Conditions for propagation and block of excitation in asymptotic model of atrial tissue

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Outline of the talk

1) Introduction
   a) Cardiac function and physiology
   b) Electrical properties of cardiac cells and ionic models
2) Motivation: Examples of break-up and self-termination.
3) Asymptotic simplification of detailed voltage-gated models of cardiac tissue
4) Application: Conditions of propagation in atrial tissue
5) Conclusions
Function of the heart

The human heart is really a DOUBLE PUMP i.e. two pumps in series – each pump quite separate from the other.

RIGHT ATRIUM — receives the blood returning from the lungs with its oxygen supply increased and its carbon dioxide content reduced.

This blood passes into

RIGHT VENTRICLE which pumps it round the lungs to give up some carbon dioxide and to take up some oxygen.

LEFT ATRIUM receives the blood returning from the lungs, its venous blood becomes oxygenated and its carbon dioxide content reduced.

This blood passes into

LEFT VENTRICLE which pumps it round the body to supply the tissues with oxygen and to remove carbon dioxide from the tissues.

McNaught, Callander; Illustrated Physiology, 1998
Cardiac cell contraction

Contraction of cardiac muscle cells is caused by Ca++ ions.

Cardiac cells contain structures called sarcomeres.

Berne, Levi, 1993; Kalbunde 2005

Sarcomeres contain actin and myosin which bind in the presence of Ca++ and slide past each other thus shortening the cell.
Cardiac electrical excitation and coupling with contraction

Electric potential across the cell membrane exists because of charge separation between the inside and the outside of the cell. Charge separation is possible due to the semipermeable nature of the cell membrane.

Charged ions move through the membrane through special channels driven by concentration and electrical gradient. As a result the membrane potential changes in time.

The typical shape of the voltage difference through the membrane is called an action potential (curve 1). Note that the plateau is due to increased Ca++ concentration in the cell (curve 3) which causes cell contraction (curve 2).

McNaught, Callander; Illustrated Physiology, 1998; Petersen (ed), 2006
Propagation of action potentials

The spatial and temporal movement of action potential coordinates the complex mechanical contraction of the heart.

Ionic channels are controlled by voltage. This provides a mechanism for the action potential to change in time and to propagate in space by a diffusion like process.

Extracellular propagation is ensured by gap junctions - proteins protruding two adjacent cell membranes which are freely permeable to ions.

A wave-train of action potentials in one-dimension.

A beating heart – electrical excitation propagates at an speed and in a well-defined path and causes controlled contraction and expansion.
Basis for cardiac excitation equations

The membrane is modelled as a electrical circuit with a capacitor and a resistor in parallel:

\[ C_m \frac{\partial V}{\partial t} + I_{\text{ion}}(V, t) = 0 \]

The current through a channel is given by Ohm's law, where \( m \) is the fraction of open gates of type \( m \) and \( g \) is the maximal conductance:

\[ i = g m (V - V_0) \]

The fraction of open \( m \) gates is given by the rate of change equation:

\[ \frac{\partial m}{\partial t} = \alpha_m (1 - m) - \beta_m m = \frac{\overline{m}(V) - m}{\tau_m(V)} \]

where the alpha-s and beta-s are transition rates.
Detailed voltage-gated model of human atrial tissue
Courtemanche et al., (1998)

\[
\partial_T V = D \left( \partial_X^2 + \kappa \partial_X \right) V - \frac{\left( I_{Na}(V, m, h, j) + \sum'_{I}(V, \ldots) \right)}{C_M},
\]

\[
\partial_T m = \frac{(\overline{m}(V) - m)}{\tau_m(V)},
\]

\[
\partial_T h = \frac{(\overline{h}(V) - h)}{\tau_h(V)},
\]

\[
\partial_T u_a = \frac{(\overline{u_a}(V) - u_a)}{\tau_{u_a}(V)},
\]

\[
\partial_T w = \frac{(\overline{w}(V) - w)}{\tau_{w}(V)},
\]

\[
\partial_T o_a = \frac{(\overline{o_a}(V) - o_a)}{\tau_{o_a}(V)},
\]

\[
\partial_T d = \frac{(\overline{d}(V) - d)}{\tau_d(V)},
\]

\[
\partial_T U = F(V, \ldots)
\]

- Detailed ionic single-cell model designed to fit the experimental data. Well-established in the literature.

- Consists of 21 coupled reaction-diffusion PDEs

- The voltage equation is as a result of various ions passing through the membrane under certain conditions

- The gating variables depend on voltage, concentration of substances etc.
Break-up and self termination: observation in a numerical experiment

- Courtemanche et al. (1998) detailed ionic model of human atrial tissue

- We need to understand not only the propagation of the wave but also its failure: when and under what conditions the spiralling wave will break-up and self-terminate?

- We look for a simplified mathematical model to explain the observed behaviour.
Temporary block of excitability: Standard simplified models of FitzHugh-Nagumo type

FitzHugh-Nagumo equations are a classical model of cell excitability.

\[ \partial_T V = D \partial^2_X V + \varepsilon_V (V - V^3/3 - g), \]
\[ \partial_T g = \varepsilon_g (V + \beta - \gamma g), \]
\[ \varepsilon_g / \varepsilon_V \rightarrow 0+ \]

V – voltage, \( \varepsilon_V \)– excitation parameter

When excitability restored, excitation wave resumes if excited region survived

Temporarily suppressed excitability fails to resume if excited region thinned out to zero

Biktashev. 2002
Temporary block of excitability: Detailed ionic models (Courtemanche et al., 1998)

When excitability restored, excitation wave fails to resume even if the back is still far away from the front!

Temporary suppressed excitability

In a similar way standard simplified models of FitzHugh-Nagumo type fail to reproduce:

- slow re-polarisation,
- slow sub-threshold response,
- fast accommodation,
- variable peak voltage,
- front dissipation.

Need for different simplified models
Relative speed of dynamical variables in Courtemanche's model

***Step 1:** Find out which of the variables are fast and which slow.

**Definition of τ:**

\[ \tau_i(x_1, \ldots, x_N) \equiv |(\partial f_i / \partial x_i)^{-1}| \]

Speed of variables varies with time and at the various phases of the action potential but on the average:

- \(V, m, h, u_a, w, o_a, d\) are **fast**
- The rest of the dynamical variables are considered **slow**
Further non-standard asymptotic properties

Step 2: Take into account any other relevant observations found by numerical experiments.

- $I_{Na}$ is a fast current only during the AP upstroke. In fact it is a “window” current and almost vanishes outside the upstroke region.
- All other currents except $I_{Na}$ are slow during the AP upstroke.

Na gates ($m, h$) are nearly-perfect switches and thus require introduction of small parameters in unusual places.

Biktashev, Suckley 2004
Asymptotic embedding of the detailed model of Courtemanche et al., 1998)

Step 3:
\[
\partial_T V = D \left( \partial_X^2 + \mathcal{K} \partial_X \right) V - \left( \varepsilon^{-1} I_{\text{Na}}(V,m,h,j) + \Sigma'(V,\ldots) \right) \frac{C_M}{C_M},
\]
\[
\partial_T m = \frac{(\overline{m}(V;\varepsilon) - m)}{\varepsilon \tau_m(V)}, \quad \overline{m}(V;\varepsilon) = \begin{cases} 
\theta(V - V_m), & \varepsilon = 0 \\
\overline{m}(V), & \varepsilon = 1,
\end{cases}
\]
\[
\partial_T h = \frac{(\overline{h}(V;\varepsilon) - h)}{\varepsilon \tau_h(V)}, \quad \overline{h}(V;0) = \begin{cases} 
\theta(V_h - V), & \varepsilon = 0 \\
\overline{h}(V), & \varepsilon = 1,
\end{cases}
\]
\[
\partial_T u_a = \frac{(\overline{u_a}(V) - u_a)}{\varepsilon \tau_{u_a}(V)},
\]
\[
\partial_T w = \frac{(\overline{w}(V) - w)}{\varepsilon \tau_w(V)},
\]
\[
\partial_T o_a = \frac{(\overline{o_a}(V) - o_a)}{\varepsilon \tau_{o_a}(V)},
\]
\[
\partial_T d = \frac{(\overline{d}(V) - d)}{\varepsilon \tau_d(V)},
\]
\[
\partial_T U = F(V,\ldots)
\]

Asymptotic embedding: Introduce a small parameter so that in the limit \( \varepsilon \to 1 \) the original model is recovered while in the limit \( \varepsilon \to 0 \) a simpler system is obtained.

Note: The small parameter enters in a non-standard way:
- A variable can be both fast and slow in the same solution,
- Large factor only at some but not all terms in the RHS,
- Non-isolated equilibria in the fast system,
- Discontinuous RHS of the embedded system even if the original is continuous.

The standard theory of FitzHugh-Nagumo like systems is not applicable - alternatives in Biktashev et al., 2007
Application to break-up: a simplified model of the front

- Non-dimensionalize:
  
  \[ t = \frac{T}{\epsilon}, \quad x = \frac{X}{\sqrt{\epsilon D}}, \quad \kappa = \sqrt{\epsilon D} \]

- Take the asymptotic limit
- Discard equations for \( u_a, w, o_a, d \) which decouple
- Arrive at the simplified model for the front

Note:
- Number of equations reduced from 21 to 3!
- Small parameters eliminated – model is not stiff any more!
- RHS significantly simpler!

- \( j \) plays the role of excitation parameter. The value of \( j \) can be found from the slow subsystem.

\[
\partial_t V = \left( \partial_x^2 + \kappa \partial_x \right) V + \overline{\mathcal{I}}_{Na}(V) j h m^3, \\
\partial_t h = \left( \theta(V_h - V) - h \right) / \tau_h(V), \\
\partial_t m = \left( \theta(V - V_m) - m \right) / \tau_m(V),
\]

where

\[
\overline{\mathcal{I}}_{Na}(V) = g_{Na}(V_{Na} - V), \\
\tau_k(V) = (\alpha_k(V) + \beta_k(V))^{-1}, \quad k = h, m, \\
\alpha_h(V) = 0.135 e^{-(V + 80)/6.8} \theta(-V - 40), \\
\beta_h(V) = (3.56 e^{0.079V} + 3.1 \times 10^5 e^{0.35V}) \theta(-V - 40) \\
\quad + \theta(V + 40) (0.13(1 + e^{-(V + 10.66)/11.1}))^{-1}, \\
\alpha_m(V) = \frac{0.32(V + 47.13)}{1 - e^{-0.1(V + 47.13)}}, \\
\beta_m(V) = 0.08 e^{-V/11}, \\
g_{Na} = 7.8, \quad V_{Na} = 67.53, \quad V_h = -66.66, \quad V_m = -32.7.
\]

Simitev, Biktashev 2005
Quality of the simplified model

1) The simplified model reproduces front dissipation at a temporary block.

\[ j = j_1 \quad j_1 < j_{\text{min}} < j_2, \quad j = j_2 \]

2) Quantitative agreement with the detailed model of Courtemanche.

<table>
<thead>
<tr>
<th>Model</th>
<th>Speed</th>
<th>Peak Voltage</th>
<th>Relative Error in Speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>Original</td>
<td>0.28</td>
<td>3.6</td>
<td>0.00%</td>
</tr>
<tr>
<td>Simplified</td>
<td>0.24</td>
<td>2.89</td>
<td>16.00%</td>
</tr>
</tbody>
</table>

Simitev, Biktashev 2005

The new simplified model agrees quantitatively well with the values of the wave speed and the pre-front voltage on the detailed ionic model of Courtemanche.
Travelling waves

Travelling wave ansatz:

\[ F(z) = F(x + ct) \text{ for } F = V, h, m \]

Then:

\[
V'' = (c - \kappa) V' - \overline{I_{Na}}(V) j h m^3,
\]
\[
h' = (c \tau_h(V))^{-1}(\theta(V_h - V) - h),
\]
\[
m' = (c \tau_m(V))^{-1}(\theta(V - V_m) - m),
\]

Indication of well-posedness:

\begin{itemize}
  \item System with \textbf{8 unknown constants} (4\textsuperscript{th} order & c, j, V_a, V_w) but only \textbf{6 boundary conditions}.
  \item The remaining 2 constants can be chosen arbitrary.
  \item Otherwise their values are fixed by the second half of the problem: the slow system
\end{itemize}

Boundary conditions:

\[
V(-\infty) = V_\alpha, \quad V(+\infty) = V_\omega, \\
h(-\infty) = 1, \quad h(+\infty) = 0, \\
m(-\infty) = 0, \quad m(+\infty) = 1.
\]

Advantages:

\begin{itemize}
  \item Conversion from PDE to ODE
  \item Can be solved by standard boundary value problem techniques and numerical schemes.
  \item Immense computational savings.
\end{itemize}

Simitev, Biktashev 2005
An exactly solvable toy model

- Replace functions $I_{Na}(V), \tau_h(V)$ and $\tau_m(V)$ with constants, say, by taking their values at $V=V_m$

- Obtain a piecewise system of linear ODE with constant coefficients

- The equations for $h$ and $m$ decouple and may be solved separately

- The voltage $z \leq \xi$ is homogeneous for

\[ \xi = \frac{1}{(c - \kappa)} \ln \left( \frac{V_m - V_\alpha}{V_h - V_\alpha} \right) \]

and with exponential inhomogeneity for

\[ V(z) = \begin{cases} 
(V_h - V_\alpha) e^{(c-\kappa)z} + V_\alpha, & z \leq \xi, \\
V_\omega - \overline{I_{Na}} j c^2 \tau_h^2 \tau_m^2 \sum_{n=0}^{3} A_n(c,z), & z \geq \xi,
\end{cases} \]

\[ h(z) = \begin{cases} 
1, & z \leq 0, \\
e^{-z/(c \tau_h)}, & z \geq 0,
\end{cases} \]

\[ m(z) = \begin{cases} 
0, & z \leq \xi, \\
1 - e^{(\xi - z)/(c \tau_m)}, & z \geq \xi,
\end{cases} \]

\[ V_\omega = V_m + \overline{I_{Na}} j (c \tau_h \tau_m)^2 e^{-\xi/(c \tau_h)} \sum_{n=0}^{3} \frac{a_n(c)}{\tau_m + n \tau_h}, \]

\[ 0 = (c - \kappa)(V_m - V_\alpha) - \overline{I_{Na}} j c \tau_h \tau_m e^{-\xi/(c \tau_h)} \sum_{n=0}^{3} a_n(c), \]

\[ A_n(c,z) \equiv \frac{a_n(c)}{\tau_m + n \tau_h} \exp \left( \frac{n \xi \tau_h - (\tau_m + n \tau_h) z}{c \tau_h \tau_m} \right) \]

\[ a_n(c) \equiv \binom{3}{n} \frac{(-1)^n}{c(c - \kappa) \tau_h \tau_m + \tau_m + n \tau_h}. \]

Simitev, Biktashev 2005
Of interest are the conditions at which the excitation wave fails to propagate. Thus we seek a relation between the wave speed and the excitation parameter. The dispersion relation cannot be solved for $c$ but can be easily solved for $j$.

$$j = \frac{(V_m - V_\alpha)}{6 I_{Na} \tau_h^4 \tau_m} e^{c \tau_h} \prod_{n=0}^{3} \left( c^2 \tau_h \tau_m + \tau_m + n \tau_h \right)$$

The thick solid lines show the numerical solution of the true simplified model; the thin lines show the above expression for values of $\tau_m$, $\tau_h$ and $\alpha$ corresponding to $V = -28, -30, V_m, -34, -36, -38$, from right to left. In both cases $V_a = -81.18$.

Turning point bifurcation with increase of excitation parameter.

No propagation below the bifurcation point.
The condition for propagation

The excitation waves can propagate only if the excitation of the tissue is larger than some minimal value,

\[ j > j_{\text{min}} \]

- \( j_{\text{min}} \) can be determined as a minimum of the \( j \) as a function of \( c \)

\[
j_{\text{min}}^{(0)} = \frac{(V_m - V_\alpha)}{2I_{\text{Na}}\tau_h} e^{\frac{2\Theta}{\Theta + \sqrt{\Theta^2 + 4\Theta}}} \left( \Theta + 2 + \sqrt{\Theta^2 + 4\Theta} \right)
\]

\[ \Theta = \ln\left(\frac{(V_m - V_\alpha)}{(V_h - V_\alpha)}\right). \]

Minimal value of the excitation as a function of the second free parameter, the pre-front voltage. Green and red lines are more accurate approximations.

Simitev, Biktahev 2005
Precise numerical value for the minimal excitability

The precise numerical value of the excitability necessary for propagation is found as an intersection of the minimal excitability curve and typical action potential solutions.

\[(j_*, V_*) = (0.2975 \pm 0.0015, -72.5 \pm 0.5)\]

Simitev, Biktashev 2005
Confirmation in a numerical experiment

CONDITION:
A spiralling wave in the Courtemanche’s atrial detailed ionic model will break-up whenever and wherever the value of the j-gating variable decreases below the critical value of 0.298.

- Red: voltage
- Blue: j < 0.295
- Yellow: block, at:
  - 740 ms
  - 1120 ms
  - 3740 ms
  - 3860 ms

Simitev, Biktashev 2005
Conclusions

- **Excitation fronts dissipate if not allowed to propagate fast enough**
- Dissipated fronts do not resume if excitability restored
- This is due to $I_{Na}$ and is reproduced by the new simplified model of $I_{Na}$-driven front
- Propagation can be blocked by front dissipation, long before wavelength reduces to zero
- Novel asymptotic approach applied to derive a simplified model
- Analytical conditions for front dissipation derived
- Accurate numerical values also obtained
- Results tested against the detailed ionic model of atrial tissue and excellent agreement achieved