$. Stage two is then to prove 4.2 in full generality, lifting the Q-factorial and |I| = 1 assumption. The second stage uses the Auslander–McKay correspondence in §4.2, together with the Bongartz completion to pass to the minimal model, before we then contract back down. Thus, the full proof of 4.2 will not finally appear until §4.3.

To establish functoriality, the following results will be useful later.

Proposition 4.3. Suppose that $f: X \to \operatorname{Spec} R$ and $f': X' \to \operatorname{Spec} R$ both satisfy the crepant setup 2.9, and admit a common contraction



Suppose that g and g' contract the same number of curves, and denote the contracted curves by $\{C_i \mid i \in I\}$ and $\{C'_i \mid i \in I\}$ respectively. If Θ : $D^{\mathrm{b}}(\operatorname{coh} X) \to D^{\mathrm{b}}(\operatorname{coh} X')$ is a Fourier–Mukai equivalence that satisfies

- (1) $\mathbf{R}g'_* \circ \Theta \cong \mathbf{R}g_*$
- (2) $\Theta(\mathcal{O}_X) \cong \mathcal{O}_{X'}$
- (3) $\Theta(\mathcal{O}_{C_i}(-1)) \cong \mathcal{O}_{C'_i}(-1)$ for all $i \in I$,

then $\Theta \cong \phi_*$ where $\phi \colon X \to X'$ is an isomorphism such that $g' \circ \phi = g$,

Proof. This is identical to [DW1, §7.6], which itself is based on [T1]. As in [DW1, 7.17], from properties (1) and (3) it follows that Θ takes ${}^{0}\mathfrak{Per}(X, X_{con})$ to ${}^{0}\mathfrak{Per}(X', X_{con})$. The argument is then word-for-word identical to the proof of [DW1, 7.17, 7.18], since although there it was assumed that X was projective, this is not needed in the proof.

Corollary 4.4. Suppose that $f: X \to \operatorname{Spec} R$ and $f': X' \to \operatorname{Spec} R$ both satisfy the crepant setup 2.9. If $H^0(\mathcal{V}_X) \cong H^0(\mathcal{V}_{X'})$, then there is an isomorphism $X \cong X'$ compatible with f and f'.

Proof. Temporarily denote $N := H^0(\mathcal{V}_X)$ and $M := H^0(\mathcal{V}_{X'})$. Since $N \cong M$ by assumption, certainly they have the same number of indecomposable summands, so since \mathcal{V}_X and

 $\mathcal{V}_{X'}$ are basic, it follows that the numbers of curves contracted by f and f' are the same. Further, we have a diagram of equivalences

$$\begin{array}{ccc} \mathrm{D}(\operatorname{coh} X) & \mathrm{D}(\operatorname{coh} X') \\ & & & & \uparrow \Psi_{X} \\ & & & \downarrow & & \uparrow \Psi_{X'}^{-1} \\ \mathrm{D}(\operatorname{mod} \operatorname{End}_{X}(\mathcal{V}_{X})) \xrightarrow{\cong} & \mathrm{D}(\operatorname{mod} \operatorname{End}_{X'}(\mathcal{V}_{X'})) \end{array}$$

since $\operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N) \cong \operatorname{End}_R(M) \cong \operatorname{End}_{X'}(\mathcal{V}_{X'})$ by 2.12. Denote the composition of equivalences by Θ , then the composition is a Fourier–Mukai functor [DW1, 6.16], which is thus also an equivalence. Now

$$\mathbf{R}f'_* \circ \Theta \cong \mathbf{R}f'_* \circ \Psi_{X'}^{-1} \circ F \circ \Psi_X \cong e(-) \circ \Psi_X \cong \mathbf{R}f_*$$

where the second and third isomorphisms are 2.14. Further by 2.11 Θ takes

 $\mathcal{O}_{C_i}(-1) \mapsto S_i \mapsto S'_i \mapsto \mathcal{O}_{C'_i}(-1)$

for all exceptional curves C_i , where S_i are simple $\operatorname{End}_R(N)$ -modules and S'_i are simple $\operatorname{End}_R(M)$ -modules. Lastly, Θ sends

$$\mathcal{O}_X \mapsto P_0 \mapsto P'_0 \mapsto \mathcal{O}_{X'}$$

where $P_0 \cong \operatorname{Hom}_R(N, R)$ and $P'_0 = \operatorname{Hom}_R(M, R)$. Hence applying 4.3 with $X_{\operatorname{con}} = \operatorname{Spec} R$ gives the result.

The following lemma, an easy consequence of Riedtmann–Schofield, proves 4.2(1) with restricted hypotheses.

Lemma 4.5. With the crepant setup of 2.9, suppose further that d = 3 and X is Q-factorial, that is $f: X \to \operatorname{Spec} R$ is a minimal model. Choose a single curve C_i above the origin, suppose that $\dim_{\mathbb{C}} \Lambda_i < \infty$ (equivalently, by 3.5, C_i flops), and let X^+ denote the flop of C_i . Then $\nu_i N \cong H^0(\mathcal{V}_{X^+})$.

Proof. Denote the base of the contraction of C_i by X_{con} , set $M := H^0(\mathcal{V}_{X^+})$ and let M_i denote the indecomposable summand of M corresponding to C_i^+ . It is clear that $M \ncong N$. Applying 2.14 to both sides of the contraction, $\frac{M}{M_i} \cong H^0(\mathcal{V}_{X_{\text{con}}}) \cong \frac{N}{N_i}$, so the module M differs from N only at the summand N_i . Similarly, by 2.23(3) $\nu_i N \ncong N$, and by definition of mutation, $\nu_i N$ differs from N only at the summand N_i . Consequently, as R-modules, $\nu_i N$ and M share all summands except one, and neither is isomorphic to N.

But by 2.5 both $\operatorname{End}_R(M)$ and $\operatorname{End}_R(N)$ are MMAs, and since $\operatorname{End}_R(\mathbf{v}_i N)$ is also derived equivalent to these, it too is an MMA [IW2, 4.16]. Further, $\operatorname{Hom}_R(N, \mathbf{v}_i N)$ and $\operatorname{Hom}_R(N, M)$ are tilting $\operatorname{End}_R(N)$ -modules by [IW2, 4.17(1)], and by above as $\operatorname{End}_R(N)$ modules they share all summands except one. Hence as in [IW2, 6.22], a Riedtmann– Schofield type theorem implies that $\mathbf{v}_i N \cong M$.

Corollary 4.6. With the crepant setup of 2.9, suppose further that d = 3 and X is Q-factorial. Then

$$\mathbf{v}_i N \cong \left\{ \begin{array}{ll} H^0(\mathcal{V}_{X^+}) & if \ C_i \ flops \\ H^0(\mathcal{V}_X) & else. \end{array} \right.$$

Proof. This now follows by combining 2.23 and 4.5.

The above allows us to verify Figure 2 under restricted hypotheses.

Corollary 4.7. We can run the Homological MMP in Figure 2 when d = 3 and X has only Q-factorial Gorenstein terminal singularities, and we choose only irreducible curves.

Proof. This now follows from 3.5, 4.5 and 2.15.

Later in ^{4.3} we will drop the Q-factorial assumption, and also drop the restriction to single curves.

4.2. Auslander–McKay Correspondence. Throughout this subsection we keep the crepant setup of 2.9, and as in the previous subsection assume further that d = 3 and X is Q-factorial. The R admitting such a setup are of course well-known to be precisely the cDV singularities [Re].

Definition 4.8. With R as above,

- (1) We define the full mutation graph of the MM generators to have as vertices the basic MM generators (up to isomorphism of R-modules), where each vertex N has an edge to $v_I N$ provided that $\dim_{\mathbb{C}} \Lambda_I < \infty$, for I running through all possible summands N_I of N that are not generators. The simple mutation graph is defined in a similar way, but we only allow mutation at indecomposable summands.
- (2) We define the full flops graph of the minimal models of Spec R to have as vertices the minimal models of Spec R (up to isomorphism of R-schemes), and we connect two vertices if the corresponding minimal models are connected by a flop at some curve. The simple flops graph is defined in a similar way, but we only connect two vertices if the corresponding minimal models differ by a flop at an irreducible curve.

The following is standard.

Definition 4.9. For $N \in \text{mod } R$, the stable endomorphism ring $\underline{\text{End}}_R(N)$ is defined to be the quotient of $\text{End}_R(N)$ by the two sided ideal consisting of those morphisms $N \to N$ which factor through add R.

Recall from the introduction §1.3 that there is a specified region C_+ of the GIT chamber decomposition of $\Theta(\operatorname{End}_R(N))$, and $\mathcal{M}_{\mathsf{rk},\phi}(\Lambda)$ denotes the moduli space of ϕ -semistable Λ -modules of dimension vector rk (see §5.1 for more details).

Theorem 4.10. With the d = 3 crepant setup of 2.9, assume further that X is Q-factorial. Then there exists a one-to-one correspondence

 $\{ basic \ MM \ R\text{-module generators} \} \longleftrightarrow \{ \{ minimal \ models \ f_i \colon X_i \to \operatorname{Spec} R \}$ $N \longmapsto^F \longrightarrow \mathcal{M}_{\mathsf{rk},\vartheta}(\operatorname{End}_R(N))$ $H^0(\mathcal{V}_{X_i}) \xleftarrow{}_G \dashv X_i$

where \mathcal{V}_{X_i} is the basic progenerator of ${}^{0}\mathfrak{Per}(X_i, R)$, and ϑ is any element of C_+ . Elements in the set on the left-hand side are taken up to isomorphism of R-modules, and elements of the set on the right-hand side are taken up to isomorphism of R-schemes.

Under this correspondence

- (1) For any fixed MM generator, its non-free indecomposable summands are in oneto-one correspondence with the exceptional curves in the corresponding minimal model.
- (2) For any fixed MM generator N, the quiver of $\underline{\operatorname{End}}_R(N)$ encodes the dual graph of the corresponding minimal model.
- (3) The simple mutation graph of the MM generators coincides with the simple flops graph of the minimal models.

In particular the number of basic MM generators is finite.

Proof. Pick a minimal model $X \to \operatorname{Spec} R$ and denote $N := H^0(\mathcal{V}_X)$, which we know to be an MM generator by 2.5. We now mutate N at all possible non-free indecomposable summands. By 4.6, the only new MM generators that this produces are the global sections from the progenerators of perverse sheaves of the possible flops. We continue mutating these at the non-free indecomposable summands, then either we go back to the original N, or the only new MM generators are those arising from flops of flops. Continuing in this way, since there are only a finite number of minimal models [KMa, Main Theorem], which are connected by a finite sequence of simple flops (see e.g. [Ko1]), by repeatedly mutating at non-free summands we recover only a finite number of MM generators. By [IW4, 4.3] this implies that they are all the MM generators, in particular there is only a finite number and each is isomorphic to $H^0(\mathcal{V}_Y)$ for some minimal model Y. This shows that the function G is surjective. The fact that G is injective is just 4.4, and so G is bijective. The fact that its inverse is given by F is precisely [Kar, 5.2.5], with the small caveat that [Kar, 5.2.5] works with the opposite algebra, but only since his conventions for composing morphisms are opposite to ours.

(1) Let N be an MM generator, then since by the above $N \cong H^0(\mathcal{V}_Y)$ for some minimal model $Y \to \operatorname{Spec} R$, the statement follows from the construction of the bundle \mathcal{V}_Y in §2.2. (2) Since the quiver of $\operatorname{End}_R(N)$ is the quiver of $\operatorname{End}_R(N) \cong \operatorname{End}_Y(\mathcal{V}_Y)$ with the vertex \star (corresponding to the summand R of N) removed, it follows from 2.15 that the quiver of $\operatorname{End}_R(N)$ is the double of the dual graph, together with some loops. (3) This follows from 4.6 and the above argument.

We extend the correspondence later in $\S6.2-\S6.4$.

Remark 4.11. Spec R may be its own minimal model, in which case the correspondence in 4.10 reduces to the statement that R is the only basic modifying generator.

Remark 4.12. The proof of 4.10 uses the fact that there are only a finite number of minimal models, and that they are connected by a finite sequence of simple flops. We use these results only to simplify the exposition; it is possible to instead use the moduli tracking results of $\S5$, specifically 5.25, to give a purely homological proof of 4.10.

Remark 4.13. The bijection in 4.10 extends to a bijection

{basic modifying objects in
$$\underline{CM} R$$
} \xrightarrow{F}_{G} {crepant modifications $f_i \colon X_i \to \operatorname{Spec} R$ },

satisfying the obvious extensions of (1) and (2), where by crepant modification we mean that X_i is obtained from a minimal model by contracting curves to points, and divisors to curves. However, because of 4.21, comparing mutation and flop at arbitrary summands is not so well behaved when the X_i are not minimal models.

Sometimes the minimal models of Spec R can be smooth. Recall from 2.4 the definition of a CT module.

Corollary 4.14. With the setup as in 4.10, assume further that the minimal models of Spec R are smooth (equivalently, R admits a CT module). Then 4.10 reduces to a one-to-one correspondence

 $\{basic \ CT \ R\text{-modules}\} \iff \{crepant \ resolutions \ f_i \colon X_i \to \operatorname{Spec} R\}$

satisfying the same conditions (1)-(3).

Proof. If one of (equivalently, all of) the minimal models is smooth, then $\operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$ has finite global dimension and hence is an NCCR. Thus N is a CT module. Since CM R has a CT module, by [IW2, 5.11(2)] CT modules are precisely the MM generators.

4.3. Flops and Mutation Revisited. In this subsection we use the Auslander–McKay Correspondence to finally prove 4.2 in full generality, then run the Homological MMP in Figure 2 when X has only Gorenstein terminal singularities.

We first track certain objects under the mutation functor Φ_I in (2.L). As notation, suppose that M is a basic modifying R-module, where R is complete local d-sCY. Then for each indecomposable summand M_j of M, denote the corresponding simple and projective $\operatorname{End}_R(M)$ -modules by S_j and P_j respectively. For an indecomposable summand X_j of $\nu_I M$, we order the indecomposable summands of $\nu_I M$ so that either $X_j \cong M_j$ when $j \notin I$, or $X_i \cong J_i^*$ when $i \in I$. We denote the corresponding simple and projective $\operatorname{End}_R(\mathbf{v}_I M)$ -modules by S'_i and P'_i respectively.

Lemma 4.15. Suppose that R is a complete local d-sCY normal domain, and $M \in \operatorname{ref} R$ is a basic modifying module. With notation as above, choose a summand M_I of M, and consider the mutation functor Φ_I in (2.L). Then

- (1) $\Phi_I(P_j) = P'_j \text{ for all } j \notin I.$ (2) $\Phi_I(S_i) = S'_i[-1] \text{ for all } i \in I.$

Proof. By definition, $T_I := (\bigoplus_{i \notin I} P_i) \oplus C_I$, so part (1) is obvious. For (2), fix $i \in I$ and consider S_i . Set $P_I := \bigoplus_{k \in I} P_k$, and note that $C_I = \bigoplus_{k \in I} C_k$, where the sequence (2.K) is a direct sum of exact sequences

$$0 \to P_k \to Q_k \to C_k \to 0$$

with $P_I \notin \operatorname{add} Q_k$ for all $k \in I$. Applying $\operatorname{Hom}_{\Lambda}(-, S_i)$ gives, for every $k \in I$, an exact sequence

$$0 \to \operatorname{Hom}_{\Lambda}(C_k, S_i) \to \operatorname{Hom}_{\Lambda}(Q_k, S_i) \to \operatorname{Hom}_{\Lambda}(P_k, S_i) \to \operatorname{Ext}^1_{\Lambda}(C_k, S_i) \to 0.$$

Since $P_I \notin \operatorname{add} Q_k$, necessarily $\operatorname{Hom}_{\Lambda}(Q_k, S_i) = 0$. Thus by the above sequence

$$e_{j}\mathbf{R}\mathrm{Hom}_{\Lambda}(T_{I}, S_{i}) \cong \begin{cases} \mathbf{R}\mathrm{Hom}_{\Lambda}(P_{j}, S_{i}) & \text{if } j \notin I \\ \mathbf{R}\mathrm{Hom}_{\Lambda}(C_{j}, S_{i}) & \text{if } j \in I \end{cases} \cong \begin{cases} 0 & \text{if } j \notin I \\ \mathrm{Hom}_{\Lambda}(P_{j}, S_{i})[-1] & \text{if } j \in I, \end{cases}$$

and thus $e_i \mathbf{R} \operatorname{Hom}_{\Lambda}(T_I, S_i) \cong \mathbb{C} \delta_{ij}[-1]$ follows. From this, $\Phi_I(S_i) \cong S'_i[-1]$.

We also require the following, which does not need the crepant assumption.

Lemma 4.16. In the general setup of 2.8, $\Psi_X^{-1}\Lambda_I$ is a sheaf in degree zero, which we denote by \mathcal{E}_I .

Proof. Clearly Λ_I is a finitely generated Λ -module, so $\Psi_X^{-1}\Lambda_I \in {}^0\mathfrak{Per}(X, R)$. Further, by 2.14 $\mathbf{R}f_*(\Psi_X^{-1}\Lambda_I) = 0$ since $e\Lambda_I = 0$, so since the spectral sequence collapses it follows that $H^{-1}(\Psi_X^{-1}\Lambda_I) \in \mathcal{C}_f$ and $H^0(\Psi_X^{-1}\Lambda_I) \in \mathcal{C}_f$. But since $\Psi_X^{-1}\Lambda_I \in {}^0\mathfrak{Per}(X, R)$, by definition $\operatorname{Hom}(\mathcal{C}_f, H^{-1}(\Psi_X^{-1}\Lambda_I)) = 0$. Thus $\operatorname{Hom}(H^{-1}(\Psi_X^{-1}\Lambda_I), H^{-1}(\Psi_X^{-1}\Lambda_I)) = 0$ and so $H^{-1}(\Psi_X^{-1}\Lambda_I) = 0$. Thus $\Psi_X^{-1}\Lambda_I$ is a sheaf in degree zero. \Box

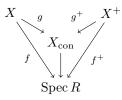
The following is one of the main results, from which 4.2 will follow easily.

Proposition 4.17. Assume the crepant setup of 2.9, with d = 3. We have $f: X \to \operatorname{Spec} R$ and as always set $N := H^0(\mathcal{V}_X), \Lambda := \operatorname{End}_R(N)$, and pick a collection of curves $\bigcup_{i \in I} C_i$ above the origin. If dim_C $\Lambda_I < \infty$ and $\nu_I N \cong H^0(\mathcal{V}_{X^+})$ for some other $f^+: X^+ \to \text{Spec } R$ satisfying the crepant setup 2.9, then

- (1) X^+ is the flop of X at the curves $\bigcup_{i \in I} C_i$.
- (2) The following diagram of equivalences is naturally commutative

$$\begin{array}{ccc} \mathrm{D^{b}}(\operatorname{coh} X) & \xrightarrow{\mathsf{Flop}} & \mathrm{D^{b}}(\operatorname{coh} X^{+}) \\ \Psi_{X} & & & & \downarrow \Psi_{X^{+}} \\ \mathrm{D^{b}}(\operatorname{mod} \Lambda) & \xrightarrow{\Phi_{I}} & \mathrm{D^{b}}(\operatorname{mod} \nu_{I}\Lambda). \end{array}$$

Proof. (1) We first establish that there are morphisms



to a common X_{con} . We define X_{con} to be the base space of the contraction of the curves $\bigcup_{i \in I} C_i$ in X. By 2.14, $\text{End}_R(N_{I^c})$ is derived equivalent to X_{con} , with $H^0(\mathcal{V}_{X_{\text{con}}}) \cong N_{I^c}$.

On the other hand, since $\operatorname{End}_R(\nu_I N)$ is derived equivalent to X^+ via $H^0(\mathcal{V}_{X^+}) \cong \nu_I N$, the summands of $\nu_I N$ correspond to exceptional curves. If we contract all the curves corresponding to the summand J_I^* , we obtain X_{con}^+ say. But again by 2.14 $\operatorname{End}_R(\frac{\nu_I N}{J_I^*}) = \operatorname{End}_R(N_{I^c})$ is derived equivalent to X_{con}^+ with $H^0(\mathcal{V}_{X_{\operatorname{con}}^+}) \cong N_{I^c}$, so by 4.4 $X_{\operatorname{con}} \cong X_{\operatorname{con}}^+$ and we can suppose that we are in the situation of the diagram above. As notation, we denote C_i^+ to be the curve in X^+ corresponding to the summand J_i^* of $\nu_I N$.

We next claim that $g^+: X^+ \to X_{con}$ is the flop of g, and to do this we use 2.7. First, $g^+: X^+ \to X_{con}$ does not contract a divisor to a curve, since $\Lambda_I \cong (\mathbf{v}_I \Lambda)_I$ and so $\dim_{\mathbb{C}}(\mathbf{v}_I \Lambda)_I < \infty$ by [IW2, 6.20]. Now with the notation as in §2.2, we let D_i in X be the Cartier divisor cutting exactly the curve C_i , and D_i^+ be the Cartier divisor in X^+ cutting exactly the curve C_i^+ . Since $-(-D_i)$ is g-ample, we let D'_i denote the proper transform of $-D_i$. In what follows, we will use the notation $[-]_X$ to denote something viewed in the class group of X. Since g and g^+ give reflexive equivalences, we will also abuse notation and for example refer to the divisor D_i on X_{con} , and on X^+ .

We next claim that D'_i is Cartier. Since X_{con} has only Gorenstein terminal singularities, which locally are hypersurfaces, by 2.25 $\nu_I \nu_I N \cong N$, and further recall $\nu_I N$ has summands N_i $(i \notin I)$ and $J_i^* \cong K_i$ $(i \in I)$. Further, by A.7 applied to $\text{End}_R(\nu_I N)$ there is an exact sequence

$$0 \to \operatorname{Hom}_{R}(\mathbf{v}_{I}N, K_{i}) \to \operatorname{Hom}_{R}(\mathbf{v}_{I}N, V_{i}) \to \operatorname{Hom}_{R}(\mathbf{v}_{I}N, U_{i}) \to \\ \to \operatorname{Hom}_{R}(\mathbf{v}_{I}N, K_{i}) \to C \to 0,$$

where C has a finite filtration by the simple $v_I \Lambda$ -modules S'_j $(j \in I)$. Across the equivalence, this gives an exact sequence

$$0 \to \mathcal{N}_i^+ \xrightarrow{\delta_i} \mathcal{W}_i \xrightarrow{\varepsilon_i} \mathcal{U}_i \to \mathcal{N}_i^+ \to \mathcal{E} \to 0$$
(4.A)

in ⁰ $\mathfrak{Per}(X^+, R)$ for some g^+ -trivial bundles \mathcal{W}_i and \mathcal{U}_i , and by 2.11 and 4.16 \mathcal{E} is a sheaf with a finite filtration with factors from $\mathcal{O}_{C_j}(-1)$ $(j \in I)$. Since all terms are sheaves, by splicing, considering the associated triangles and then taking cohomology, it follows that (4.A) is an exact sequence in $\operatorname{coh} X^+$. Let $\mathcal{F}_i := \operatorname{Cok} \delta_i$, then for any closed point $x \in X^+ \setminus C$, $\mathcal{E}_x = 0$, and so certainly $(\mathcal{F}_i)_x$ is free. Further, if $x \in C$ then (4.A) localises to a finite projective resolution of \mathcal{E}_x . Since the $\mathcal{O}_{C_j}(-1)$ are Cohen–Macaulay, depth $_{\mathcal{O}_{X^+,x}} \mathcal{E}_x = 1$, so by Auslander–Buchsbaum $\operatorname{pd}_{\mathcal{O}_{X^+,x}} \mathcal{E}_x = 2$ and thus $(\mathcal{F}_i)_x$ is free. This shows that \mathcal{F}_i is a locally free sheaf.

Denote $\mathcal{G}_i := \operatorname{Cok} \varepsilon_i$. Since $\mathbf{R}^1 g_*^+ \mathcal{U}_i = 0$ as in the proof of 2.14, it follows that $\mathbf{R}^1 g_*^+ \mathcal{G}_i = 0$. Then since $\mathbf{R} g_*^+ \mathcal{E} = 0$, it then follows that $\mathbf{R}^1 g_*^+ \mathcal{N}_i^+ = 0$. Thus $\mathbf{R} g_*^+ \mathcal{N}_i^+ = g_*^+ \mathcal{N}_i^+$, and again as in the proof of 2.14, $\mathbf{R} g_*^+ \mathcal{W}_i = g_*^+ \mathcal{W}_i$.

As a consequence, $\mathbf{R}g_*^+\mathcal{F}_i = g_*^+\mathcal{F}_i$ and there is an exact sequence

$$0 \to g_*^+ \mathcal{N}_i^+ \to g_*^+ \mathcal{W}_i \to g_*^+ \mathcal{F}_i \to 0 \tag{4.B}$$

on $X_{\rm con}$. Across the equivalence with $\operatorname{End}_R(N_{I^c})$, by 2.14 this corresponds to a triangle

$$\operatorname{Hom}_{R}(N_{I^{c}}, K_{i}) \xrightarrow{\cdot c_{i}} \operatorname{Hom}_{R}(N_{I^{c}}, V_{i}) \to \Psi_{X_{\operatorname{con}}}(g_{*}^{+}\mathcal{F}_{i}) \to$$

But by construction

$$0 \to \operatorname{Hom}_{R}(N_{I^{c}}, K_{i}) \xrightarrow{\cdot c_{i}} \operatorname{Hom}_{R}(N_{I^{c}}, V_{i}) \to \operatorname{Hom}_{R}(N_{I^{c}}, N_{i}) \to 0$$

is exact, and by 2.14 $g_*\mathcal{N}_i$ corresponds under the equivalence to $\operatorname{Hom}_R(N_{I^c}, N_i)$. It follows that $g_*\mathcal{N}_i \cong g_*^+\mathcal{F}_i$, and so by reflexive equivalence D'_i , the proper transform of $-D_i$, is Cartier and is represented by $[\det \mathcal{F}_i]_{X^+}$. Using the exact sequence

$$0 \to \mathcal{N}_i^+ \to \mathcal{W}_i \to \mathcal{F}_i \to 0$$

it follows that

$$[D'_{i}]_{X^{+}} \cdot C^{+}_{j} = [\det \mathcal{F}_{i}]_{X^{+}} \cdot C^{+}_{j} = -[\det \mathcal{N}^{+}_{i}]_{X^{+}} \cdot C^{+}_{j} = \delta_{ij}$$

for all $j \in I$, since \mathcal{W}_i is g^+ -trivial. Hence by 2.7 $g^+: X^+ \to X_{\text{con}}$ is the flop of g. (2) Denote $\Theta := \Psi_{X^+}^{-1} \circ \Phi_I \circ \Psi_X$: D^b(coh X) \to D^b(coh X^+), then it is well known that this is a Fourier–Mukai functor [DW1, 6.16], and being the composition of equivalences it is also an equivalence. Note that

- (1) $\mathbf{R}g_*^+ \circ F \cong \mathbf{R}g_*,$
- (2) $F(\mathcal{O}_X) \cong \mathcal{O}_{X^+},$
- (3) $F(\mathcal{O}_{C_i}(-1)) \cong \mathcal{O}_{C^+}(-1)[-1]$ for all $i \in I$,

when F is either Flop or Θ . For Flop, the inverse of the Bridgeland-Chen flop functor, this is well-known; see e.g. [DW1, 7.16] or [T3, Appendix B]. For the functor Θ , denoting $\Gamma := \operatorname{End}_R(N_{I^c})$, property (1) follows from the commutative diagram

where the two outer squares commute by 2.14 and the commutativity of the inner square is obvious. Property (2) follows from 4.15(1), and property (3) from 4.15(2). Hence the functor $\Theta^{-1} \circ \mathsf{Flop}$ satisfies the conditions (1)–(3) of 4.3, so $\Theta^{-1} \circ \mathsf{Flop} \cong \phi_*$ where $\phi: X \to X$ is an isomorphism compatible with the contraction. Since ϕ is necessarily the identity away from the flopping locus, $\phi = \mathrm{Id}$, so $\Theta \cong \mathsf{Flop}$.

Thus to prove 4.2, by 4.17 we just need to establish that $\nu_I N \cong H^0(\mathcal{V}_{X^+})$ for some $X^+ \to \operatorname{Spec} R$. The trick in 4.5 in the minimal model case with $I = \{i\}$ was to use Riedtmann–Schofield. To work in full generality requires another standard technique from representation theory, namely the Bongartz completion.

Proof of 4.2. Since R admits an MM module, by Bongartz completion we may find $F \in$ ref R such that $\operatorname{End}_R(v_IN \oplus F)$ is an MMA [IW2, 4.18]. Since v_IN is a generator, necessarily $F \in \operatorname{CM} R$. By the Auslander–McKay Correspondence 4.10 $v_IN \oplus F$ is one of the finite number of MM generators, and further $v_IN \oplus F = H^0(\mathcal{V}_Y)$ for some minimal model Y, where the non-free summands of $v_IN \oplus F$ correspond to the exceptional curves for $Y \to \operatorname{Spec} R$. Contracting all the curves in Y that correspond to the summand F, as in (1.B) we factorise $Y \to \operatorname{Spec} R$ as $Y \to X^+ \to \operatorname{Spec} R$ for some X^+ . By 2.14 $v_IN \cong H^0(\mathcal{V}_{X^+})$, so parts (1) and (2) both follow from 4.17.

Corollary 4.18. We can run the Homological MMP in Figure 2 when X has only Gorenstein terminal singularities, for arbitrary subsets of curves.

Proof. This now follows from 3.5, 4.2 and 2.15.

Corollary 4.19. With the crepant setup $X \to \operatorname{Spec} R$ with d = 3, choose a subset of curves $\bigcup_{i \in I} C_i$ and suppose that $\dim_{\mathbb{C}} \Lambda_I < \infty$, so that $\bigcup_{i \in I} C_i$ flops. Then

- (1) $\mathcal{M}_{\mathsf{rk},\vartheta}(\Lambda) \cong X$ for all $\vartheta \in C_+(\Lambda)$.
- (2) $\mathcal{M}_{\mathsf{rk},\vartheta}(\mathsf{v}_I\Lambda) \cong X^+$ for all $\vartheta \in C_+(\mathsf{v}_I\Lambda)$.

Proof. Part (1) follows immediately from [Kar, 5.2.5] applied to X. By 4.2, part (2) follows from [Kar, 5.2.5] applied to X^+ .

The following extends 4.6 by dropping the Q-factorial assumption and considering multiple curves, but now the statement is a little more subtle.

Corollary 4.20. With the crepant setup of 2.9, suppose further that d = 3. Set $N := H^0(\mathcal{V}_X)$, and pick a subset of curves $\bigcup_{i \in I} C_i$. Then

- (1) If $\bigcup_{i \in I} C_i$ flops (equivalently, by 3.5, dim_C $\Lambda_I < \infty$), then $\nu_I N \cong H^0(\mathcal{V}_{X^+})$.
- (2) If $I = \{i\}$, $pd_{\Lambda}\Lambda_i < \infty$ and C_i does not flop (equivalently, $\dim_{\mathbb{C}} \Lambda_i = \infty$), then $\nu_I N \cong N$.

Proof. Part (1) is just 4.2. For part (2), since Λ_i is local and has finite projective dimension, by [Ra, 2.15] depth_R $\Lambda_i = \dim_R \Lambda_i = \operatorname{inj.dim}_{\Lambda_i} \Lambda_i$. The result follows using the argument of [IW2, 6.23(1)].

Remark 4.21. The statement in 4.20(2) is not true for multiple curves, indeed the hypothesis in 4.20(2) cannot be weakened. First, if $I \neq \{i\}$ then Λ_i is not local and there are examples that satisfy $\nu_I N \ncong N$ even when $\mathrm{pd}_{\Lambda}\Lambda_I < \infty$ and $\dim_{\mathbb{C}}\Lambda_I = \infty$. Second, if $I = \{i\}$ and $\mathrm{pd}_{\Lambda}\Lambda_I = \infty$, there are examples that satisfy $\dim_{\mathbb{C}}\Lambda_i = \infty$ but $\nu_I N \ncong N$.

There are two separate problems here, namely in general Λ_I need not be perfect, and it need not be Cohen–Macaulay. Both cause independent technical difficulties, and this will also be evident in §5. See also B.1.

One further corollary of this section is that both commutative and noncommutative deformations of curves are preserved under flop.

Corollary 4.22. With the crepant setup of 2.9, and d = 3, pick a subset $\bigcup_{i \in I} C_i$ of curves, and suppose that $\bigcup_{i \in I} C_i$ flops. Then

- (1) The noncommutative deformation functor of $\bigcup_{i \in I} C_i$ is represented by the same ring as the noncommutative deformation functor of $\bigcup_{i \in I} C_i^+$.
- (2) The statement in (1) also holds for commutative deformations.

Proof. By 3.5, since $\bigcup_{i \in I} C_i$ flops, dim_C $\Lambda_I < \infty$ and the noncommutative deformations of $\bigcup_{i \in I} C_i$ are represented by Λ_I . By 3.5 and 4.2, the noncommutative deformations of $\bigcup_{i \in I} C_i^+$ are represented by $(\mathbf{v}_I \Lambda)_I$. By [IW2, 6.20] $\Lambda_I \cong (\mathbf{v}_I \Lambda)_I$. (2) This follows by taking the abelianization of (1).

4.4. Auslander–McKay Revisited. Now that 4.2 has been established in full generality, we can extend the Auslander–McKay Correspondence in 4.10.

Definition 4.23. Let R be as above, then

- (1) The derived mutation groupoid is defined by the following generating set. It has vertices $D^{b}(\text{mod} \operatorname{End}_{R}(N))$, running over all isomorphism classes of basic MM generators N, and as arrows each vertex $D^{b}(\text{mod} \operatorname{End}_{R}(N))$ has the mutation functors Φ_{I} emerging, as I runs through all possible summands satisfying $\dim_{\mathbb{C}} \Lambda_{I} < \infty$.
- (2) The derived flops groupoid is defined by the following generating set. It has vertices D^b(coh X), running over all minimal models X, and as arrows we connect vertices by the inverse of the Bridgeland-Chen flop functors, running through all possible combinations of flopping curves.

Theorem 4.24. The correspondence in 4.10 further satisfies

- (3)' The full mutation graph of the MM generators coincides with the full flops graph of the minimal models.
- (4) The derived groupoid of the MM modules is functorially isomorphic to the derived flops groupoid of the minimal models.

Proof. (3)' By definition, the full mutation graph and derived mutation groupoid only considers \mathbf{v}_I provided that $\dim_{\mathbb{C}} \Lambda_I < \infty$, which by 3.5 is equivalent to the condition that $\bigcup_{i \in I} C_i$ flops. Hence the result follows by combining the bijection in 4.10 with 4.2(1). (4) This follows by combining the bijection with 4.2(2).

5. STABILITY AND MUTATION

In this section we relate stability and mutation, then use this together with the Homological MMP (proved in 4.18) to give results in GIT, specifically regarding chamber decompositions and later in §6.1 the Craw–Ishii conjecture.

After first proving general moduli-tracking results in §5.2, running Figure 2 over all possibilities and tracking all the moduli back then computes the full GIT chamber decomposition. We further prove in §5.3 that mutation is preserved under generic hyperplane section, which in effect means (in §5.4) that the chamber decomposition reduces to knitting on ADE surface singularities, which is very easy to calculate. Amongst other things, this observation can be used to prove the braiding of flops in dimension three [DW3].

5.1. **GIT background.** There are two GIT approaches to moduli that could be used in this paper. The first is quiver GIT, which relies on presenting Λ^{op} as (the completion of) a quiver with relations, and the second is the more abstract approach given in [VdB2, §6.2]. For most purposes either is sufficient, so for ease of exposition we use quiver GIT.

Consider $\Lambda = \operatorname{End}_R(N)$ and present $\Lambda^{\operatorname{op}}$ as the complete path algebra of a quiver Q subject to relations I, where the number of vertices in Q equals the number of indecomposable summands of N. We denote by Q_0 the vertex set of Q, and remark that under the conventions in §1.6, Λ -modules correspond to representations of (Q, I). Below, we will implicitly use this identification. We call an element $\beta \in \mathbb{Z}_{\geq 0}^{|Q_0|}$ a dimension vector. We denote by $(\mathbb{Z}^{|Q_0|})^*$ the dual lattice of $\mathbb{Z}^{|Q_0|}$, and define the parameter space Θ by

$$\Theta := (\mathbb{Z}^{|Q_0|})^* \otimes_{\mathbb{Z}} \mathbb{Q}.$$

An element $\vartheta \in \Theta$ is called a *stability parameter*. For a stability parameter ϑ and a dimension vector β , the canonical pairing defines us

$$artheta\cdoteta:=\sum_{i\in Q_0}artheta_ieta_i$$

Given $x \in \text{fdmod } \Lambda = \text{Rep}(Q, I)$, let $\underline{\dim} x \in \mathbb{Z}_{\geq 0}^{|Q_0|}$ denote its dimension vector, considering x as a finite dimensional representation.

Definition 5.1. [Ki] Given $\vartheta \in \Theta$, $x \in \text{fdmod } \Lambda = \text{Rep}(Q, I)$ is called ϑ -semistable if $\vartheta \cdot \underline{\dim x} = 0$ and every subobject $x' \subseteq x$ satisfies $\vartheta \cdot \underline{\dim x'} \ge 0$. Such an object x is called ϑ -stable if the only subobjects x' with $\vartheta \cdot \underline{\dim x'} = 0$ are x and 0. Two ϑ -semistable modules are called S-equivalent if they have filtrations by ϑ -stable modules which give isomorphic associated graded modules. Further, for a given β , we say that ϑ is generic if every ϑ -semistable module of dimension vector β is ϑ -stable.

Notation 5.2. For any $\vartheta \in \Theta$ and any dimension vector β ,

- (1) Denote by $\mathcal{M}_{\beta,\vartheta}(\Lambda)$ the moduli space of ϑ -semistable Λ -modules of dimension vector β .
- (2) Denote by $S_{\vartheta}(\Lambda)$ the full subcategory of fdmod Λ which has as objects the ϑ semistable objects, and denote by $S_{\beta,\vartheta}(\Lambda)$ the full subcategory of $S_{\vartheta}(\Lambda)$ consisting
 of those elements with dimension vector β .

By King [Ki] (see also [VdB2, 6.2.1]) $\mathcal{M}_{\beta,\vartheta}(\Lambda)$ is a coarse moduli space that parameterises *S*-equivalence classes of ϑ -semistable modules of dimension vector β . If further β is an indivisible vector and ϑ is generic, then $\mathcal{M}_{\beta,\vartheta}(\Lambda)$ is a fine moduli space, and *S*-equivalence classes coincide with isomorphism classes.

5.2. Tracking Stability Through Mutation. In this subsection we track stability conditions through mutation, extending [SY, NS] to work in a much greater level of generality. Throughout, we will make use of the following setup. Setup 5.3. Suppose that R is a normal complete local d-sCY commutative algebra with $d \geq 2, M$ is a basic modifying module and M_I is a summand of M. Set $\Lambda := \operatorname{End}_R(M)$ and $\Gamma := \mathbf{v}_I \Lambda$. We denote the projective Λ -modules by P_j , the simple Λ -modules by S_j , and the simple Γ -modules by S'_i .

For each indecomposable summand M_i^* of M_I^* , consider its minimal right add $M_{I^c}^*$ approximation

$$\bigoplus_{j \notin I} M_j^{* \oplus b_{i,j}} \to M_i$$

for some collection $b_{i,j} \in \mathbb{Z}_{\geq 0}$. Dualizing and using (A.A) gives an exact sequence

$$0 \to M_i \to \bigoplus_{j \notin I} M_j^{\oplus b_{i,j}}.$$
(5.A)

Summing the sequences (5.A) together gives the minimal left add M_{Ic} -approximation of M_I , namely (A.A). In other words, we decompose U_I as $U_I = \bigoplus_{i \in I} U_i$, then decompose each U_i as $U_i = \bigoplus_{j \notin I} M_i^{\oplus b_{i,j}}$.

Applying $\operatorname{Hom}_{R}(M, -)$ to (5.A) gives exact sequences

$$0 \to \operatorname{Hom}_{R}(M, M_{i}) \to \operatorname{Hom}_{R}(M, \oplus_{j \notin I} M_{j}^{\oplus b_{i,j}}) \to C_{i} \to 0$$
(5.B)

for each $i \in I$, and summing the sequences in (5.B) together gives (2.K). Hence by definition $T_I = (\bigoplus_{i \notin I} P_i) \oplus (\bigoplus_{i \in I} C_i)$, where recall that T_I is the tilting module defined in §**2.3**.

Definition 5.4. Suppose that β is a dimension vector, and $\vartheta \in \Theta$ is a stability condition. Given the data $\mathbf{b}_{\mathbf{I}} = (b_{i,j})_{i \in I, j \notin I}$ from (5.A), we define the vectors $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \boldsymbol{\beta}$ and $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta$ by

$$(\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\beta)_{i} = \begin{cases} \beta_{i} & \text{if } i \notin I \\ \left(\sum_{j \notin I} b_{i,j}\beta_{j}\right) - \beta_{i} & \text{if } i \in I \end{cases} \qquad (\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta)_{j} = \begin{cases} \vartheta_{j} + \sum_{i \in I} b_{i,j}\vartheta_{i} & \text{if } j \notin I \\ -\vartheta_{j} & \text{if } j \in I. \end{cases}$$

Thus given the data of $\mathbf{b}_{\mathbf{I}} = (b_{i,j})$, we thus view $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}$ as an operation on dimension vectors, and as a (different) operation on stability parameters.

Remark 5.5. We remark that the b's are defined with respect to the mutation $\Lambda \mapsto \gamma_I \Lambda$. When we iterate and consider another mutation $\nu_I \Lambda \mapsto \nu_I \nu_I \Lambda$, the b's may change for this second mutation. This change may occur even in the situation $\nu_I \nu_I \Lambda \cong \Lambda$, and we are considering the mutation back $\nu_I \Lambda \mapsto \nu_I \nu_I \Lambda \cong \Lambda$. The papers [SY, NS] involve a global rule for $v_{\mathbf{b}_{\mathbf{f}}} \vartheta$ (in their notation, $s_i \vartheta$), and this is the reason why their combinatorial rule, and proofs, only work in a very restricted setting.

The following two lemmas are elementary.

Lemma 5.6. For any dimension vector β and any stability $\vartheta \in \Theta$.

- (1) $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \boldsymbol{\beta} \cdot \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \boldsymbol{\vartheta} = \boldsymbol{\beta} \cdot \boldsymbol{\vartheta}.$ (2) $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\mathbf{\beta} = \mathbf{\beta}.$
- (3) $\vartheta \cdot \nu_{\mathbf{b}_{\mathbf{I}}} \beta = \nu_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \beta.$

Proof. This is easily verified by direct calculation.

Lemma 5.7. With the setup 5.3 of this subsection, let $x \in \text{mod } \Lambda$ and $y \in \text{mod } \Gamma$.

- (1) If $\operatorname{Ext}_{\Lambda}^{1}(T_{I}, x) = 0$, then $\operatorname{\underline{\dim}} \operatorname{Hom}_{\Lambda}(T_{I}, x) = \mathbf{v}_{\mathbf{b}_{I}} \operatorname{\underline{\dim}} x$. (2) If $\operatorname{Tor}_{\Gamma}^{\Gamma}(T_{I}, y) = 0$, then $\operatorname{\underline{\dim}}(T_{I} \otimes_{\Gamma} y) = \mathbf{v}_{\mathbf{b}_{I}} \operatorname{\underline{\dim}} y$.

Proof. (1) By definition $T_I = (\bigoplus_{i \notin I} P_i) \oplus (\bigoplus_{i \in I} C_i)$. Set $\beta := \underline{\dim} x$. It is clear that

$$e_t \operatorname{Hom}_{\Lambda}(T_I, x) = \begin{cases} \operatorname{Hom}_{\Lambda}(P_t, x) & \text{if } t \notin I \\ \operatorname{Hom}_{\Lambda}(C_t, x) & \text{if } t \in I \end{cases} \cong \begin{cases} e_t x & \text{if } t \notin I \\ \operatorname{Hom}_{\Lambda}(C_t, x) & \text{if } t \in I \end{cases}$$

and thus $(\underline{\dim} \operatorname{Hom}_{\Lambda}(T_{I}, x))_{t} = \beta_{t}$ when $t \notin I$, and hence we just need to verify that $\dim_{\mathbb{C}} \operatorname{Hom}_{\Lambda}(C_{t}, x) = \left(\sum_{j \notin I} b_{t,j} \beta_{j}\right) - \beta_{t}$. But by the assumptions, applying $\operatorname{Hom}_{\Lambda}(-, x)$ to the exact sequence (5.B) gives an exact sequence

$$0 \to \operatorname{Hom}_{\Lambda}(C_t, x) \to \operatorname{Hom}_{\Lambda}(\oplus_{j \notin I} P_j^{\oplus b_{t,j}}, x) \to \operatorname{Hom}_{\Lambda}(P_t, x) \to 0.$$

Counting dimensions, using $\operatorname{Hom}_{\Lambda}(P_j, x) \cong e_j x$, yields the result.

(2) By assumption and 2.20, $T_I \otimes_{\Gamma}^{\mathbf{L}} y = T_I \otimes_{\Gamma} y$. Mutation gives a derived equivalence, so $\mathbf{R}\operatorname{Hom}_{\Lambda}(T_I, T_I \otimes_{\Gamma} y) \cong y$, which implies that $T_I \otimes_{\Gamma} y$ satisfies the conditions in (1), and further $\operatorname{Hom}_{\Lambda}(T_I, T_I \otimes_{\Gamma} y) \cong y$. Consequently

$$\underline{\dim} y = \underline{\dim} \operatorname{Hom}_{\Lambda}(T_I, T_I \otimes_{\Gamma} y) \stackrel{(1)}{=} \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim}(T_I \otimes_{\Gamma} y),$$
mplies that $\underline{\dim}(T_I \otimes_{\Gamma} y) = \mathbf{y}, \quad \mathbf{y}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim}(T_I \otimes_{\Gamma} y) = \mathbf{y}, \quad \dim(T_I \otimes_{\Gamma} y) = \mathbf{y},$

which by 5.6(2) implies that $\underline{\dim}(T_I \otimes_{\Gamma} y) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim}(T_I \otimes_{\Gamma} y) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim} y.$

When tracking stability under mutation, as in 4.21 the fact that Λ_I need not be Cohen-Macaulay and need not be perfect causes problems. The following two technical results allows us to overcome the first. To avoid cases in the statement and proof, as a convention $\frac{M}{(a_1,...,a_t)M} := M$ when t = 0.

Lemma 5.8. With the setup 5.3 of this subsection, let $M, N \in \text{mod } \Lambda$ with depth_R M := t, and choose a regular sequence $\{a_1, \ldots, a_t\}$ for M. If

(1) $\operatorname{pd}_{\Lambda} M < \infty$, (2) $N \in \operatorname{fdmod} \Lambda$, (3) $\operatorname{Hom}_{\Lambda} \left(N, \frac{M}{(a_1, \dots, a_t)M} \right) = 0$,

then $\operatorname{Ext}_{\Lambda}^{d-t}(M, N) = 0.$

Proof. When t = 0, $\operatorname{Ext}_{\Lambda}^{d}(M, N) \cong D \operatorname{Hom}_{\Lambda}(N, M) = 0$ since Λ is *d*-sCY, *M* has finite projective dimension and *N* has finite length. This establishes the result in the case t = 0, so we can assume that t > 0. Hence a_1 exists, and applying $\operatorname{Hom}_{\Lambda}(-, N)$ to the exact sequence

$$0 \to M \xrightarrow{a_1} M \to \frac{M}{a_1 M} \to 0$$

gives an exact sequence

$$\dots \to \operatorname{Ext}_{\Lambda}^{d-t}(M,N) \xrightarrow{\cdot a_1} \operatorname{Ext}_{\Lambda}^{d-t}(M,N) \to \operatorname{Ext}_{\Lambda}^{(d-t)+1}\left(\frac{M}{a_1M},N\right) \to \dots$$

If $\operatorname{Ext}_{\Lambda}^{d-t}(M, N) \neq 0$, then by Nakayama's Lemma the image of $(\cdot a_1)$ is a proper submodule of $\operatorname{Ext}_{\Lambda}^{d-t}(M, N)$, which implies that $\operatorname{Ext}_{\Lambda}^{(d-t)+1}(\frac{M}{a_1M}, N) \neq 0$. Inducting along the regular sequence gives $\operatorname{Ext}_{\Lambda}^{d}(\frac{M}{(a_1,\ldots,a_t)M}, N) \neq 0$. But again

$$\operatorname{Ext}_{\Lambda}^{d}\left(\frac{M}{(a_{1},\dots,a_{t})M},N\right) \cong D\operatorname{Hom}_{\Lambda}\left(N,\frac{M}{(a_{1},\dots,a_{t})M}\right) = 0$$

since Λ is *d*-sCY, $\frac{M}{(a_1,...,a_t)M}$ has finite projective dimension [Wei, 4.3.14], and N has finite length. This is a contradiction, and so $\operatorname{Ext}_{\Lambda}^{d-t}(M,N) = 0$, as claimed. \Box

Corollary 5.9. With the setup 5.3 of this subsection, suppose that either

(a) $\mathbf{v}_I M \cong M$, or

(b) d = 3, $\nu_I \nu_I M \cong M$ and $\dim_{\mathbb{C}} \Lambda_I < \infty$.

Set $t := \operatorname{depth}_R \Lambda_I$, then $\operatorname{Ext}_{\Lambda}^{d-t}(\Lambda_I, x) = 0$ for all $x \in \operatorname{fdmod} \Lambda$ provided $\operatorname{Hom}_{\Lambda}(x, S_i) = 0$ for all $i \in I$.

Proof. By either 2.21(2) or 2.22(2), $\mathrm{pd}_{\Lambda}\Lambda_{I} < \infty$. Thus by 5.8 applied with $M = \Lambda_{I}$ and N = x, we only need to verify that $\mathrm{Hom}_{\Lambda}(x, \frac{\Lambda_{I}}{(a_{1}, \dots, a_{t})\Lambda_{I}})$ is zero. Consider an element f, then since x is finite dimensional, so is $\mathrm{Im} f$. Thus being a submodule of a factor of Λ_{I} , $\mathrm{Im} f$ must have a finite filtration with factors from the set $\{S_{i} \mid i \in I\}$. Since $\mathrm{Hom}_{\Lambda}(x, S_{i}) = 0$

for all $i \in I$, inducting along the finite filtration gives $\operatorname{Hom}_{\Lambda}(x, \operatorname{Im} f) = 0$, and hence $\operatorname{Hom}_{\Lambda}(x, \frac{\Lambda_I}{(a_1, \dots, a_t)\Lambda_I}) = 0$.

The following, which is a consequence of 2.26 and 5.9, will be needed in 5.12.

Corollary 5.10. With the setup 5.3 of this subsection, assume that either

- (a) $\mathbf{v}_I M \cong M$, or
- (b) $\mathbf{v}_I \mathbf{v}_I M \cong M$ and $\dim_{\mathbb{C}} \Lambda_I < \infty$.

Then for all $x \in \operatorname{fdmod} \Lambda$ and $y \in \operatorname{fdmod} \Gamma$,

- (1) $\operatorname{Ext}_{\Lambda}^{1}(T_{I}, x) = 0$ provided $\operatorname{Hom}_{\Lambda}(x, S_{i}) = 0$ for all $i \in I$.
- (2) $\operatorname{Tor}_{1}^{\Gamma}(T_{I}, y) = 0$ provided $\operatorname{Hom}_{\Gamma}(S'_{i}, y) = 0$ for all $i \in I$.

Proof. Denote $t = \operatorname{depth} \Lambda_I$.

(1) In situation (a), by 2.21(2) $\mathrm{pd}_{\Lambda}\Lambda_{I} = 2$ and $\mathrm{Ext}_{\Lambda}^{1}(T_{I}, x) \cong \mathrm{Ext}_{\Lambda}^{2}(\Lambda_{I}, x)$, which is $\mathrm{Ext}_{\Lambda}^{d-t}(\Lambda_{I}, x)$ by Auslander–Buchsbaum. This is zero by 5.9. In situation (b), by A.7(4) the assumptions in fact force $d \leq 3$. If d = 2 then the result is precisely 2.26, so we can assume that d = 3. In this case, by 2.22(2) $\mathrm{pd}_{\Lambda}\Lambda_{I} = 3$ and $\mathrm{Ext}_{\Lambda}^{1}(T_{I}, x) \cong \mathrm{Ext}_{\Lambda}^{3}(\Lambda_{I}, x) = \mathrm{Ext}_{\Lambda}^{d-t}(\Lambda_{I}, x)$, which again is zero by 5.9.

(2) By [CE, VI.5.1] There is an isomorphism

$$\operatorname{Tor}_{1}^{\Gamma}(T_{I}, y) \cong D\operatorname{Ext}_{\Gamma^{\operatorname{op}}}^{\Gamma}(T_{I}, Dy),$$

where D is the \mathbb{C} -dual. Note that $0 = \operatorname{Hom}_{\Gamma}(S'_i, y) \cong \operatorname{Hom}_{\Gamma^{\operatorname{op}}}(Dy, DS'_i)$ for all $i \in I$. Now the simple left $\Gamma^{\operatorname{op}}$ -modules are the DS'_j , and by A.6 either the assumptions (a) or (b) hold for $(\mathbf{v}_I M)^*$. Hence by 2.20(2) we can apply (1) to $\Gamma^{\operatorname{op}} \cong \operatorname{End}_R((\mathbf{v}_I M)^*)$ to obtain $\operatorname{Ext}^{1}_{\Gamma^{\operatorname{op}}}(T_I, Dy) = 0$, and so $\operatorname{Tor}^{1}_{\Gamma}(T_I, y) = 0$.

The following lemma is elementary.

Lemma 5.11. Assume the setup 5.3 of this subsection. Suppose that $\vartheta \in \Theta(\Lambda)$ and $\phi \in \Theta(\Gamma)$ are stability parameters, with $x \in S_{\vartheta}(\Lambda)$ and $y \in S_{\Phi}(\Gamma)$.

(1) If $\vartheta_i > 0$ for all $i \in I$, then $\operatorname{Hom}_{\Lambda}(x, S_i) = 0$ for all $i \in I$.

(

(2) If $\phi_i < 0$ for all $i \in I$, then $\operatorname{Hom}_{\Gamma}(S'_i, y) = 0$ for all $i \in I$.

Proof. (1) If there exists a non-zero morphism $x \to S_i$, then necessarily it has to be surjective, so there is a short exact sequence

$$0 \to K_i \to x \to S_i \to 0.$$

This implies that $\vartheta_i = \vartheta \cdot \underline{\dim} S_i = \vartheta \cdot \underline{\dim} x - \vartheta \cdot \underline{\dim} K_i \leq 0$, since $x \in S_\vartheta(\Lambda)$, contradicting the assumption $\vartheta_i > 0$.

(2) Any non-zero morphism $S'_i \to y$ is necessarily injective, so $\phi_i = \phi \cdot \underline{\dim} S'_i \ge 0$ since $y \in S_{\phi}(\Gamma)$. Since $\phi_i < 0$, the morphism must be zero.

Given the technical preparation above, the following is now very similar to [SY, 3.5].

Theorem 5.12. With the setup 5.3 of this subsection, assume that either

- (a) $\mathbf{v}_I M \cong M$, or
- (b) $\mathbf{v}_I \mathbf{v}_I M \cong M$ and $\dim_{\mathbb{C}} \Lambda_I < \infty$.

Then for every dimension vector β , and for every $\vartheta \in \Theta$ with $\vartheta_i > 0$ for all $i \in I$,

- (1) $\operatorname{Hom}_{\Lambda}(T_{I}, -) \colon \mathcal{S}_{\vartheta}(\Lambda) \to \mathcal{S}_{\nu_{\mathbf{b}_{I}}\vartheta}(\Gamma)$ is an exact functor.
- (2) $T_I \otimes_{\Gamma} -: \mathcal{S}_{\mathbf{v}_{\mathbf{b}_{\mathbf{r}}}\vartheta}(\Gamma) \to \mathcal{S}_{\vartheta}(\Lambda)$ is an exact functor.
- (3) There is a categorical equivalence

$$\mathcal{S}_{\beta,\vartheta}(\Lambda) \xrightarrow[T_I \otimes_{\Gamma} -]{} \mathcal{S}_{\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\beta,\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$$
(5.C)

preserving S-equivalence classes, under which ϑ -stable modules correspond to $\nu_{\mathbf{b}_{\mathbf{I}}}\vartheta$ -stable modules.

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(4) ϑ is generic if and only if $\nu_{\mathbf{b}_{\mathbf{l}}}\vartheta$ is generic.

Proof. (1) By 5.10(1) and 5.11(1), $\operatorname{Hom}_{\Lambda}(T_{I}, -)$ is exact out of $\mathcal{S}_{\vartheta}(\Lambda)$. To see that $\operatorname{Hom}_{\Lambda}(T_{I}, -)$ maps $\mathcal{S}_{\vartheta}(\Lambda)$ to $\mathcal{S}_{\mathbf{v}_{\mathbf{b}_{I}}\vartheta}(\Gamma)$, suppose that $x \in \mathcal{S}_{\vartheta}(\Lambda)$, let $y := \operatorname{Hom}_{\Lambda}(T_{I}, x) \cong$ $\mathbf{R}\operatorname{Hom}_{\Lambda}(T_{I}, x)$ and consider a Γ -submodule $y' \subseteq y$. Since $\mathbf{v}_{\mathbf{b}_{I}}\vartheta \cdot \underline{\dim} y = \mathbf{v}_{\mathbf{b}_{I}}\vartheta \cdot \mathbf{v}_{\mathbf{b}_{I}}\underline{\dim} x =$ $\vartheta \cdot \underline{\dim} x = 0$ by 5.7(1) and 5.6(1), it suffices to show that $\mathbf{v}_{\mathbf{b}_{I}}\vartheta \cdot \underline{\dim} y' \geq 0$.

The inclusion $y' \subseteq y$ induces an exact sequence

$$0 \to y' \to y \to c \to 0.$$

Since mutation is a derived equivalence, $T_I \otimes_{\Gamma}^{\mathbf{L}} y \cong x$, so $\operatorname{Tor}_1^{\Gamma}(T_I, y) = 0$. Thus applying $T_I \otimes_{\Gamma} -$ to the above sequence and using 2.20 gives an exact sequence

$$0 \to \operatorname{Tor}_{1}^{\Gamma}(T_{I}, y') \to 0 \to \operatorname{Tor}_{1}^{\Gamma}(T_{I}, c) \to T_{I} \otimes_{\Gamma} y' \to T_{I} \otimes_{\Gamma} y \to T_{I} \otimes_{\Gamma} c \to 0$$
(5.D)

of Λ -modules. Now $e_j \operatorname{Tor}_1^{\Gamma}(T_I, c) = \operatorname{Tor}_1^{\Gamma}(e_j T_I, c) = 0$ for all $j \notin I$, since $e_j T_I = e_j \operatorname{Hom}_{\Lambda}(\Lambda, T_I) \cong \operatorname{Hom}_{\Lambda}(P_j, T_I)$ is a projective $\Gamma^{\operatorname{op}}$ -module if $j \notin I$. Consequently

$$(\underline{\dim}\operatorname{Tor}_{1}^{\Gamma}(T_{I},c))_{j} = \begin{cases} 0 & \text{if } j \notin I\\ n_{j} & \text{if } j \in I \end{cases}$$

for some collection $n_j \in \mathbb{Z}_{\geq 0}$. Splicing (5.D) gives an exact sequence

$$0 \to \operatorname{Tor}_{1}^{\Gamma}(T_{I}, c) \to T_{I} \otimes_{\Gamma} y' \to a \to 0$$
(5.E)

where a is a submodule of $T_I \otimes_{\Gamma} y \cong x$, so $\vartheta \cdot \underline{\dim} a \ge 0$ since x is ϑ -semistable. Thus applying ϑ to (5.E) we obtain

$$\vartheta \cdot \underline{\dim}(T_I \otimes_{\Gamma} y') = \vartheta \cdot \underline{\dim} a + \vartheta \cdot \underline{\dim} \operatorname{Tor}_1^{\Gamma}(T_I, c) = \vartheta \cdot \underline{\dim} a + \sum_{i \in I} \vartheta_i n_i \ge 0.$$
(5.F)

It follows that

$$\nu_{\mathbf{b}_{\mathbf{I}}}\vartheta \cdot \underline{\dim} y' = \vartheta \cdot \nu_{\mathbf{b}_{\mathbf{I}}} \underline{\dim} y' \qquad (by \ 5.6(3))$$
$$= \vartheta \cdot \underline{\dim}(T_{I} \otimes_{\Gamma} y') \qquad (by \ (5.D) \ and \ 5.7(2))$$
$$\geq 0, \qquad (by \ (5.F))$$

and so y is $v_{\mathbf{b}_{\mathbf{I}}}\vartheta$ -semistable, proving the claim.

(2) This is similar to (1), but we give the proof for completeness. By 5.10(2) and 5.11(2), $T_I \otimes_{\Gamma} -$ is exact out of $S_{\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$. To see that $T_I \otimes_{\Gamma} -$ maps $S_{\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$ to $S_{\vartheta}(\Lambda)$, let $y \in S_{\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$ and consider $x := T_I \otimes_{\Gamma} y \cong T_I \otimes_{\Gamma} y$ where the last isomorphism holds by 2.20 and Tor₁ vanishing. Consider a Λ -submodule $x' \subseteq x$, then this induces an exact sequence

$$0 \to x' \to x \to d \to 0.$$

Since $\vartheta \cdot \underline{\dim} x = \vartheta \cdot \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim} y = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} y = 0$ by 5.7(2) and 5.6(3), it suffices to show that $\vartheta \cdot \underline{\dim} x' \ge 0$, or equivalently $\vartheta \cdot \underline{\dim} d \le 0$.

The above exact sequence induces an exact sequence

$$0 \to \operatorname{Hom}_{\Lambda}(T_{I}, x') \to y \to \operatorname{Hom}_{\Lambda}(T_{I}, d) \to \operatorname{Ext}^{1}_{\Lambda}(T_{I}, x') \to 0 \to \operatorname{Ext}^{1}_{\Lambda}(T_{I}, d) \to 0, \quad (5.G)$$

again using 2.20. Splicing this sequence gives an exact sequence

$$0 \to b \to \operatorname{Hom}_{\Lambda}(T_I, d) \to \operatorname{Ext}^1_{\Lambda}(T_I, x') \to 0$$
 (5.H)

where $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} b \leq 0$ since b is a factor of the $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta$ -stable module y. But now $e_j \operatorname{Ext}^1_{\Lambda}(T_I, x') = \operatorname{Ext}^1_{\Lambda}(P_j, x') = 0$ for all $j \notin I$, so

$$(\underline{\dim}\operatorname{Ext}^{1}_{\Lambda}(T_{I}, x'))_{j} = \begin{cases} 0 & \text{if } j \notin I \\ m_{j} & \text{if } j \in I \end{cases}$$

for some collection $m_i \in \mathbb{Z}_{>0}$. Hence

$$\vartheta \cdot \underline{\dim} d = \vartheta \cdot \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim} \operatorname{Hom}_{\Lambda}(T_{I}, d) \qquad (by \ (5.G) \ and \ 5.7(1)) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} \operatorname{Hom}_{\Lambda}(T_{I}, d) \qquad (by \ 5.6(3)) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} \ b + \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} \operatorname{Ext}_{\Lambda}^{1}(T_{I}, x') \qquad (by \ (5.H)) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta \cdot \underline{\dim} \ b + \sum_{i \in I} (\mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \vartheta)_{i} m_{i},$$

which is less than or equal to zero.

(3) If $x \in \mathcal{S}_{\beta,\vartheta}(\Lambda)$ then by 5.10(1) and 5.11(1) $\operatorname{Ext}^{1}_{\Lambda}(T_{I}, x) = 0$. Thus $\operatorname{\underline{dim}} \operatorname{Hom}_{\Lambda}(T_{I}, x) =$ $\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\beta$ by 5.7(1). Similarly if $y \in \mathcal{S}_{\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\beta,\mathbf{v}_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$ then by 5.10(2) and and 5.11(2) $\operatorname{Tor}_{1}^{\Gamma}(T_{I}, y) =$ 0 and so $\underline{\dim}(T_I \otimes_{\Gamma} y) = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \underline{\dim} y = \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \mathbf{v}_{\mathbf{b}_{\mathbf{I}}} \beta = \beta$ by 5.7(2) and 5.6(2). Thus the functors in (5.C) are well defined, and further since T_I has projective dimension one (on both sides) by 2.20, they are isomorphic to their derived versions. Since the derived versions are an equivalence, we deduce the underived versions are. They are exact by (1) and (2), so it follows that they preserve the S-equivalence classes. It is also clear in the above proof that replacing > 0 by > 0 throughout shows that under the equivalence, stable modules correspond to stable modules.

(4) Follows immediately from (3).

Leading up to the next corollary, recall that $\mathbf{b}_{\mathbf{I}}$ is defined in (5.A) by decomposing first $U_I = \bigoplus_{i \in I} U_i$, then further decomposing each U_i . We may play the same trick to the V_I 's, namely for each indecomposable summand M_i of M_I consider its minimal right add M_{I^c} -approximation

$$\bigoplus_{j \notin I} M_j^{\oplus c_{i,j}} \to M_i$$

for some collection $c_{i,j} \in \mathbb{Z}_{\geq 0}$. These give $\mathbf{c}_{\mathbf{I}} := (c_{i,j})_{i \in I, j \notin I}$. In general, $\mathbf{b}_{\mathbf{I}} \neq \mathbf{c}_{\mathbf{I}}$.

Corollary 5.13. With notation and assumptions as in 5.12, for every dimension vector β , and for every $\vartheta \in \Theta$ with $\vartheta_i > 0$ for all $i \in I$,

- (1) There is an isomorphism $\mathcal{M}_{\beta,\vartheta}(\Lambda) \cong \mathcal{M}_{\nu_{\mathbf{b}_{\mathbf{I}}}\beta,\nu_{\mathbf{b}_{\mathbf{I}}}\vartheta}(\Gamma)$. (2) There is an isomorphism $\mathcal{M}_{\nu_{\mathbf{c}_{\mathbf{I}}}\beta,\nu_{\mathbf{c}_{\mathbf{I}}}\vartheta}(\Lambda) \cong \mathcal{M}_{\beta,\vartheta}(\Gamma)$.

Proof. (1) It follows immediately from 5.12(3) that there is a bijection on closed points. The fact that 5.12(3) holds after base change, and so there is an isomorphism of schemes, is dealt with in [SY, 4.20], noting the small correction in [Kar, Appendix A].

(2) By A.6 either the assumption (a) or (b) holds for $v_I M$. Hence we can apply 5.12(3) to the mutation $\Gamma \mapsto \nu_I \Gamma \cong \Lambda$. For this mutation, the b's are given by $\mathbf{c}_{\mathbf{I}}$, using (A.K) (and the fact that $W_I \cong V_I$ there).

Recall from the introduction $\S1.3$ the definition of the dimension vector rk.

Corollary 5.14. With the notation and assumptions as in 5.13, suppose further that $\mathbf{b_I} = \mathbf{c_I}$ (equivalently, $U_i \cong V_i$ for all $i \in I$). Then for every dimension vector $\boldsymbol{\beta}$, and for every $\vartheta \in \Theta$ with $\vartheta_i \neq 0$ for all $i \in I$, there is an isomorphism

$$\mathcal{M}_{\beta,\vartheta}(\Lambda) \cong \mathcal{M}_{\mathbf{v}_{\mathbf{b}_{\mathbf{f}}}\beta,\mathbf{v}_{\mathbf{b}_{\mathbf{f}}}\vartheta}(\Gamma).$$

In particular, if $\mathbf{b}_{\mathbf{I}} = \mathbf{c}_{\mathbf{I}}$, then $\mathcal{M}_{\mathsf{rk},\vartheta}(\Lambda) \cong \mathcal{M}_{\mathsf{rk},\mathsf{v}_{\mathbf{b}_{\mathbf{r}}}\vartheta}(\Gamma)$ for every $\vartheta \in \Theta$ with $\vartheta_i \neq 0$ for all $i \in I$.

Remark 5.15. We will prove later in 5.22 that $U_i \cong V_i$ for all $i \in I$ in the case of cDV singularities, so $\mathbf{b}_{\mathbf{I}} = \mathbf{c}_{\mathbf{I}}$ in this case. However, even for NCCRs in dimension three with $I = \{i\}, \mathbf{b}_{\mathbf{I}} \neq \mathbf{c}_{\mathbf{I}}$ in general.

5.3. Chamber Structure: Reduction to Surfaces. In this subsection we revert back to the crepant one dimensional fibre setting of 2.9. Throughout, we restrict to the dimension vector rk, and show that (for this dimension vector) the chamber structure on the stability parameters can be calculated by passing to a Kleinian singularity.

Remark 5.16. As the moduli space $\mathcal{M}_{\mathsf{rk},\vartheta}(\Lambda)$ parameterises only semistable Λ -modules of dimension vector rk , and such modules x necessarily satisfy $\vartheta \cdot \mathsf{rk} = \vartheta \cdot \underline{\dim x} = 0$ by definition of semistability, henceforth we are only concerned with those stability parameters for which $\vartheta \cdot \mathsf{rk} = 0$. This subspace of Θ , which we will temporarily denote by Θ_{rk} , has a wall and chamber structure. The non-generic parameters cut out walls, dividing the generic parameters of Θ_{rk} into chambers.

Recall in the general setup of 2.8 that $\Lambda = \operatorname{End}_X(\mathcal{V}_X)$, where \mathcal{V}_X has a summand \mathcal{O}_X , which has rank one. Write \star (or sometimes 0) for the vertex in Λ corresponding to \mathcal{O}_X , and consider the dimension vector rk. Since by definition all elements $\vartheta \in \Theta_{\mathsf{rk}}$ satisfy $\vartheta \cdot \mathsf{rk} = 0$, it follows that

$$\vartheta_{\star} = -\sum_{i \in Q_0 \setminus \star} (\operatorname{rank} \mathcal{N}_i) \vartheta_i$$

and so $\Theta_{\rm rk}$ can be viewed as $\mathbb{Q}^{|Q_0|-1}$, with co-ordinates ϑ_i for $i \neq 0$. Later, this means that to calculate the wall and chamber structure in $\Theta_{\rm rk}$, we do not need to mutate at the summand R.

Each Λ in the general setup of 2.8 has an associated Θ_{rk} , and as the chamber structure of Θ_{rk} depends on Λ , later care will be required. When it is necessary to emphasise which ring is being considered, we will use the notation $\Theta_{rk}(\Lambda)$.

Notation 5.17. Henceforth, until the end of the paper, we will write Θ_{rk} as simply Θ , and $\Theta_{\mathsf{rk}}(\Lambda)$ as simply $\Theta(\Lambda)$, with it being implicit that everywhere walls and chambers are discussed, this involves only working with those stability parameters ϑ such that $\vartheta \cdot \mathsf{rk} = 0$. This is an abuse of notation, but it is required to maintain readability later.

Lemma 5.18. In the general setup of 2.8, consider $\Lambda := \operatorname{End}_X(\mathcal{V}_X)$, with dimension vector rk. As above, consider Θ with co-ordinates ϑ_i for $i \neq 0$. Then

$$C_{+} := \{ (\vartheta_{i}) \in \Theta \mid \vartheta_{i} > 0 \text{ for all } i \}$$

is a chamber in Θ .

Proof. It is clear that every element of C_+ is generic, and further if $\vartheta, \vartheta' \in C_+$, then x is ϑ -stable if and only if it is ϑ' -stable. Hence C_+ is contained in some GIT chamber. It suffices to show that for each i, there exists some $x_i \in \mathcal{M}_{\mathsf{rk},C_+}(\Lambda)$ and an injection $S_i \hookrightarrow x_i$, since this implies that x_i is not stable in the limit $\vartheta_i \to 0$ and so $\vartheta_i = 0$ then defines a wall.

Consider the curve C_i and pick a point $y \in C_i$. There is a short exact sequence

$$0 \to \mathcal{O}_{C_i}(-1) \to \mathcal{O}_{C_i} \to \mathcal{O}_u \to 0$$

and thus after tensoring by \mathcal{L}_i^* and rotating gives a triangle

$$\mathcal{O}_{C_i}(-1) \to \mathcal{O}_y \to \mathcal{O}_{C_i}(-2)[1] \to$$

in $D^{b}(\operatorname{coh} X)$. Applying $\mathbf{R}\operatorname{Hom}_{X}(\mathcal{V}_{X}, -)$, using 2.11 gives a triangle

$$S_i \to x_i \to C \to C$$

in $D^{b}(\text{mod} \operatorname{End}_{X}(\mathcal{V}_{X}))$, where x_{i} is a C_{+} -stable module of dimension vector rk by [Kar, §5.2]. The first morphism is non-zero, and so since $S_{i} = \mathbb{C}$ it is necessarily injective. \Box

The strategy to describe the chambers of $\Theta(\Lambda)$ is to track C_+ through mutation, and calculate the combinatorics by passing to surfaces. This requires a special case of the following general result.

Proposition 5.19. Let R be a complete local 3-sCY normal domain, suppose that M is modifying, and M_I is a summand of M with $R \in \text{add } M_{I^c}$. Consider the exchange sequence (2.C)

$$0 \to K_i \xrightarrow{c_i} V_i \xrightarrow{a_i} M_i$$

Then a_i is surjective. Further, for any $x \in \mathfrak{m}$ which is an $\operatorname{Ext}^1_R(M, M)$ -regular element, denoting $F := (R/xR) \otimes_R -$, then

- (1) $(R/xR) \otimes_R \operatorname{End}_R(M) \cong \operatorname{End}_{FR}(FM)$, and FM is indecomposable.
- (2) If further x is $\operatorname{Ext}_{R}^{1}(K_{i}, K_{i})$ -regular, the sequence

$$0 \to FK_i \to FV_i \xrightarrow{Fa_i} FM_i \to 0 \tag{5.1}$$

is exact, and further Fa_i is a minimal add FM_{I^c} -approximation.

Proof. (1) The first statement is well-known; see for example the argument in [IW4, 5.24], which uses the fact that x is $\operatorname{Ext}_{R}^{1}(M, M)$ -regular. The second follows from the first, since if FM decomposes, since R is complete local we can lift idempotents to obtain a contradiction.

(2) Since M_{I^c} is a generator and $\operatorname{Hom}_R(M_{I^c}, -)$ applied to (2.E) is exact, it follows that a_i is surjective. Also, since M_{I^c} is a generator and $\operatorname{End}_R(M) \in \operatorname{CM} R$, necessarily $M \in \operatorname{CM} R$ and since CM modules are closed under kernels of epimorphisms, $K_I \in \operatorname{CM} R$.

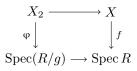
Now since $x \in \mathfrak{m}$ and CM modules are submodules of free modules, x is not a zero divisor on any of the modules in (2.E), thus

$$\begin{array}{cccc} 0 \longrightarrow K_i \longrightarrow V_i \longrightarrow M_i \longrightarrow 0 \\ & x & \uparrow & x & \uparrow \\ 0 \longrightarrow K_i \longrightarrow V_i \longrightarrow M_i \longrightarrow 0 \end{array}$$

and so by the snake lemma (5.I) is exact. Now since a_i is an add M_{I^c} -approximation, there is a commutative diagram

where the bottom two vertical maps are isomorphisms by (1). It follows that the bottom horizontal map is surjective, so Fa_i is indeed an add FM_{I^c} -approximation. For minimality, by (1) applied to K_i , $\operatorname{End}_R(K_i)/x \operatorname{End}_R(K_i) \cong \operatorname{End}_{FR}(FK_i)$. Thus if Fa_i were not minimal then FK_i would decompose into more summands than K_i , which since $\operatorname{End}_R(K_i)/x \operatorname{End}_R(K_i) \cong \operatorname{End}_{FR}(FK_i)$ is impossible since R is complete local so we can lift idempotents.

In the crepant setup of 2.9 with d = 3, by Reid's general elephant principle [Re, 1.1, 1.14], cutting by a generic hyperplane section yields



where R/g is an ADE singularity and φ is a partial crepant resolution. Since $N \in CMR$ and g is not a zero-divisor on N, necessarily $N/gN \in CMR/g$, and so any indecomposable summand N_i of N cuts to N_i/gN_i , which must correspond to a vertex in an ADE Dynkin diagram via the original Auslander–McKay correspondence.

Following the notation from [K], we encode X_2 pictorially by simply describing which curves are blown down from the minimal resolution. The diagrams



represent, respectively, the minimal resolution of the D_5 surface singularity, and the partial resolution obtained from it by contracting the curves corresponding to the black vertices.

Corollary 5.20. With the crepant setup 2.9 with d = 3, if g is a sufficiently generic hyperplane section, then

- (1) $\Lambda/g\Lambda \cong \operatorname{End}_{R/qR}(N/gN).$
- (2) Let N_I be a summand as in 2.13, and consider the exchange sequences

$$0 \to K_i \xrightarrow{c_i} V_i \xrightarrow{d_i} N_i$$
$$0 \to J_i \xrightarrow{d_i} U_i^* \xrightarrow{b_i} N_i^*$$

Then a_i and b_i are surjective, and

$$0 \to FK_i \xrightarrow{Fc_i} FV_i \xrightarrow{Fa_i} FN_i \to 0$$
$$0 \to FJ_i \xrightarrow{Fd_i} FU_i^* \xrightarrow{Fb_i} FN_i^* \to 0$$

are exact, with Fa_i and Fb_i being minimal right approximations.

(3) We have that $0 \to J_i \xrightarrow{d_i} U_i^* \xrightarrow{b_i} N_i^* \to 0$ is exact, inducing an exact sequence

$$0 \to FN_i \xrightarrow{F(b_i^*)} FU_i \xrightarrow{F(d_i^*)} FJ_i^* \to 0$$

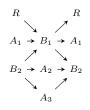
where $F(b_i^*)$ is a minimal left add FM_{I^c} -approximation.

Proof. (1)(2) Since $\operatorname{End}_R(N) \in \operatorname{CM} R$, depth $\operatorname{Ext}^1_R(N,N) > 0$ and so if an element g acts on $E_N := \operatorname{Ext}^1_R(N,N)$ as a zero divisor, then it is contained in one of the finitely many associated primes of E_N , which are all non-maximal. We can apply the same logic to both K_I and J_I^* , and thus the finite number of associated primes of $E_N \oplus E_{K_I} \oplus E_{J_I^*}$ are non-maximal. Hence we can find g sufficiently generic to be $E_N \oplus E_{K_I} \oplus E_{J_I^*}$ -regular, so the first two parts follow from 5.19.

(3) This is just the dual of (2), and follows by A.1, part (2) and isomorphisms such as $\operatorname{Hom}_{FR}(FN_i^*, FR) \cong F\operatorname{Hom}_R(N_i^*, R) \cong FN_i$.

The proof of the next lemma, 5.22, requires a little knowledge regarding knitting on AR quivers, which we briefly review in an example. We refer the reader to [IW1, §4] for full details.

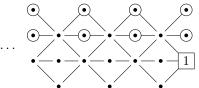
Example 5.21. Consider the D_5 ADE surface singularity R. The AR quiver, which coincides with the McKay quiver [A86], is



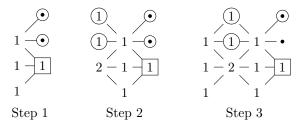
where the left and right hand sides are identified. In this example, suppose that $N := R \oplus A_1 \oplus B_2$ and $N_I := B_2$ (so that $N_{I^c} := R \oplus A_1$). We calculate the minimal add N_{I^c} -approximation of N_I .

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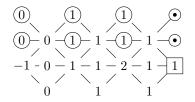
Consider the cover of the AR quiver, since this is easiest to draw, and drop labels and the directions of arrows. The calculation begins by placing a 1 in the position of B_2 (boxed below), and circling all the vertices corresponding to indecomposable summands of N_{I^c}



The calculation continues by counting backwards, using the usual knitting rule that for any given AR sequence, the left-hand value is the sum of the middle values, minus the right-hand value. Doing this, we obtain



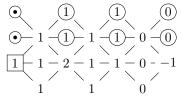
where in Step 3 the values in the circled vertices act like zero. Continuing, the process stops when the value -1 appears



Summing up the values on the circled vertices gives $R^{\oplus 2} \oplus A_1^{\oplus 2}$, and the vertex with -1 corresponds to B_2 . From this, we read off that

$$0 \to B_2 \to R^{\oplus 2} \oplus A_1^{\oplus 2} \to B_2 \to 0$$

is an exact sequence, with the first map a minimal right add N_{Ic} -approximation. The calculation for the minimal left approximation is similar, by placing a 1 and counting forwards to give



This also gives the exact sequence $0 \to B_2 \to R^{\oplus 2} \oplus A_1^{\oplus 2} \to B_2 \to 0$. Observe that the second calculation can be obtained from the first simply by reflecting in the vertical line through the boxed vertex.

The following is an extension of the above observation.

Lemma 5.22. With the crepant setup 2.9, consider the modifying R-module $N := H^0(\mathcal{V}_X)$ and choose a summand N_I as in 2.13. With the notation in 5.20,

(1)
$$FU_i \cong FV_i$$

(2) $U_i \cong V_i$.

Proof. As in 5.20, let g be a sufficiently generic hyperplane section and let $F := (R/gR) \otimes_R$ (-). As before, decompose $U_i \cong \bigoplus_{j \notin I} N_j^{\oplus b_{i,j}}$ and $V_i \cong \bigoplus_{j \notin I} N_j^{\oplus c_{i,j}}$, from which it is clear that $FU_i \cong \bigoplus_{j \notin I} (FN_j)^{\oplus b_{i,j}}$ and $FV_i \cong \bigoplus_{j \notin I} (FN_j)^{\oplus c_{i,j}}$. By 5.19(1) the FN_j are indecomposable, so by Krull–Schmidt to prove both parts it suffices to show that $b_{i,j} = c_{i,j}$ for all $i \in I, j \notin I$.

Both FU_i and FV_i can be calculated by knitting on the AR quiver of the ADE singularity FR. As in 5.21, the calculation for FU_i begins by placing a 1 in the place of FN_i , and proceeds by counting to the left, using the usual knitting rules, and records the numbers in the circles whilst treating them as zero for the next step. At the end of the calculation, we read off the $b_{i,j}$ by adding the numbers in the circled vertices.

On the other hand, the calculation for FV_i begins by placing a 1 in the place of FN_i , then proceeds by counting to the right. In exactly the same way, we read off the $c_{i,j}$ by adding the numbers in the circled vertices. Since the AR quiver of ADE surface singularities coincides with the McKay quiver [A86], which is symmetric, we can obtain one calculation from the other by reflecting in the line through the original boxed vertex. Thus both calculations return the same numbers, so $c_{i,j} = b_{i,j}$ for all $i \in I$ and $j \notin I$. \Box

Corollary 5.23. With the d = 3 crepant setup $f: X \to \operatorname{Spec} R$ of 2.9, set $N := H^0(\mathcal{V}_X)$ and $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$. Suppose further that either

(A) $f: X \to \operatorname{Spec} R$ is a minimal model, or

(B) $f: X \to \operatorname{Spec} R$ is a flopping contraction.

Then, for any i, the region

$$\vartheta_i < 0, \quad \vartheta_i + b_i \vartheta_i > 0 \text{ for all } j \neq i$$

defines a chamber in $\Theta(\Lambda)$, and for any parameter ϑ inside this chamber,

$$\mathcal{M}_{\mathsf{rk},\vartheta}(\Lambda) \cong \begin{cases} X_i^+ & \text{if } C_i \text{ flop} \\ X & \text{else,} \end{cases}$$

where X_i^+ denotes the flop of X at C_i . Thus the flop of C_i , if it exists, is obtained by crashing through the single wall $\vartheta_i = 0$ in $\Theta(\Lambda)$.

Proof. Pick a curve C_i (i.e. consider $I = \{i\}$), and mutate at the indecomposable summand N_i of N. By 5.18, $\vartheta_i = 0$ is a wall. Since we are mutating only at indecomposable summands, in situation (A) 2.23 shows that the assumptions of 5.12 are satisfied. In situation (B), 2.25 together with 3.5 shows that the assumptions of 5.12 are satisfied. Thus, in either case, since $U_i \cong V_i$ by 5.22, provided that $\vartheta_i \neq 0$ it is possible to track moduli using 5.14.

In either (A) or (B), if $\dim_{\mathbb{C}} \Lambda_i < \infty$ then C_i flops, in which case $\nu_i N \cong H^0(\mathcal{V}_{X_i^+})$ by 4.20. Thus $\mathcal{M}_{\mathsf{rk},\Phi}(\nu_i\Lambda) \cong X_i^+$ for all $\phi \in C_+(\nu_i\Lambda)$ by 4.19(2), so the result then follows by moduli tracking 5.14. The only remaining case is when $\dim_{\mathbb{C}} \Lambda_i = \infty$ in situation (A), but then $\nu_i N \cong N$ by 2.23 and so the result is obvious.

The main result of this subsection needs the following result, which may be of independent interest. The case when Y is the minimal resolution is well known [CS, Kr].

Theorem 5.24. Consider an ADE singularity Spec R, let Λ be the corresponding NCCR, and let $Y \to \text{Spec } R$ be a partial crepant resolution. Set $N := H^0(\mathcal{V}_Y)$ and $\Gamma := \text{End}_R(N)$. Suppose that the minimal resolution $X \to \text{Spec } R$ has curves C_1, \ldots, C_n , and after reindexing if necessary Y is obtained from X by contracting the curves C_{r+1}, \ldots, C_n . Then

- (1) The walls of $\Theta(\Gamma)$ are obtained by intersecting the subspace L of $\Theta(\Lambda)$ spanned by $\vartheta_1, \ldots, \vartheta_r$ with the walls of $\Theta(\Lambda)$ that do not contain L.
- (2) $\Theta(\Gamma)$ has a finite number of chambers, and the walls are given by a finite collection of hyperplanes containing the origin. The co-ordinate hyperplanes $\vartheta_i = 0$ are included in this collection.

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(3) Considering iterated mutations at indecomposable summands, tracking the chamber C_+ on $\mathbf{v}_{i_1} \dots \mathbf{v}_{i_t}(\Gamma)$ back to $\Theta(\Gamma)$ gives all the chambers of $\Theta(\Gamma)$.

Proof. With the ordering of the curves as in the statement, we first contract C_n , then C_{n-1} , and continue to obtain a chain of crepant morphisms

$$X \xrightarrow{f_1} X_{n-1} \xrightarrow{f_2} \ldots \to Y.$$

The intersection in (1) can be calculated inductively, so we first establish the result is true for $\Lambda_{n-1} := \operatorname{End}_{X_{n-1}}(\mathcal{V}_{X_{n-1}}) \cong (1-e_n)\Lambda(1-e_n).$

As notation, $\Theta(\Lambda)$ has coordinates $\vartheta_1, \ldots, \vartheta_n$, and we let S be the subspace spanned by $\vartheta_1, \ldots, \vartheta_{n-1}$. By abuse of notation, we let $\vartheta_1, \ldots, \vartheta_{n-1}$ also denote the coordinates of $\Theta(\Lambda_{n-1})$, so that we identify $\Theta(\Lambda_{n-1})$ with S. We let W_S be the set of walls of $\Theta(\Lambda)$ not containing S, then the intersection $S \cap W_S$ partitions S into a finite number of regions. We claim that these are precisely the chambers of $\Theta(\Lambda_{n-1})$.

First, since by 5.18 $\{\vartheta \in \Theta(\Lambda) \mid \vartheta_i > 0 \text{ for all } 1 \leq i \leq n\}$ is a chamber of $\Theta(\Lambda)$, certainly no walls of $\Theta(\Lambda)$ intersect $\{\vartheta \in S \mid \vartheta_i > 0 \text{ for all } 1 \leq i \leq n-1\}$. Thus we may identify this region of $S \setminus (S \cap W_S)$ with C_+ in $\Theta(\Lambda_{n-1})$.

Next, on Λ we mutate the summand $N_1 \oplus N_n$. By 5.14, tracking C_+ from $\nu_{\{1,n\}}\Lambda$ to Λ using the formula in 5.4 gives the chamber

$$\vartheta_1 < 0, \quad \vartheta_n < 0, \quad \vartheta_i + b_i \vartheta_1 + a_i \vartheta_n > 0 \text{ for all } i \notin \{1, n\}$$
(5.J)

of $\Theta(\Lambda)$, where the b_i are obtained from an $\operatorname{add}(R \oplus N_2 \oplus \ldots \oplus N_{n-1})$ -approximation of N_1 , and the a_i are obtained from an $\operatorname{add}(R \oplus N_2 \oplus \ldots \oplus N_{n-1})$ -approximation of N_n . On the other hand, using the approximation of N_1 above, by 5.14 tracking C_+ from $\nu_1 \Lambda_{n-1}$ to Λ_{n-1} using the formula in 5.4 gives the chamber

$$\vartheta_1 < 0, \quad \vartheta_i + b_i \vartheta_1 > 0 \text{ for all } i \neq 1$$

$$(5.K)$$

of $\Theta(\Lambda_{n-1})$. We already know the $\vartheta_1 = 0$ edge of (5.K) is a wall, and since the other edge walls of C_+ on $\nu_1 \Lambda_{n-1}$ can also be tracked by 5.12(4) to give strictly semi-stable points, the walls bounding (5.K) are precisely the intersection of the walls bounding (5.J) with S (just set $\vartheta_n = 0$). Since we know that the walls of $\Theta(\Lambda)$ are a hyperplane arrangement of planes through the origin [CS, Kr], this implies that the walls of the chamber (5.K) of $\Theta(\Lambda_{n-1})$ are given by intersecting S with all members of W_S . There is nothing special about ϑ_1 , so by symmetry all the walls of all the chambers bordering C_+ in $\Theta(\Lambda_{n-1})$ are given by intersecting S with the elements of W_S .

The proof then proceeds by induction. By applying the argument above, tracking C_+ from $v_{\{2,n\}}v_{\{1,n\}}\Lambda$ to $v_{\{1,n\}}\Lambda$, implies that tracking C_+ from $v_2v_1\Lambda_{n-1}$ to $v_1\Lambda_{n-1}$ gives a chamber in $\Theta(v_1\Lambda_{n-1})$, adjacent to C_+ , cut out by intersecting walls from $\Theta(\Lambda)$. In particular, the plane $x_1 = 0$ does not cut through this chamber, so by 5.14 we can track the full chamber all the way back to $\Theta(\Lambda_{n-1})$ to obtain a chamber adjacent to (5.K). Again, the same argument shows that its walls are given by intersecting S with the elements of W_S . By symmetry, all the walls of all the chambers bordering all the chambers that border C_+ in $\Theta(\Lambda_{n-1})$ are given by intersecting S with the elements of W_S .

Since $\Theta(\Lambda)$ has finitely many walls [CS, Kr], so does $S \cap W_S$, so continuing the above process all the walls of $\Theta(\Lambda_{n-1})$ are given by intersecting S with the elements of W_S , and each region is the tracking of C_+ under iterated mutation. This proves (1), (2) and (3) for X_{n-1} .

Next, consider $f_2: X_{n-1} \to X_{n-2}$. Since by above $\Theta(\Lambda_{n-1})$, and all other Λ'_{n-1} obtained from X by contracting only a single curve, have walls given by a finite collection of hyperplanes passing through the origin, the above argument can be repeated to $\Lambda_{n-2} \cong (1 - e_{n-1})\Lambda_{n-1}(1 - e_{n-1})$ to show that $\Theta(\Lambda_{n-2})$ can be obtained from $\Theta(\Lambda_{n-1})$ by intersecting (and thus from $\Theta(\Lambda)$ by intersecting), and each region is the tracking of C_+ under iterated mutation. By induction, parts (1), (2) and (3) follow.

The following is the main result of this subsection.

Corollary 5.25. With the d = 3 crepant setup $f: X \to \operatorname{Spec} R$ of 2.9, set $N := H^0(\mathcal{V}_X)$ and $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$. Suppose further that either

- (A) $f: X \to \operatorname{Spec} R$ is a minimal model, or
- (B) $f: X \to \operatorname{Spec} R$ is a flopping contraction.

Then for sufficiently generic g,

- (1) The chamber structure of $\Theta(\Lambda)$ is the same as the chamber structure of $\Theta(\Lambda/g\Lambda)$.
- (2) $\Theta(\Lambda)$ has a finite number of chambers, and the walls are given by a finite collection of hyperplanes containing the origin. The co-ordinate hyperplanes $\vartheta_i = 0$ are included in this collection.
- (3) Considering iterated mutations at indecomposable summands, tracking the chamber C_+ on $\nu_{i_1} \dots \nu_{i_t} \Lambda$ back to $\Theta(\Lambda)$ gives all the chambers of $\Theta(\Lambda)$.

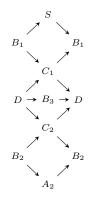
Proof. By 5.20 the combinatorics of tracking C_+ are the same for the surface R/gR as they are for the 3-fold R, so all parts follow immediately from 5.24.

5.4. Surfaces Chamber Structure via AR theory. Having in 5.24 and 5.25 reduced the problem to tracking the chamber C_+ under iterated mutation for partial crepant resolutions of Kleinian singularities, in this subsection we illustrate the combinatorics in two examples, summarising others in §7.1, and give some applications.

The intersection in 5.24(1) is in practice very cumbersome to calculate, since the full root systems are very large and contain much redundant information. In addition to giving an easy, direct way of calculating the chamber structure, the benefit of working with mutation is that we also obtain, in 5.28, a lower bound for the number of minimal models on the 3-fold.

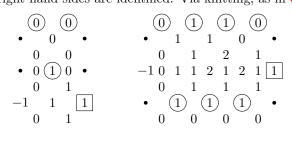
Example 5.26. Let S be the E_7 surface singularity, and consider the partial resolution $Y \to \operatorname{Spec} S$ depicted by

where the vertices have been labelled by their corresponding CM S-modules. We calculate the chamber structure of $\operatorname{End}_S(S \oplus B_2 \oplus D)$. The AR quiver for CM S is



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where the left and right hand sides are identified. Via knitting, as in 5.21,

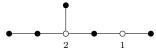


we obtain the exchange sequences

$$0 \to B_2 \to D \to B_2 \to 0 \tag{5.M}$$

$$0 \to D \to R^{\oplus 2} \oplus B_2^{\oplus 3} \to D \to 0 \tag{5.N}$$

Thus in this example, the dual graph does not change under mutation. Now fix the ordering of the curves



First, we track the C_+ chamber from $\nu_1 \Lambda$ to Λ . By 5.14,

$$\begin{array}{ccc} \varphi_1 & (\underline{\mathbf{5.M}}) & -\varphi_1 \\ \varphi_2 & \varphi_1 + \varphi \end{array}$$

and so the C_+ chamber from $\nu_1 \Lambda$ maps to the region $\vartheta_1 < 0$ and $\vartheta_1 + \vartheta_2 > 0$ of Λ , and thus this is a chamber for Λ . Next, we track the C_+ chamber from $\nu_2 \nu_1 \Lambda$ to $\nu_1 \Lambda$ to Λ . By the same logic

$$\begin{array}{cccc} \varphi_1 & (\underline{5.N}) & \varphi_1 + 3\varphi_2 & (\underline{5.M}) \\ \varphi_2 & -\varphi_2 & & -\varphi_2 + (\varphi_1 + 3\varphi_2) \\ \end{array} = \begin{array}{ccc} -\varphi_1 - 3\varphi_2 \\ \varphi_1 + 2\varphi_2 \end{array}$$

which is precisely the region $\vartheta_1 + \vartheta_2 < 0$ and $2\vartheta_1 + 3\vartheta_2 > 0$ of Λ , and so this too is a chamber. Continuing in this fashion, we obtain the chamber structure illustrated in Figure 3, where there are 12 chambers in total.

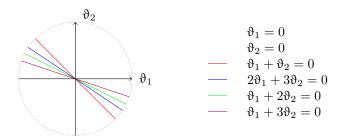


FIGURE 3. Chamber structure for E_7 with configuration (5.L).

However, often the dual graph does change under mutation.

Example 5.27. Let S be the D_4 surface singularity, and consider the partial resolution depicted by

Via knitting, to mutate at A_3 the relevant exchange sequence is

$$0 \to M \to R \oplus A_1 \oplus A_2 \to A_3 \to 0 \tag{5.P}$$

Hence $\nu_3 \Lambda = \operatorname{End}_R(R \oplus A_1 \oplus A_2 \oplus M)$, and this corresponds to the partial resolution

Hence under mutation, the dual graph changes from (5.0) to (5.Q). Tracking the chamber C_+ from $\nu_3 \Lambda$ to Λ , by 5.14

$$\begin{array}{ccc} \varphi_1 & \phi_1 + \phi_3 \\ \varphi_2 & \mapsto & \phi_2 + \phi_3 \\ \varphi_3 & & -\phi_3 \end{array}$$

which is the region $\vartheta_3 < 0$, $\vartheta_1 + \vartheta_3 > 0$, $\vartheta_2 + \vartheta_3 > 0$. Hence this is a chamber for Λ , and it corresponds to a difference curve configuration. Note that since $\nu_3 N \not\cong N$ on the surface, by combining 4.6 and 5.20 any cDV singularity with minimal model that cuts under generic hyperplane section to (5.0) must flop when crossing the wall $\vartheta_3 = 0$. By symmetry, it must also flop when crossing the walls $\vartheta_1 = 0$ and $\vartheta_2 = 0$. This shows that any such 3-fold must have at least four minimal models, since we can flop three different curves. In this example, the full chamber structure coincides (after a change in parameters) with the chamber structure in Figure 6, so there are 32 chambers in total.

The following is an extension of the above observation. In each chamber of $\Theta(\Lambda/g\Lambda)$, we draw the curve configuration appearing on the surface mutation calculation, as calculated in the above example. We refer to this as the *enhanced chamber structure* of $\Theta(\Lambda/g\Lambda)$. See 7.3 for an example.

Lemma 5.28. Suppose that R is a cDV singularity, with a minimal model $X \to \text{Spec } R$. Set $\Lambda := \text{End}_R(N)$, where $N := H^0(\mathcal{V}_X)$. Calculating $\Theta(\Lambda)$ by passing to a general hyperplane section g, the number of minimal models of Spec R is bounded below by the number of different curve configurations obtained in the enhanced chamber structure of $\Theta(\Lambda/g\Lambda)$.

Proof. Certainly if two minimal models X and Y cut under generic hyperplane section to two different curve configurations, then X and Y must be different minimal models. Thus it suffices to show that every curve configuration in the enhanced chamber structure of $\Theta(\Lambda/g\Lambda)$ does actually appear as the cut of some minimal model. By 5.24(3) and 5.25(3) it is possible to reach any such configuration starting at C_+ by mutating at indecomposable summands. Since by 4.6 at each wall crossing either the moduli stays the same, or some curve flops, each chamber in $\Theta(\Lambda)$ gives a minimal model of Spec R. Hence if a curve configuration is in a chamber D of $\Theta(\Lambda/g\Lambda)$, consider the minimal model given by the chamber D of $\Theta(\Lambda)$. This minimal model cuts to the desired curve configuration, by 5.20.

6. First Applications

6.1. The Craw–Ishii Conjecture. Combining moduli tracking from §5 with the Homological MMP in Figure 2 leads immediately to a proof of the Craw–Ishii conjecture for cDV singularities. To prove a slightly more precise version, the following terminology will be convenient.

Definition 6.1. The skeleton of the GIT chamber decomposition of Θ is defined to be the graph obtained by placing a vertex in every chamber, and two vertices are connected by an edge if and only if the associated chambers share a codimension one wall.

The following is the main result of this subsection.

Theorem 6.2. With the d = 3 crepant setup of 2.9, assume further that X is Q-factorial. Set $N = H^0(\mathcal{V}_X)$ and $\Lambda = \operatorname{End}_R(N)$, then

- (1) In the skeleton of $\Theta(\Lambda)$, there exists a connected path, containing the chamber C_+ , where every minimal model can be found. Furthermore, each wall crossing in this path corresponds to a flop.
- (2) The Craw-Ishii Conjecture 1.7 is true for cDV singularities, namely for any fixed $MMA \ \Gamma := \operatorname{End}_R(M)$ with $R \in \operatorname{add} M$, every projective minimal model can be obtained as the moduli space of Γ for some stability parameter ϑ .

Proof. (1) We run Figure 2 whilst picking only single curves satisfying $\dim_{\mathbb{C}} \Lambda_i < \infty$. As in 4.10, this produces all minimal models. By 4.19 we can view all these minimal models as the C_+ moduli on their corresponding algebra $\nu_{i_1} \dots \nu_{i_t} \Lambda$. By 5.25(3) it is possible to track all these back to give chambers in $\Theta(\Lambda)$, and the proof of 5.24 shows that this combinatorial tracking gives a connected path. The fact that each wall gives a flop is identical to 5.23, since at each stage $\dim_{\mathbb{C}} \Lambda_i < \infty$.

(2) Consider an MMA $\Gamma := \operatorname{End}_R(M)$ as in the statement. By the Auslander–McKay correspondence 4.10 $M \cong H^0(\mathcal{V}_Y)$ for some minimal model $Y \to \operatorname{Spec} R$. The result then follows by applying (1) to $Y \to \operatorname{Spec} R$.

We remark that flops of multiple curves can also be easily described. The following is the multi-curve version of 5.23.

Lemma 6.3. With the d = 3 crepant setup of 2.9, set $N = H^0(\mathcal{V}_X)$, $\Lambda = \operatorname{End}_R(N)$, and pick a subset of curves I above the origin. If $\dim_{\mathbb{C}} \Lambda_I < \infty$, then $\mathcal{M}_{\mathsf{rk}, \nu_{\mathbf{b}_I} \vartheta}(\Lambda)$ is the flop of $\bigcup_{i \in I} C_i$, for all $\vartheta \in C_+(\Lambda)$

Proof. This follows by combining 4.19 with moduli tracking 5.14, using 5.22 to establish that $\mathbf{b_I} = \mathbf{c_I}$.

6.2. Auslander–McKay Revisited. In the d = 3 crepant setup of 2.9, in this subsection we use the extra information of the GIT chamber decomposition of $\Theta(\Lambda)$ from §5 to extend aspects of the Auslander–McKay Correspondence from §4.2.

Theorem 6.4. The correspondence in 4.10 and 4.24 further satisfies

- (5) The simple mutation graph of MM generators can be viewed as a subgraph of the skeleton of the GIT chamber decomposition of $\Theta(\Lambda)$.
- (6) The number of MM generators is bounded above by the number of chambers in the GIT chamber decomposition of any of the MMAs, and is bounded below by the number of different curve configurations obtained in the enhanced chamber structure of Θ(Λ/gΛ).

Proof. Part (5) follows from 6.2(1) together with 4.10(3). The first part of (6) is then obvious, and the second half is 5.28.

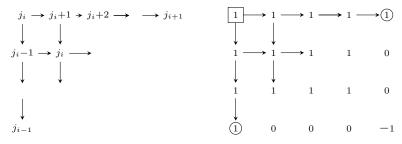
6.3. **Root Systems.** We observed in 5.26 that the chamber structure of partial resolutions of Kleinian singularities, and thus by 5.25 also the corresponding cDV singularities, cannot in general be identified with the root system of a semisimple Lie algebra. In special cases, however, they can.

Lemma 6.5. With the crepant setup $f: X \to \operatorname{Spec} R$ of 2.9, suppose that d = 2 and R is a type A Kleinian singularity. Set $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$. If there are t curves above the unique closed point, then the chamber structure for $\Theta(\Lambda)$ can be identified with the root system of \mathfrak{sl}_t .

Proof. Label the CM *R*-modules corresponding to the curves in the minimal resolution by N_1, \ldots, N_n , from left to right. Since X is dominated by the minimal resolution, it is obtained by contracting curves, to leave CM modules N_{j_1}, \ldots, N_{j_t} say, so that $N = H^0(\mathcal{V}_X) = N_{j_1} \oplus \ldots \oplus N_{j_t}$. By 5.24(3), the chamber structure can be calculated by tracking C_+ back through iterated mutation at indecomposable summands. The AR quiver is

$$\begin{array}{c} i \rightarrow i{+}1 \rightarrow \\ \downarrow \qquad \downarrow \\ i{-}1 \rightarrow i \rightarrow \\ \downarrow \qquad \downarrow \end{array}$$

Consider an indecomposable summand N_{j_i} (i.e. $I = \{j_i\}$), then to calculate its add N_{I^c} approximation, by knitting it is clear that



and so the combinatorics that determine the tracking negates ϑ_{j_i} and adds ϑ_{j_i} to each of its neighbours.

On the other hand, if we consider the minimal resolution of the Type A singularity $\frac{1}{t+1}(1,-1)$, which also has t curves above the origin, the combinatorics that governs tracking C_+ in this case is also the rule that negates ϑ_j and adds ϑ_j to its neighbours. Hence since the chamber structure for the minimal resolution of $\frac{1}{t+1}(1,-1)$ can be identified with the root system of \mathfrak{sl}_t [CS, Kr], so too can the chamber structure of $\Theta(\Lambda)$.

By combining 5.25 and 6.5, the following is immediate.

Corollary 6.6. With the d = 3 crepant setup $f: X \to \operatorname{Spec} R$ of 2.9, set $N := H^0(\mathcal{V}_X)$ and $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$. Suppose further that either

- (A) $f: X \to \operatorname{Spec} R$ is a minimal model, or
- (B) $f: X \to \operatorname{Spec} R$ is a flopping contraction.

where R is a complete local cA_n singularity. Set $\Lambda := \operatorname{End}_X(\mathcal{V}_X) \cong \operatorname{End}_R(N)$. If there are t curves above the unique closed point, then the chamber structure for $\Theta(\Lambda)$ can be identified with the root system of \mathfrak{sl}_t .

There are also other cases in which root systems appear. Consider the following assumption, made throughout in [T1].

Setup 6.7. In the d = 3 crepant setup of 2.9, suppose that R is isolated and there is a hyperplane section which cuts X to give the minimal resolution.

The setup is restrictive, for example in the case of a minimal model of Spec R with only one curve above the origin, it forces R to be Type A. Nevertheless, under the setup 6.7, associated to R is some ADE Dynkin diagram. The following recovers [T2, §5.1].

Lemma 6.8. With the assumption in 6.7,

- (1) The chamber structure of $\Theta(\Lambda)$ can be identified with the root system of the corresponding Dynkin diagram.
- (2) There are precisely |W| chambers, where W is the corresponding Weyl group.

Proof. (1) Since R is isolated $\operatorname{Ext}_{R}^{1}(N, N) = 0$. Thus the $\operatorname{Ext}_{R}^{1}(N, N)$ -regular condition in 5.19 is redundant, so 5.20 holds for the particular g in 6.7. Appealing to this directly in the proof of 5.25 shows that the chamber structure of $\Theta(\Lambda)$ and $\Theta(\Lambda/g\Lambda)$ coincide. Since by 6.7 the pullback of the hyperplane section is the full minimal resolution, it follows that

 $\Lambda/g\Lambda$ is the preprojective algebra of the corresponding Dynkin diagram, and its chamber structure is well-known [CS, Kr]. Part (2) is immediate.

6.4. Auslander–McKay for Isolated Singularities. With the crepant setup of 2.9, the case when R is in addition an isolated singularity is particularly important for two reasons. First, it aligns well with cluster theory, since in this setting $\underline{CM} R$ is a Hom-finite 2-CY category, with maximal rigid objects the MM generators, and cluster tilting objects (if they exist) the CT modules. Second, the minimal models are easier to count, thus we have finer control over the mutation graph.

Recall that if \mathcal{C} is an exact category, then $M \in \mathcal{C}$ is called *rigid* if $\operatorname{Ext}^{1}_{\mathcal{C}}(M, M) = 0$, and $M \in \mathcal{C}$ is called *maximal rigid* if M is rigid and further it is maximal with respect to this property, namely if there exists $Y \in \mathcal{C}$ such that $M \oplus Y$ is rigid, then $Y \in \operatorname{add} M$. Equivalently, M is a maximal rigid object of \mathcal{C} if

add $M = \{Y \in \mathcal{C} \mid \operatorname{Ext}^{1}_{\mathcal{C}}(M \oplus Y, M \oplus Y) = 0\}.$

Also, recall that $M \in \mathcal{C}$ is called a *cluster tilting* object in \mathcal{C} if

add $M = \{Y \in \mathcal{C} \mid \text{Ext}^{1}_{\mathcal{C}}(M, Y) = 0\} = \{X \in \mathcal{C} \mid \text{Ext}^{1}_{\mathcal{C}}(X, M) = 0\}.$

Corollary 6.9. Let R be a complete local isolated cDV singularity. Then 4.10 reduces to a one-to-one correspondence

{basic maximal rigid objects in CM R} \longleftrightarrow {minimal models $f_i: X_i \to \operatorname{Spec} R$ }.

If further the minimal models of Spec R are smooth (equivalently, CM R admits a cluster tilting object), then this reduces to

 $\{basic \ cluster \ tilting \ objects \ in \ CM \ R\} \ \longleftrightarrow \ \{crepant \ resolutions \ f_i \colon X_i \to \operatorname{Spec} \ R\}.$

In either case, under this correspondence properties (1)-(4) in 4.10 and 4.24 still hold, but further we now also have

- (5) The simple mutation graph of the maximal rigid (respectively, cluster tilting) objects in $\underline{CM} R$ is precisely the skeleton of the GIT chamber structure.
- (6) The number of basic maximal rigid (respectively, cluster tilting) objects in $\underline{CM}R$ is precisely the number of chambers in the GIT chamber decomposition.

If furthermore 6.7 is satisfied, then

(7) There are precisely |W| maximal rigid objects in $C = \underline{CM}R$, where W is the corresponding Weyl group.

Proof. Since R is isolated, M is a maximal rigid object in the category CM R if and only if M is an MM generator [IW2, 5.12], so the first bijection is a special case of the bijection in 4.10. The second bijection is similar, using [IW2, 5.11]. Further, since R is isolated, it follows that always dim_{$\mathbb{C}} \Lambda_i < \infty$, so all curves flop, and all summands non-trivially mutate. Thus (5) follows from 4.10(3), using the argument of 6.2(1). Part (6) follows immediately from (5), and part (7) follows from (6) together with 6.8.</sub>

We refer the reader to §7.1 for examples of chamber structures and mutation graphs. The following is a non-explicit proof of [BIKR, 4.15], extended from crepant resolutions to also cover minimal models.

Corollary 6.10. Consider an isolated cDV singularity $R := \mathbb{C}[[u, v, x, y]]/(uv - f_1 \dots f_n)$ where each $f_i \in \mathfrak{m} := (x, y) \subseteq \mathbb{C}[[x, y]]$. Then there are precisely n! maximal rigid objects in $\underline{CM} R$, and all are connected by mutation.

Proof. As in [BIKR, 6.1(e)], R is a cA_m singularity, where $m = \operatorname{ord}(f_1 \dots f_n) - 1$, and it is well known (see e.g. the calculation in [IW3, §5.1]) that the minimal models of Spec R have n curves above the origin. But by 6.6 the GIT chamber decomposition of any of the MMAs $\operatorname{End}_R(M)$ with $R \in \operatorname{add} M$ has precisely n! chambers, so the result follows from 6.9.

6.5. **Partial Converse.** Let R be a complete local Gorenstein 3-fold. By the Auslander–McKay correspondence, if R is cDV then there are only finitely many basic MM modules up to isomorphism. Recall from 1.14 that we conjecture the converse to be true. Since such R are known to be hypersurfaces, the corollary of the following result, although it does not prove the conjecture, does give it some credibility.

As preparation, recall that the *complexity* of $M \in \text{mod } R$ measures the rate of growth of the ranks of the free modules in the minimal projective resolution of M, and is defined

$$\operatorname{cx}_R(M) := \inf\{t \in \mathbb{Z}_{>0} \mid \exists a \in \mathbb{R} \text{ with } \dim_{\mathbb{C}} \operatorname{Ext}_R^n(M,k) \le an^{t-1} \text{ for } n \gg 0\}.$$

Since $\operatorname{cx}_R(M)$ measures the asymptotic behaviour, it is clear that $\operatorname{cx}_R(M) = \operatorname{cx}_R(\Omega^i M)$ for all $i \geq 0$.

The following extends [B13, §3] to cover not-necessarily-isolated singularities.

Proposition 6.11. Suppose that R is a d-dimensional complete local Gorenstein algebra. If R admits only finitely many basic CT modules up to isomorphism, then R is a hypersurface.

Proof. Let M be such a CT module, which is necessarily a generator, and consider $X := \Omega^d k \in CM R$. Since R is Gorenstein, by taking a projective cover of X^* then dualizing, we have an exact sequence $0 \to X \to P_0 \to P_1$ with each $P_i \in \text{add } R$. Applying $\text{Hom}_R(M, -)$ gives an exact sequence

 $0 \to \operatorname{Hom}_R(M, X) \to \operatorname{Hom}_R(M, P_0) \xrightarrow{g} \operatorname{Hom}_R(M, P_1) \to \operatorname{Cok} g \to 0.$

Since both $\operatorname{Hom}_R(M, P_i)$ are projective $\operatorname{End}_R(M)$ -modules, and $\operatorname{gl.dim} \operatorname{End}_R(M) = d$ by [IW2, 5.4], it follows that $\operatorname{pd}_{\operatorname{End}_R(M)} \operatorname{Hom}_R(M, X) \leq d-2$.

Since M is a generator, $\operatorname{Hom}_R(M, -)$: $\operatorname{mod} R \to \operatorname{mod} \operatorname{End}_R(M)$ is fully faithful, and restricts to an equivalence add $M \to \operatorname{proj} \operatorname{End}_R(M)$, see e.g. [IW2, 2.5(1)]. Thus we may take a projective resolution

$$0 \to \operatorname{Hom}_R(M, M_{d-2}) \to \ldots \to \operatorname{Hom}_R(M, M_0) \to \operatorname{Hom}_R(M, X) \to 0$$

which necessarily comes from a complex

$$0 \to M_{d-2} \to M_{d-3} \dots \to M_0 \to X \to 0. \tag{6.A}$$

This complex (6.A) is exact, since M is a generator.

Now, by general mutation theory, $\Omega^i M$ are CT modules for all $i \in \mathbb{N}$ [IW2, 6.11], and since by assumption there are only finitely many basic CT modules, $\Omega^i M \cong \Omega^j M$ for some $i \neq j$, which by taking cosyzygies implies that $\Omega^t M \cong M$ for some $t \ge 1$. Consequently, $\operatorname{cx}_R M \le 1$.

But splicing the sequence (6.A) gives an exact sequence

$$0 \rightarrow M_{d-2} \rightarrow M_{d-3} \rightarrow C_{d-3} \rightarrow 0$$

and thus an exact sequence

$$\dots \to \operatorname{Ext}_{R}^{n}(M_{d-2},k) \to \operatorname{Ext}_{R}^{n+1}(C_{d-3},k) \to \operatorname{Ext}_{R}^{n+1}(M_{d-3},k) \to \dots$$
(6.B)

Since $\operatorname{cx}_R M \leq 1$ there exist $a_i \in \mathbb{R}$ such that $\dim_{\mathbb{C}} \operatorname{Ext}_R^n(M_i, k) \leq a_i$ for $n \gg 0$. Thus inspecting (6.B) it follows that $\dim_{\mathbb{C}} \operatorname{Ext}_R^n(C_{d-3}, k) \leq a_{d-2} + a_{d-3}$ for $n \gg 0$, so $\operatorname{cx}_R C_{d-3} \leq 1$. Inducting along the splicing of (6.A) gives $\operatorname{cx}_R X \leq 1$, which implies that $\operatorname{cx}_R k \leq 1$. This is well-known to imply that R is a hypersurface [G]. \Box

Corollary 6.12. Suppose that R is a 3-dimensional complete local normal Gorenstein algebra, and suppose that R admits an NCCR. If there are only finitely many basic MM generators up to isomorphism, then R is a hypersurface.

Proof. Since R admits an NCCR, by [IW2, 5.9] CM R has a CT module. As a consequence, by [IW2, 5.11(2)] CT modules are precisely the MM generators, so the assumptions now imply that there are only finitely many CT modules. Thus the result follows from 6.11. \Box

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7. Examples

In this section we summarise the GIT chamber decompositions of some crepant partial resolutions of ADE surface singularities, and give the corresponding applications to cDV singularities. We also illustrate how to run Figure 2 in some explicit cases.

7.1. **GIT Chamber structures.** Throughout this subsection, $Y \to \operatorname{Spec} S$ denotes a crepant partial resolution, where S is a complete local ADE surface singularity, and $X \to \operatorname{Spec} R$ denotes a crepant partial resolution, where R is cDV.

Example 7.1. Suppose that $Y \to \operatorname{Spec} S$ has only one curve above the origin. Then Θ is parametrised by ϑ_1 , and there is a single wall at $\vartheta_1 = 0$



In the d = 3 crepant setting 2.9, if $X \to \operatorname{Spec} R$ has only one curve above the origin and does not contract a divisor, then it has the above chamber structure. This includes, as a special case, all simple flops.

Example 7.2. With notation as in $\S5.3$, using a similar argument as in 5.26, the following are examples of chamber structures for some 2-curve configurations.

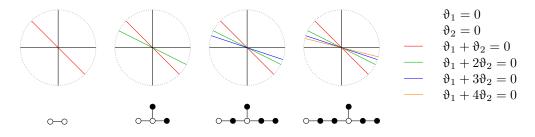


FIGURE 4. Chamber structures for some two curve configurations.

Example 7.3. If further we enhance each chamber with the curve configuration for that chamber (calculated as a byproduct of mutation, as in 5.27), for E_6 with configuration

after rescaling we obtain the enhanced GIT chamber decomposition

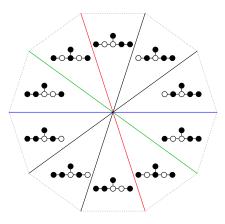


FIGURE 5. Enhanced chamber decomposition for E_6 with configuration (7.A).

By 5.28, it follows that any cDV singularity with a minimal model that cuts under generic hyperplane section to (7.A) has at least 5, and at most 10, minimal models.

Example 7.4. For the 3-curve configuration ----, the chamber structure is

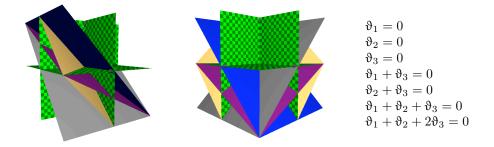


FIGURE 6. The 32 chambers for (1, 2, 1)

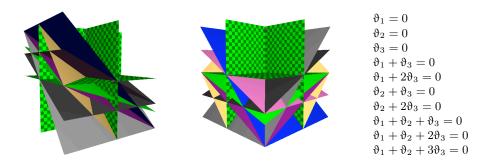


FIGURE 7. The 60 chambers for (1, 3, 1)

Tracking the dual graph through mutation, as in 5.27 and 5.28, any cDV singularity with a minimal model that cuts to the above D_4 configuration has at least 4 and at most 32 minimal models. Any cDV singularity with a minimal model that cuts to the above E_6 configuration has at least 5 and at most 60 minimal models.

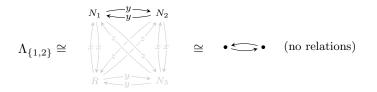
Remark 7.5. The singularity $R := \mathbb{C}[[u, x, y, z]]/(u^2 - xyz)$ in 3.4 is in fact cD_4 with a three curve configuration, so the chamber structure is precisely Figure 6. The chamber structure for the particular example $u^2 = xyz$ was computed independently, using entirely different methods, by Craw and King in 2000. Indeed, [C01, 5.31, footnote 5 p117] computes the first four chambers. See also [MT].

7.2. Running the algorithm. This subsection illustrates how to run the Homological MMP in two examples. For the aid of the reader, we begin with the toric example in 3.4, since the geometry will already be familiar.

Example 7.6. Consider again the cD_4 singularity $R := \mathbb{C}[[u, x, y, z]]/(u^2 = xyz)$. As in [IW2, 6.26], $N := R \oplus (u, x) \oplus (u, y) \oplus (u, z)$ is an MM (in fact, CT) *R*-module, and

with the relations being interpreted as x, y and z commute wherever that makes sense. From the quiver, by 2.15 we read off that the fibre above the origin has three curves meeting at a point, and all are (-1, -1)-curves.

Step 1: Contractions. We inspect the contraction algebras to determine which sets of curves are floppable. It is clear that $\Lambda_{\{1\}} = \Lambda_{\{2\}} = \Lambda_{\{3\}} = \mathbb{C}$, and so each of the three curves is individually floppable. Furthermore,

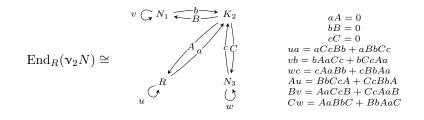


since all relations in (7.B) involve x's and z's, and these are zero in the quotient. Thus $\dim_{\mathbb{C}} \Lambda_{\{1,2\}} = \infty$ and so curves 1 and 2 do not flop together. By symmetry in this example, the same can be said of all pairs. Finally $\dim_{\mathbb{C}} \Lambda_{\{1,2,3\}} = \infty$. Hence each individual curve flops, but no other combinations do.

Step 2: Flops. By symmetry, we only need mutate at N_2 (i.e. flop curve two), since the other cases are identical. In this example, it is clear that the relevant approximation is

$$0 \to N_2 \xrightarrow{(z \, y \, x)} R \oplus N_1 \oplus N_3$$

Thus the mutation at vertex N_2 changes $N = R \oplus N_1 \oplus N_2 \oplus N_3$ into $\nu_2 N := R \oplus N_1 \oplus K_2 \oplus N_3$ where K_2 is the cokernel of the above map which (by counting ranks) has rank 2. On the level of quivers of the endomorphism rings, this induces the mutation



By 2.15 we read off that the new dual graph has three curves intersecting in a type A configuration, with the outer two curves being (-2, 0)-curves, and the inner curve being a (-1, -1)-curve. By the symmetry of the situation, we obtain the beginning of the simple mutation graph:

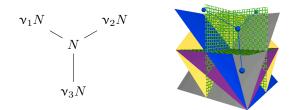


FIGURE 8. The simple mutation graph for $u^2 = xyz$.

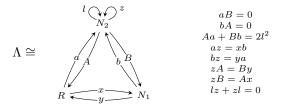
We next claim that this is precisely the simple mutation graph of the MM generators, equivalently we have already found all minimal models of Spec R.

Step 1b: Contractions. We plug in the mutated algebra $\operatorname{End}_R(\nu_2 N)$ into Step 1, and repeat. Due to the relations in the algebra $\nu_2 \Lambda = \operatorname{End}_R(\nu_2 N)$, it follows that $\dim_{\mathbb{C}}(\nu_2 \Lambda)_{\{1\}} = \infty = \dim_{\mathbb{C}}(\nu_2 \Lambda)_{\{3\}}$, thus in $\nu_2 \Lambda$ the only curve we can non-trivially mutate is the middle one, which gives us back our original N. Thus the Homological MMP stops, and we have reached all minimal models.

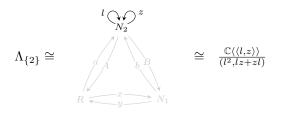
Example 7.7. Consider the cD_4 singularity $R := \mathbb{C}[[u, v, y, z]]/(u^2 - v(x^2 - 4y^3))$. Since $R \cong \mathbb{C}[[x, y, z]]^{S_3}$ for the subgroup

$$S_3 := \left\langle \begin{pmatrix} \varepsilon_3 & 0 & 0\\ 0 & \varepsilon_3^2 & 0\\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0\\ 1 & 0 & 0\\ 0 & 0 & -1 \end{pmatrix} \right\rangle \le \mathrm{SL}(3, \mathbb{C}),$$

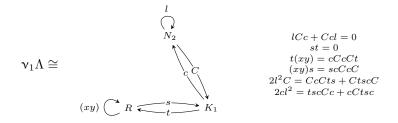
there is an MM generator (in fact, CT module) given by the skew group ring $\Lambda := \operatorname{End}_R(N)$, and further by [BSW] it can be presented as



given by the superpotential $\Phi := Axb + Bya - zAa - zBb + 2zl^2$. By 2.15 we read off that there are two curves intersecting transversely, one with normal bundle (-3, 1), the other with normal bundle (-1, -1). Further,

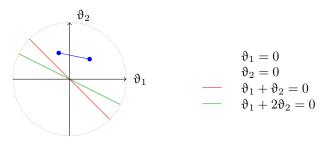


which is infinite dimensional, and clearly $\Lambda_{\{1\}} = \mathbb{C}$, which is finite dimensional. Hence by 3.5 only the (-1, -1)-curve flops. It is easy to calculate that



given by potential $\Phi' := -t(xy)s - cl^2C + cCcCts$. Again by inspection, $(\nu_1\Lambda)_{\{2\}} = \mathbb{C}[[l]]$, which is infinite dimensional, and $(\nu_1\Lambda)_{\{2\}} = \mathbb{C}$, which is finite dimensional.

Hence the only way to mutate is back, so the Homological MMP finishes. It follows that the full mutation graph, viewed inside the GIT chamber structure $\Theta(\Lambda)$, is



Remark 7.8. The mutation trees of quivers are usually quite easy to write down, and this then determines all the geometry. We refer the reader to [NS, §4.1] for the calculation of the mutation trees for some other quotient singularities, in particular [NS, 4.4]. We remark that it follows from Figure 2 that [NS, §4.1] is now enough to establish we have all minimal models. In particular, we can immediately read off the dual graph and whether curves flop from the quivers there, avoiding all the hard explicit calculations in [NS, §5–6].

APPENDIX A. MUTATION SUMMARY

This appendix contains the mutation results needed in the text, including 2.21 and 2.22, which for the most part are just mild generalisations of some of the results in [IW2, §6]. Throughout, we maintain the setup of §2.3 and 5.3, so unless stated otherwise R denotes a complete local normal d-sCY commutative algebra with $d \ge 2$, $M \in \text{ref } R$ denotes a basic modifying module M, and M_I is a summand of M.

The following duality proposition is important, and will be used extensively.

Proposition A.1. [IW2, 6.4] With notation as above,

(1) Applying $\operatorname{Hom}_{R}(-, M_{I^{c}})$ to (2.E) induces an exact sequence

 $0 \to \operatorname{Hom}_R(M_I, M_{I^c}) \xrightarrow{\cdot a} \operatorname{Hom}_R(V_I, M_{I^c}) \xrightarrow{\cdot c} \operatorname{Hom}_R(K_I, M_{I^c}) \to 0.$

In particular c is a minimal left add M_{I^c} -approximation.

(2) Applying $\operatorname{Hom}_{R}(-, M_{I^{c}}^{*})$ to (2.1) induces an exact sequence

$$0 \to \operatorname{Hom}_{R}(M_{I}^{*}, M_{I^{c}}^{*}) \xrightarrow{\circ b} \operatorname{Hom}_{R}(U_{I}^{*}, M_{I^{c}}^{*}) \xrightarrow{\cdot d} \operatorname{Hom}_{R}(J_{I}, M_{I^{c}}^{*}) \to 0$$

In particular d is a minimal left add M_{Ic}^* -approximation.

(3) We have that

$$0 \to M_I^* \xrightarrow{a^*} V_I^* \xrightarrow{c^*} K_I^*$$
$$0 \to M_I \xrightarrow{b^*} U_I \xrightarrow{d^*} J_I^*$$
(A.A)

are exact, inducing exact sequences

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, M_{I}^{*}) \xrightarrow{a^{*}} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, V_{I}^{*}) \xrightarrow{c^{*}} \operatorname{Hom}_{R}(M_{I^{c}}^{*}, K_{I}^{*}) \to 0$$
(A.B)

$$0 \to \operatorname{Hom}_{R}(K_{I}^{*}, M_{I^{c}}) \xrightarrow{c^{*}} \operatorname{Hom}_{R}(V_{I}^{*}, M_{I^{c}}^{*}) \xrightarrow{a^{*}} \operatorname{Hom}_{R}(M_{I}^{*}, M_{I^{c}}^{*}) \to 0$$
(A.B)

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}, M_{I}) \xrightarrow{b^{*}} \operatorname{Hom}_{R}(M_{I^{c}}, U_{I}) \xrightarrow{d^{*}} \operatorname{Hom}_{R}(M_{I^{c}}, J_{I}^{*}) \to 0$$
(A.C)

$$0 \to \operatorname{Hom}_{R}(J_{I}^{*}, M_{I^{c}}) \xrightarrow{d^{*}} \operatorname{Hom}_{R}(U_{I}, M_{I^{c}}) \xrightarrow{b^{*}} \operatorname{Hom}_{R}(M_{I}, M_{I^{c}}) \to 0$$
(A.C)

In this level of generality, usually $\nu_I M \ncong \mu_I M$, and $\nu_I \nu_I M \ncong M$. However, we will be interested in when these, and other, nice situations occur.

Proposition A.2. In setup of 5.3, assume further that $pd_{\Lambda}\Lambda_I = 2$. Then

- (1) $\mu_I M \cong M \cong \nu_I M$.
- (2) The minimal projective resolution of Λ_I as a Λ -module is

$$0 \to \operatorname{Hom}_R(M, M_I) \xrightarrow{\cdot c} \operatorname{Hom}_R(M, V_I) \to \operatorname{Hom}_R(M, M_I) \xrightarrow{\cdot a} \Lambda_I \to 0$$

(3) The minimal projective resolution of Λ_I^{op} as a $\Lambda^{\text{op}} \cong \text{End}_R(M^*)$ -module is

$$0 \to \operatorname{Hom}_{R}(M^{*}, M_{I}^{*}) \xrightarrow{\cdot a^{*}} \operatorname{Hom}_{R}(M^{*}, V_{I}^{*}) \xrightarrow{\cdot c^{*}} \operatorname{Hom}_{R}(M^{*}, M_{I}^{*}) \to \Lambda_{I}^{\operatorname{op}} \to 0$$

Proof. Since $pd_{\Lambda}\Lambda_I = 2$ there is a minimal projective resolution

$$0 \to Q_1 \to Q_0 \xrightarrow{f} P_I \to \Lambda_I \to 0 \tag{A.D}$$

where $P_I := \text{Hom}_R(M, M_I)$ is not a summand of Q_0 . Now $M_I = \bigoplus_{i \in I} M_i$, so taking the minimal right M_{I^c} -approximations of each M_i gives exact sequences

$$0 \to K_i \xrightarrow{c_i} V_i \xrightarrow{a_i} M_i \tag{A.E}$$

which sum together to give the exact sequence

$$0 \to (K_I = \bigoplus_{i \in I} K_i) \xrightarrow{c} (V_I = \bigoplus_{i \in I} V_i) \xrightarrow{a} (M_I = \bigoplus_{i \in I} M_i).$$
(A.F)

This is the minimal right add M_{I^c} -approximation of M_I , so applying $\operatorname{Hom}_R(M, -)$ gives (A.D). In particular $K_I \in \operatorname{add} M$. We claim that $K_I \cong M_I$, as this proves (2).

First, each $K_i \in \text{add } M_I$. To see this, suppose it is false, which since $K_I \in \text{add } M$ would mean that $K_i \in \text{add } M_{I^c}$. By A.1, dualizing (A.E) gives exact sequences

$$0 \to M_i^* \to V_i^* \to K_i^* \tag{A.G}$$

such that

$$0 \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, M_{i}^{*}) \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, V_{i}^{*}) \to \operatorname{Hom}_{R}(M_{I^{c}}^{*}, K_{i}^{*}) \to 0$$
(A.H)

is exact. Since we are assuming $K_i \in \operatorname{add} M_{I^c}$, this would mean that

$$0 \to \operatorname{Hom}_{R}(K_{i}^{*}, M_{i}^{*}) \to \operatorname{Hom}_{R}(K_{i}^{*}, V_{i}^{*}) \to \operatorname{Hom}_{R}(K_{i}^{*}, K_{i}^{*}) \to 0$$

is exact. Considered as $\operatorname{End}_R(K_i^*)$ -modules, the last term is projective, so the sequence splits. It follows that $\operatorname{Hom}_R(K_i^*, M_i^*)$ is a summand of $\operatorname{Hom}_R(K_i^*, V_i^*)$. By reflexive equivalence, M_i^* is then a summand of V_i^* , thus M_i is a summand of V_i , which is a contradiction since $V_i \in \operatorname{add} M_{I^c}$. This shows that each $K_i \in \operatorname{add} M_I$.

Now since each K_i is indecomposable, it remains to show that $K_i \ncong K_j$ for $i \neq j$. Suppose that it is false, i.e. $K_i \cong K_j$ with $i \neq j$. By (A.G) and (A.H), the map $c_i^* \colon V_i^* \to K_i^*$ is a minimal right add $M_{I^c}^*$ -approximation for all $i \in I$, thus since $K_i^* \cong K_j^*$ it follows that $M_i^* \cong M_j^*$, which is a contradiction since M is basic. It follows that $K_I \cong M_I$, so (2) holds. Further, (A.F) is the exact sequence

$$0 \to M_I \xrightarrow{c} V_I \xrightarrow{a} M_I \tag{A.I}$$

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with a a minimal right add M_{I^c} -approximation of M_I , so by definition $\mu_I M = M_{I^c} \oplus \text{Ker } a \cong M$, proving the first half of (1). Now by A.1, dualizing (A.I) gives an exact sequence

$$0 \to M_I^* \xrightarrow{a^*} V_I^* \xrightarrow{c^*} M_I^* \tag{A.J}$$

and by (A.B) c^* is a minimal right add $M_{I^c}^*$ -approximation. Thus applying $\operatorname{Hom}_R(M^*, -)$ gives the minimal projective resolution of $\Lambda_I^{\operatorname{op}}$, proving (3). Also, by definition $\nu_I M = M_{I^c} \oplus (\operatorname{Ker}(c^*))^* \cong M$, proving the second half of (1).

The following gives equivalent conditions to when the assumptions of A.2 hold.

Lemma A.3. In the setup of 5.3, the following are equivalent

- (1) $\mathrm{pd}_{\Lambda}\Lambda_{I} = 2.$
- (2) $\operatorname{pd}_{\Lambda}\Lambda_{I} < \infty$ and $\operatorname{depth}_{R}\Lambda_{I} = d 2$.
- (3) $\mathbf{v}_I M \cong M$.
- (4) $\mu_I M \cong M$.

Proof. (1) \Leftrightarrow (2) is just the Auslander–Buchsbaum formula [IW2, 2.15]. (1) \Rightarrow (3) is A.2.

(3) \Rightarrow (4) Since $\nu_I M \cong M$, (A.A) is simply

$$0 \to M_I \xrightarrow{b^*} U_I \xrightarrow{d^*} M_I$$

where d^* is a minimal add M_{I^c} -approximation by A.1. Since minimal approximations are unique, $V_I \cong U_I$ and $\mu_I M \cong M_{I^c} \oplus M_I = M$.

(4) \Rightarrow (1) Applying Hom_R(M, -) to (2.E) gives an exact sequence

$$0 \to \operatorname{Hom}_R(M, K_I) \to \operatorname{Hom}_R(M, V_I) \to \operatorname{Hom}_R(M, M_I) \to \Lambda_I \to 0.$$

Since $\mu_I M \cong M$, $K_I \cong M_I$ and so the first three terms are all projective.

Remark A.4. We remark that when dim R = 2, R is an isolated singularity and so automatically dim_C $\Lambda_I < \infty$, which implies that depth_R $\Lambda_I = 0$. Thus in this case the conditions in A.3 are equivalent to simply $pd_{\Lambda}\Lambda_I < \infty$.

The last two results combine to prove the following, which was stated in $\S2.3$.

Corollary A.5. In the setup of 5.3, suppose that $v_I M \cong M$. Then

- (1) $T_I = \Lambda (1 e_I) \Lambda$ and $\Gamma := \operatorname{End}_{\Lambda}(T_I) \cong \Lambda$.
- (2) $\Omega_{\Lambda}\Lambda_I = T_I$, thus $\mathrm{pd}_{\Lambda}\Lambda_I = 2$ and $\mathrm{Ext}^1_{\Lambda}(T_I, -) \cong \mathrm{Ext}^2_{\Lambda}(\Lambda_I, -)$.

Proof. (1) Adding the exact sequence $0 \to 0 \to \operatorname{Hom}_R(M, M_{I^c}) \xrightarrow{\operatorname{Id}} \operatorname{Hom}_R(M, M_{I^c}) \to 0 \to 0$ to the minimal projective resolution in A.2(2) gives the projective resolution

$$0 \to \operatorname{Hom}_R(M, M_I) \xrightarrow{\Psi} \operatorname{Hom}_R(M, V_I \oplus M_{I^c}) \to \Lambda \to \Lambda_I \to 0.$$

By definition T_I is the cokernel of the morphism ψ , which by inspection is $\Lambda(1 - e_I)\Lambda$. The isomorphism $\operatorname{End}_{\Lambda}(T_I) \cong \Lambda$ is [DW1, 6.1(1)].

(2) This follows from the exact sequence above, together with dimension shifting. \Box

By contrast to A.5, it is often the case that $v_I M \ncong M$. The following is needed, and depends heavily on A.1.

Lemma A.6. In the setup of 5.3, suppose further that either

- (a) $\mathbf{v}_I M \cong M$, or
- (b) $\mathbf{v}_I \mathbf{v}_I M \cong M$ and $\dim_{\mathbb{C}} \operatorname{End}_R(M)_I < \infty$.

holds. Then (a) or (b) also holds for $N_1 := \mathbf{v}_I M$, $N_2 := M^*$ and $N_3 := (\mathbf{v}_I M)^*$.

Proof. Suppose that M satisfies assumption (a). The fact that $\nu_I M$ also satisfies (a) is obvious. The fact that M^* does too is a consequence of A.1, so since $(\nu_I M)^* = M^*$ in this case, so too does N_3 .

Hence we can assume that M satisfies assumption (b). We see that $\mathbf{v}_I \mathbf{v}_I N_1 \cong N_1$ simply by applying \mathbf{v}_I to both sides of the equation $\mathbf{v}_I \mathbf{v}_I M \cong M$. Since $\Lambda_I \cong (\mathbf{v}_I \Lambda)_I$ by [IW1, 6.20], the finite dimensionality is preserved too. For the statement involving N_2 , we need some notation. Since $\mathbf{v}_I M := M_{I^c} \oplus J_I^*$, we consider a minimal right $\operatorname{add}(\frac{\mathbf{v}_I M}{J_*^*})^* = \operatorname{add} M_{I^c}^*$ approximation of $(J_I^*)^* \cong J_I$

$$0 \to \operatorname{Ker} \to W_I^* \to J_I$$

then since $\nu_I \nu_I M \cong M$, Ker^{*} $\cong M_I$. Thus dualizing the above, using A.1,

$$0 \to J_I^* \to W_I \to M_I \tag{A.K}$$

is exact, where the last map is a minimal add M_{I^c} -approximation. By uniqueness of minimal approximations $W_I \cong V_I$, and $\nu_I(M^*) = M_{I^c}^* \oplus J_I$. Finally (A.A) and (A.C) show that $\nu_I \nu_I(M^*) \cong M^*$. The finite dimensionality part follows since $(\Lambda_I)^{\text{op}} = (\Lambda^{\text{op}})_I$. The statement for N_3 follows by combining the statements for N_1 and N_2 .

Proposition A.7. In the setup of 5.3, suppose further that $d \ge 3$, and that assumption (b) in A.6 is satisfied. Then

(1) Applying $\operatorname{Hom}_R(M, -)$ to the sequence (A.A) gives an exact sequence

 $0 \to \operatorname{Hom}_R(M, M_I) \to \operatorname{Hom}_R(M, U_I) \to \operatorname{Hom}_R(M, J_I^*) \to 0.$

- (2) $\mathbf{v}_I M \ncong M$.
- (3) The minimal projective resolution of Λ_I as a Λ -module is

 $0 \to \operatorname{Hom}_R(M, M_I) \to \operatorname{Hom}_R(M, U_I) \to \operatorname{Hom}_R(M, V_I) \to \operatorname{Hom}_R(M, M_I) \to \Lambda_I \to 0.$ (4) d = 3.

Proof. (1) This is the argument in [IW2, (6.Q)]. Denote $\mathbb{G} := \operatorname{Hom}_R(M_{I^c}, -)$, then applying $\operatorname{Hom}_R(M, -)$ to (A.A) and applying $\operatorname{Hom}_{\Lambda}(\mathbb{G}M, -)$ to (A.C) and comparing them, by reflexive equivalence

Hence C is a submodule of $\operatorname{Ext}_{\Lambda}^{1}(\mathbb{G}M, \mathbb{G}M_{I})$. But since (A.C) is exact, it follows that $e_{I}C = 0$ and so C is a finitely generated Λ_{I} -module. Since Λ_{I} has finite length, so too does C. But depth_R $\operatorname{Ext}_{\Lambda}^{1}(\mathbb{G}M, \mathbb{G}M_{I}) > 0$ since $\operatorname{Hom}_{\Lambda}(\mathbb{G}M, \mathbb{G}M_{I}) \cong \operatorname{Hom}_{R}(M, M_{I}) \in \operatorname{CM} R$, hence C = 0.

(2) If $\nu_I M \cong M$, then $J_I^* \cong M_I$. Consequently, viewing the exact sequence in (1) as $\operatorname{End}_R(M)$ -modules, the last term is projective and so the sequence splits. By reflexive equivalence this would imply that M_I is a summand of $U_I \in \operatorname{add} M_{I^c}$, which is a contradiction.

(3) Since the last map in (A.K) is a minimal right add M_{I^c} -approximation, applying $\operatorname{Hom}_R(M, -)$ to (A.K) gives an exact sequence

$$0 \to \operatorname{Hom}_R(M, J_I^*) \to \operatorname{Hom}_R(M, V_I) \to \operatorname{Hom}_R(M, M_I) \to \Lambda_{\operatorname{con}}^I \to 0$$

Splicing this with the exact sequence in (1) gives the result.

(4) If d > 3, applying the depth lemma to the projective resolution in (3) gives a contradiction.

The above results give the following, stated in $\S2.3$.

Corollary A.8. Suppose that $d \ge 3$, $\nu_I \nu_I M \cong M$ and $\dim_{\mathbb{C}} \Lambda_I < \infty$. As above, set $\Gamma := \operatorname{End}_{\Lambda}(T_I) \cong \operatorname{End}_R(\nu_I M)$. Then

- (1) $T_I \cong \operatorname{Hom}_R(M, \nu_I M).$
- (2) $\Omega_{\Lambda}^2 \Lambda_I = T_I$, thus $\operatorname{pd}_{\Lambda} \Lambda_I = 3$ and $\operatorname{Ext}^1_{\Lambda}(T_I, -) \cong \operatorname{Ext}^3_{\Lambda}(\Lambda_I, -)$.

Proof. (1) This follows from the definition of T_I , together with A.7(1). (2) This is now immediate from (1), A.7(1) and A.7(3).

APPENDIX B. CONJECTURES

This appendix outlines conjectures and further directions. First and foremost, we are hampered by the fact that the Bridgeland–Chen flop functor is only known to be an equivalence in the setting of Gorenstein terminal singularities. This paper began by trying to lift the reconstruction algebra of [Wem] to 3-folds, and through the analysis of many non-Gorenstein examples. There is evidence to suggest the following.

Conjecture B.1. Suppose that $X \to X_{\text{con}}$ is a flopping contraction of 3-folds, where X has at worst CM rational singularities. Then the flop functor is an equivalence if and only if the universal sheaf of the noncommutative deformation functor associated to the curves is a perfect complex (equivalently, $pd_{\Lambda}\Lambda_{\text{con}} < \infty$).

This would recover Bridgeland [B02] and Chen [C02], since when X has only Gorenstein terminal singularities, the universal sheaf is guaranteed to be perfect [DW1, 7.1].

Whilst mutation needs R to be Gorenstein to ensure that it gives a derived equivalence, it can sometimes be an equivalence when R is not Gorenstein. The relationship between flops and mutation seems to be tight.

Conjecture B.2. When C_i is a crepant curve whose universal sheaf is perfect, and X has at worst CM rational singularities, then Theorem 1.2 remains true.

Conjecture B.3. The Homological MMP in Figure 2 can be used to flop curves and jump between minimal models of non–Gorenstein singularities, again in the CM rational singularities setting, provided that we account for $pd_{\Lambda}\Lambda_{con} < \infty$.

Even although $pd_{\Lambda}\Lambda_{con} < \infty$ seems necessary to relate mutation to flops, it does not seem so relevant for moduli tracking purposes. The following is at least true in many examples, and may be true more generally.

Conjecture B.4. The moduli tracking theorem 5.12 is true under the simplifying assumption $\mathbf{v}_I \mathbf{v}_I M \cong M$.

Tracking moduli in the non-Gorenstein setting is substantially harder, since even reasonable algebras like NCCRs need not be closed under derived equivalence.

In an algebraic direction, 4.10 should extend to the situation when R is not Gorenstein. There is a version of the Auslander–McKay Correspondence in dimension two when R is not Gorenstein [Wun, Wem], obtained by replacing CM modules by Wunram's notion of a special CM module [Wun]. There should be a three dimensional analogue of this.

Conjecture B.5. There is a notion of 'special MM generator' such that the Auslander– McKay Correspondence 4.10 holds for non–Gorenstein rational 3-fold singularities whose minimal models have fibres that are at most one-dimensional.

Of course, the above conjecture must also account for $pd_{\Lambda}\Lambda_{con} < \infty$, but again this is guaranteed if we restrict to those Spec R admitting minimal models with only Gorenstein terminal singularities.

Since the noncommutative deformations in §3 detect contractions for both flips and flops, and has no restriction on singularities, it is reasonable to speculate about modifying the Homological MMP to cover flips. Indeed, philosophically there we should *not* be changing the GIT stability, since there is no derived equivalence so we do not expect to be able to track the moduli back. Instead, we change the algebra, keeping the GIT fixed.

Conjecture B.6. In the setting of CM rational singularities, given $N = H^0(\mathcal{V}_X)$, there is some homological modification of mutation that produces $H^0(\mathcal{V}_{X'})$ where X' is the flip. Consequently, the Homological MMP in Figure 2 can be extended to cover both flips and flops.

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