DIFFEOMORPHISM GROUPS OF PRIME 3-MANIFOLDS

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ABSTRACT. Let X be a compact orientable non-Haken 3-manifold modeled on the Thurston geometry Nil. We show that the diffeomorphism group Diff(X) deformation retracts to the isometry group Isom(X). Combining this with earlier work by many authors, this completes the determination the homotopy type of Diff(X) for any compact, orientable, prime 3-manifold X.

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1. INTRODUCTION

For a compact, connected, smooth 3-manifold X, we denote by Diff(X) the group of smooth diffeomorphisms of X equipped with the C^{∞} -topology.

Our goal in this paper is to prove the following:

Theorem 1.1. Let X be a compact, connected, geometrizable 3-manifold modeled on the Thurston geometry Nil, and g_0 be a Nil-metric on X. Then the inclusion $\operatorname{Isom}(X, g_0) \hookrightarrow \operatorname{Diff}(X)$ is a homotopy equivalence.

Combined with results from our previous two papers [BK17, BK19] and work of many other mathematicians [Hat76, Iva76, Iva82, Iva84, Gab01, HKMR12, MS13], Theorem 1.1 completes the project of understanding the topology of Diff(X), when X is a closed, orientable, prime 3-manifold; see [BK17, HKMR12] for references and history.

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We remark that in the setting of Theorem 1.1 the Lie group $\text{Isom}(X, g_0)$ is an extension of a finite group F by a circle S^1 ; it can be characterized using the Seifert structure on X.

The proof of Theorem 1.1 is based on Ricci flow and follows [BK17] closely, except for some input specific to Nil geometry. We refer the reader to the introduction of [BK17] for an outline of the proof.

Together with previous work, we have shown that singular Ricci flow offers a uniform approach to studying diffeomorphism groups of a large class of prime manifolds: spherical space forms, hyperbolic manifolds, $S^2 \times S^1$ and non-Haken manifolds modeled on Nil. We expect that the methods from this paper can be readily adapted to also cover the non-Haken case modeled on $\mathbb{H}^2 \times \mathbb{R}$ and $\widetilde{SL(2,\mathbb{R})}$ and the Haken case modeled on Solv, which were covered by McCullough-Soma [MS13] and Hatcher [Hat76], respectively. We believe that our methods can be even carried further to cover all geometrizable cases; this would be more technical, however, due to the fact that the asymptotic behavior of the Ricci flow is not fully understood in this case (see [Bam18e, Question 1.7]).

2. Preliminaries

In this section we cover some of the background material needed for the proof Theorem 1.1; since the proof follows [BK17] closely, the reader may wish to consult the preliminaries section of [BK17] as well.

2.1. Nil geometry and Nil-structures. We collect some facts about Nil geometry and Nil structures [Sco83].

Thurston's Nil-geometry is the Heisenberg group

equipped with the left invariant Riemannian metric g_{Nil} for which the basis $X_1 := E_{1,2}$, $X_2 := E_{2,3}$, $X_3 := E_{1,3}$ of elementary matrices is orthonormal; here we use the standard identification of the Lie algebra L(Nil) with the space of strictly upper triangular matrices. We have $[X_1, X_2] = X_3$, $[X_1, X_3] = [X_2, X_3] = 0$. In what follows we will use Nil to denote the Lie group or the Riemannian manifold (Nil, g_{Nil}), depending on the context.

The automorphism group of L(Nil) is generated by elements whose matrix with respect to the basis X_1, X_2, X_3 has one of the two forms:

(2.2)
$$\begin{pmatrix} A & 0 \\ 0 & \det A \end{pmatrix}$$
(2.3)
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ b_1 & b_2 & 1 \end{pmatrix}$$

for some $A \in \operatorname{GL}(2,\mathbb{R})$, $b_1, b_2 \in \mathbb{R}$. Automorphisms as in (2.2) with $A = \lambda$ id are (Carnot) dilations. The affine group of Nil is the group Aff(Nil) generated by the left translations and the automorphisms; this is the semidirect product of the translations with the automorphism group Aut(Nil). Every $\Phi \in \operatorname{Aff}(\operatorname{Nil})$ carries left invariant vector fields to left invariant vector fields, and we denote by $D\Phi \in \operatorname{Aut}(L(\operatorname{Nil}))$ the associated Lie algebra automorphism. The isometry group Isom(Nil) is the set of $\Phi \in \operatorname{Aff}(\operatorname{Nil})$ such that $D\Phi$ is as in (2.2) for some $A \in O(2)$. Carnot dilations normalize Isom(Nil). Any left-invariant metric g on Nil is homothetic to g_{Nil} ; more specifically, there exists an automorphism $\phi \in \operatorname{Aut}(\operatorname{Nil})$ and some $\lambda > 0$ such that $g = \lambda^2 \phi^* g_{\operatorname{Nil}}$.

We identify the abelianization Nil / $\exp(\mathbb{R}X_3)$ with \mathbb{R}^2 . Any automorphism of Nil preserves the center $\exp(\mathbb{R}X_3)$, and hence any $\Phi \in \operatorname{Aff}(\operatorname{Nil})$ induces an affine map $\mathbb{R}^2 \to \mathbb{R}^2$. This yields an Aff(Nil)-equivariant fibration Nil $\to \mathbb{R}^2$; this is also an Isom(Nil)-equivariant fibration, when we restrict to Isom(Nil) \subset Aff(Nil).

A **Nil-structure** on a manifold X is a Riemannian metric g locally isometric to Nil; we say that X is **modeled on** Nil if it admits a Nil-structure. When X is compact and connected, then the universal cover $(\widetilde{X}, \widetilde{g})$ is isometric to Nil, and up to isometry we have $X = \text{Nil}/\Gamma$ for some lattice $\Gamma \subset \text{Isom}(\text{Nil})$ acting freely on Nil. Since Aff(Nil) \curvearrowright Nil is orientation preserving, Nil/ Γ is orientable.

Any lattice $\Gamma \subset \text{Isom}(\text{Nil})$ has a finite index translation subgroup [Aus60, Rag72]. Any isomorphism $\Gamma_1 \to \Gamma_2$ between two lattices $\Gamma_1, \Gamma_2 \subset \text{Isom}(\text{Nil})$ is induced by (conjugation by) some $\Phi \in \text{Aff}(\text{Nil})$ [Aus60].

If $\Gamma \subset \text{Isom}(\text{Nil})$ is a lattice acting freely on Nil, then as above we obtain an isometric action $\Gamma \curvearrowright \mathbb{R}^2$, and a quotient Euclidean orbifold $\mathbb{R}^2/\overline{\Gamma}$, where $\overline{\Gamma}$ is the image of Γ in $\text{Isom}(\mathbb{R}^2)$. The abelianization fibration $\text{Nil} \to \mathbb{R}^2$ is Γ -equivariant, and descends to a Seifert fibration $\text{Nil}/\Gamma \to \mathbb{R}^2/\overline{\Gamma}$ over a flat orbifold whose singular points are only of cone type (i.e., there are no reflectors or corner reflectors). By conjugating Γ by a Carnot dilation we may arrange that Nil/Γ has unit volume.

An orientable 3-manifold X is called **Haken** if it is prime and contains an embedded, 2-sided, incompressible surface (i.e., a surface $Y \subset X$ of nonpositive Euler characteristic such that $\pi_1(Y) \to \pi_1(X)$ is injective).

Lemma 2.4. Suppose X is a compact connected geometrizable non-Haken 3-manifold modeled on Nil. Then it has a unique unit volume Nil-structure, up to isometry.

Proof. Let $\Gamma := \pi_1(X)$, and consider two isometric covering group actions $\Gamma \curvearrowright^{\rho,\rho'} \cap^{\gamma'}$ Nil with quotients diffeomorphic to X and of unit volume; we denote by $\Gamma \curvearrowright^{\overline{\rho},\overline{\rho'}} \mathbb{R}^2$ the induced isometric actions on \mathbb{R}^2 , and $\Gamma \curvearrowright^{D\rho,D\rho'} L(\text{Nil})$, $\Gamma \curvearrowright^{D\overline{\rho},D\overline{\rho'}} \mathbb{R}^2$ the associated linear actions obtained by taking "linear parts".

Claim. The orthogonal actions $D\overline{\rho}$, $D\overline{\rho}'$ are irreducible.

Proof. Since X is non-Haken, the quotient orbifold $\mathbb{R}^2/\overline{\rho}(\Gamma)$ contains no 2-sided, embedded, closed geodesics. By the classification of flat orbifolds, $\mathbb{R}^2/\overline{\rho}(\Gamma)$ must be a 2-sphere with 3 cone points, which implies irreducibility of $D\overline{\rho}$.

Alternatively, we can argue as follows: Suppose $D\overline{\rho}$ is reducible, so each element of Γ acts as a reflection, a rotation by π or trivially. If there is an element $g \in \Gamma$ that acts by a reflection, then $\overline{\rho}(g)$ must be a glide reflection; let $\gamma \subset \mathbb{R}^2$ be its axis. If there is no such element, then let $\gamma \subset \mathbb{R}^2$ be a line that projects to a circle under the quotient map $\mathbb{R}^2 \to \mathbb{R}^2/\overline{\rho}(\Gamma)$. In both cases, a generic line $\gamma' \subset \mathbb{R}^2$ parallel to γ projects to a 2-sided, embedded, geodesic in $\mathbb{R}^2/\overline{\rho}(\Gamma)$, which is a contradiction.

The proof for $D\overline{\rho}'$ is the same.

It follows from the Claim that the actions $\Gamma \xrightarrow{D\rho, D\rho'} L(\text{Nil})$ restricted to the 2dimensional subspace X_3^{\perp} , are irreducible. By [Aus60] — the statement and proof of which are variations on the classical Bieberbach theorem on crystallographic groups — there is an affine mapping $\Phi : \text{Nil} \to \text{Nil}$ conjugating ρ to ρ' . Since $D\Phi : L(\text{Nil}) \to$ L(Nil) is equivariant with respect to the linear actions $D\rho$, $D\rho'$, it preserves X_3^{\perp} , and induces a conformal mapping $X_3^{\perp} \to X_3^{\perp}$; hence $D\Phi$ has a matrix as in (2.2) where $A = \lambda B$ for some $\lambda > 0$ and $B \in O(2)$, and so det $D\Phi = \lambda^4$. Now $\text{vol}(\text{Nil}/\rho(\Gamma)) =$ $\text{vol}(\text{Nil}/\rho'(\Gamma))$ implies that $|\det D\Phi| = 1$, so $\lambda = 1$ and Φ is an isometry.

2.2. Spaces of maps and metrics. If X is a smooth manifold, we let Met(X) denote the set of smooth Riemannian metrics on X equipped with the C^{∞} -topology. Now assume that X is compact, connected and modeled on Nil. Let $Met_{Nil}(X)$ denote the subspace of Met(X) consisting of unit volume Riemannian metrics isometrically covered by Nil (this is nonempty as mentioned above). We will need the following result:

Lemma 2.5. Suppose X is non-Haken, and pick $g_X \in Met_{Nil}(X)$. Then:

- There is a fibration $\operatorname{Diff}(X) \to \operatorname{Met}_{\operatorname{Nil}}(X)$ with fiber homeomorphic to $\operatorname{Isom}(X, g_X)$.
- $\operatorname{Diff}(X)$ and $\operatorname{Met}_{\operatorname{Nil}}(X)$ are homotopy equivalent to CW complexes.
- Met_{Nil}(X) is contractible if and only if the inclusion $\text{Isom}(X, g_X) \to \text{Diff}(X)$ is a homotopy equivalence.

This follows from Lemma 2.4 as in the proof of [BK17, Lemma 2.2].

2.3. Singular Ricci flows. We will use the terminology associated to the concept of singular Ricci flow, as defined in [BK17]; see also [KL17, BK]. For convenience, we call a Ricci flow spacetime $(\mathcal{M}, \mathfrak{t}, \partial_{\mathfrak{t}}, g)$, which we often abbreviate by \mathcal{M} , a singular Ricci flow if it is an $(\epsilon_{\operatorname{can}}, r)$ -singular Ricci flow according to [BK17, Definition 2.13], for $\epsilon_{\operatorname{can}} > 0$ as in [BK17, Theorem 2.14] and for some function $r : [0, \infty) \to (0, \infty)$. Recall that for every closed, 3-dimensional Riemannian manifold (\mathcal{M}, g) there is a singular Ricci flow \mathcal{M} whose initial time-slice (\mathcal{M}_0, g_0) is isometric to (\mathcal{M}, g) and this flow is unique up to isometry (existence was established in [KL17] and uniqueness in [BK]). In contrast to Perelman's Ricci flow with surgery [Per03], surgeries in \mathcal{M} are not performed at discrete time-steps; instead, change of topology occurs at an infinitesimal scale.

In the following, we collect the necessary topological and geometric properties of singular Ricci flows that will be needed in this paper.

If M is a manifold, then a **punctured copy of** M is a manifold diffeomorphic to $M \setminus S$, where $S \subset M$ is a finite (possibly empty) subset. Note that if M_1 , M_2 are compact 3-manifolds, then punctured copies of M_1 and M_2 can be diffeomorphic only if M_1 is diffeomorphic to M_2 . This follows from the fact that if D, D' are 3-disks where $D' \subset \text{Int } D$, then $\overline{D \setminus D'}$ is diffeomorphic to $S^2 \times [0, 1]$. Hence the notion of "filling in" punctures is well-defined.

A compact Riemannian manifold (M, g) is called ϵ -almost-flat if

$$\sup_{M} |\operatorname{Rm}| (\operatorname{diam}(M,g))^2 \le \epsilon.$$

Theorem 2.6 (Structure of singular Ricci flows). Let (X, g_0) be a compact Riemannian 3-manifold, and let \mathcal{M} be a singular Ricci flow with initial time slice $\mathcal{M}_0 = (X, g_0)$. Then:

- (1) For every $t \in [0, \infty)$, each component $C \subset \mathcal{M}_t$ is a punctured copy of some compact 3-manifold.
- (2) Let $\mathcal{M}_t^{\text{fill}}$ be the (possibly empty) 3-manifold obtained from \mathcal{M}_t by filling in the punctures and throwing away the copies of S^3 . Then $\mathcal{M}_t^{\text{fill}}$ is a compact 3-manifold, i.e., all but finitely many components of \mathcal{M}_t are punctured copies of S^3 . Furthermore, for every $t_1 < t_2$ the prime decomposition of $\mathcal{M}_{t_2}^{\text{fill}}$ is part of the prime decomposition of $\mathcal{M}_{t_1}^{\text{fill}}$. Hence there are only finitely many times at which the prime decomposition of $\mathcal{M}_t^{\text{fill}}$ changes.
- (3) $\mathcal{M}_t^{\text{fill}}$ is irreducible and aspherical for large t, depending only on the following bounds on the geometry of \mathcal{M}_0 : upper bounds on the curvature and volume, and a lower bound on the injectivity radius.
- (4) If X is modeled on Nil, then for every $\epsilon > 0$ there is a time $T(g_0, \epsilon) < \infty$ such that \mathcal{M} restricted to $[T, \infty)$ is non-singular and (\mathcal{M}_t, g_t) is ϵ -almost-flat for all $t \geq T$. Here $T(g_0, \epsilon)$ may be chosen to depend continuously on the initial metric g_0 in the C^2 -topology.

Proof. Assertions (1)–(3) are a restatement of [BK17, Theorem 2.16].

To see Assertion (4), note first that the corresponding statement (excluding the last sentence) holds for Ricci flow with surgery due to [Bam18e, Theorem 1.4] and Lemma 2.7 below, assuming that surgeries are performed sufficiently precisely. We will argue that the proof of [Bam18e, Theorem 1.4] also works for singular Ricci flows. This is true in general, but we focus on the case in which (\mathcal{M}_0, g_0) is a non-Haken Nil-manifold, because some of the discussion simplifies in this case.

Note first that for large times we still obtain a thick-thin decomposition $\mathcal{M}_t = \mathcal{M}_t^{\text{thick}} \cup \mathcal{M}_t^{\text{thin}}$, as described in [Per03, 7.4] or [KL08, Proposition 90.1], [Bam18a, Proposition 3.16], where $\mathcal{M}_t^{\text{thick}}$ is diffeomorphic to a hyperbolic manifold whose cuspidal tori are incompressible within \mathcal{M}_t . This can be seen either directly by reproving the necessary estimates in the setting of singular Ricci flows or by approximating \mathcal{M} with Ricci flows with surgery whose surgery parameter goes to zero. For the latter approach see the end of the proof of [BK17, Theorem 2.16]. Since, by assumption, \mathcal{M}_0 , and thus also $\mathcal{M}_t^{\text{fill}}$, does not have any hyperbolic pieces in its geometric decomposition, we must have $\mathcal{M}_t^{\text{thick}} = \emptyset$ for large t.

Next, we can decompose $\mathcal{M}_t = \mathcal{M}_t^{\text{thin}}$ for large t, as explained in [Bam18d, Proposition 2.1]. Note that this result is purely Riemannian, hence it can be directly applied in the setting of singular Ricci flows at non-singular times, which are dense in $[0, \infty)$ [KL20]. The subsequent study of the local collapse and the topological discussion in [Bam18d, Section 2] also applies to non-singular time-slices of \mathcal{M} .

Let us now follow the lines of the proof of [Bam18e, Theorem 1.1] in [Bam18d, line 1054], Case 2 (which is significantly simpler than Case 1). Apart from what we have already discussed, this proof relies on the following additional ingredients:

- The curvature bound from [Bam18a, Proposition 4.4]. The proof of this bound can be translated easily to the setting of singular Ricci flows. Alternatively, it can again be obtained by approximating \mathcal{M} with Ricci flows with surgery and passing to the limit.
- The existence of a family of piecewise smooth maps $f_{k,t} : V \to \mathcal{M}_t$ of controlled area, where the simplicial complex V and the homotopy class of $f_{k,t}$ are constructed in [Bam18c, Section 3.7]. Note that [Bam18c] is purely topological and makes no reference to Ricci flows at all and [Bam18b] only concerns classical Ricci flows, except for [Bam18b, Proposition 5.5], which easily generalizes to singular Ricci flows.

The remainder of the arguments in Case 2 of the proof of [Bam18e, Theorem 1.1] also hold for non-singular time-slices of \mathcal{M} , showing that there is some time $T' < \infty$ such that $\mathcal{M}_{[T',\infty)}$ can be described by a conventional Ricci flow without singularities and that we have a curvature bound of the form $|\text{Rm}| \leq Ct^{-1}$.

After time-shifting $\mathcal{M}_{[T',\infty)}$, we can finally apply [Bam18e, Theorem 1.4] and Lemma 2.7 below to conclude the proof of the first part of Assertion (4).

It remains to establish the last statement concerning continuity of T. To see this, we use the stability theorem for singular Ricci flows, [BK, Theorem 1.5] to conclude

that if $\epsilon_1 > 0$ there is a $\delta(g_0, \epsilon_1) > 0$, which depends continuously on the initial metric g_0 in the C^2 -topology, such that (\mathcal{M}'_T, g'_T) is ϵ_1 -almost-flat for any singular flow \mathcal{M}' with initial time-slice isometric to (X, g'_0) if $||g'_0 - g_0||_{C^2} < \delta$. By Theorem 2.8 below, for $\epsilon_1 = \epsilon_1(\epsilon) > 0$, we obtain that (\mathcal{M}'_t, g'_t) is ϵ -almost-flat for all $t \geq T$. This implies that we may choose T to depend continuously on the initial metric, for example, using a partition of unity.

Lemma 2.7. Suppose that X is a compact, non-Haken manifold modeled on Nil and $\pi : \hat{X} \to X$ is a finite covering. Then for any $K < \infty$ there is an $\epsilon(\pi, K) > 0$ such that there is no Riemannian metric g on X with the following properties:

- (1) $|\operatorname{Rm}_g| \leq K$
- (2) $\operatorname{diam}(\widehat{X}, \widehat{g} := \pi^* g) \ge \epsilon^{-1}$
- (3) There is a Riemannian metric \hat{g}' on \hat{X} such that $(1 \epsilon)\hat{g} \leq \hat{g}' \leq (1 + \epsilon)\hat{g}$ and such that the following holds: We can represent \hat{X} as the total space of a T^2 -fibration over S^1 such that in a fibered neighborhood of each T^2 -fiber there is a free, \hat{g}' -isometric T^2 -action whose orbits are the T^2 -fibers of this fibration and those orbits have diameter $\leq \epsilon$.

Proof. Let $\alpha > 0$ be a small constant whose value we will determine in the course of the proof. Applying [CFG92] to g yields a $(\rho(\alpha, K), k(\alpha))$ -round metric g'' on X with $(1-\alpha)g \leq g'' \leq (1+\alpha)g$ together with a nilpotent Killing structure \mathfrak{N} , whose orbits have diameter $< \alpha$. The lift $\widehat{g}'' := \pi^* g''$ is (ρ, Ck) -round, it is compatible with the pullback $\widehat{\mathfrak{N}} := \pi^* \mathfrak{N}$ and has orbits of diameter $\langle C\alpha$, where C may depend on $\pi : \hat{X} \to X$. Note that we still have $(1 - \alpha)\hat{g} \leq \hat{g}'' \leq (1 + \alpha)\hat{g}$ and thus $(1 - 2\alpha)\hat{g}' \leq \hat{g}'' \leq (1 + 2\alpha)\hat{g}'$ for small enough ϵ . So if ϵ is chosen small enough, then the orbits $\widehat{\mathcal{O}}_p$ of $\widehat{\mathfrak{N}}$ cannot be 3-dimensional, by Assumption (2), or 0 or 1-dimensional, by Assumption (3). So all orbits must by 2-dimensional and therefore isometric to a flat 2-torus or a Klein bottle. Moreover, these orbits must lie close enough and be homotopic to the orbits of the local isometric T^2 -action of \hat{g}' for sufficiently small α, ϵ . We can now exclude orbits $\widehat{\mathcal{O}}_p$ diffeomorphic to the Klein bottle, since any such orbit has a neighborhood that is diffeomorphic to a \mathbb{Z}_2 -quotient of $T^2 \times [-1, 1]$, equivariant with respect to the corresponding T^2 -action. So the orbits $\widehat{\mathcal{O}}_p$ are all 2-tori and form a fibration of \widehat{X} over a circle. On the other hand, by construction, we have $\pi(\widehat{\mathcal{O}}_p) = \mathcal{O}_{\pi(p)}$ for any $p \in \widehat{X}$. So the orbits \mathcal{O}_p of (X, g'') must again be 2-dimensional and, therefore, generic orbits \mathcal{O}_p must be 2-tori that are finitely covered by incompressible 2-torus orbits $\widehat{\mathcal{O}}_p$ of $(\widehat{X}, \widehat{g}'')$. This, however, contradicts our assumption that X is non-Haken.

The following theorem is a uniform version of the main result in [Guz08]; this slightly improved statement can be easily extracted from the proof in [Guz08]. We have also included a proof for the reader's convenience.

Theorem 2.8 ([Guz08]). For every $\epsilon > 0$ there exists $\delta = \delta(\epsilon, n) > 0$ such that Ricci flow starting from any δ -almost-flat n-manifold is immortal and ϵ -almost-flat for all $t \ge 0$.

Theorem 2.8 follows immediately by taking $\delta := C^{-1} \min(\epsilon_0, \epsilon)$ where ϵ_0 and C are as in Lemma 2.9 below, and applying that lemma iteratively on time intervals $[T_{j-1}, T_j]$ where $T_j = T_{j-1} + AK_{T_{j-1}}^{-1}$; note that intervals $[T_{j-1}, T_j]$ grow at least geometrically by Assertion (4) of the lemma.

Lemma 2.9. There exist $\epsilon_0(n) > 0$, $A(n), C(n) < \infty$ with the following property. Suppose that $(M, (g_t)_{t \in [0,T)})$ is a Ricci flow on a compact, n-manifold with ϵ -almost-flat initial condition (M, g_0) for some $\epsilon \leq \epsilon_0$; here $T \leq \infty$ is chosen maximal. Then for $K_t := \sup_M |\operatorname{Rm}_{g_t}|$ we have, assuming that $K_0 > 0$:

(1) $T > AK_0^{-1}$. (2) (M, g_t) is $C\epsilon$ -almost-flat for all $t \in [0, AK_0^{-1}]$. (3) (M, g_t) is $\frac{\epsilon}{2}$ -almost-flat for $t = AK_0^{-1}$. (4) $K_t \leq \frac{1}{2}K_0$ for $t = AK_0^{-1}$.

Proof. We need the following statement.

Claim. There exist $A'(n), C'(n) < \infty$ with the following property. Suppose that $(M^*, (g_t^*)_{t \in [0,T^*)})$ is a maximal Ricci flow through left-invariant metrics on a simply connected, nilpotent Lie group with $|\operatorname{Rm}_{g_0^*}| = 1$. Then $T^* = \infty$ and the following is true:

- (1) $|\operatorname{Rm}_{g_t^*}| \le C'$ and $|\operatorname{Rm}_{g_t^*}|g_t^* \le C'g_0^*$ for all t > 0.
- (2) $|\operatorname{Rm}_{g_t^*}| \leq \frac{1}{8}$ and $|\operatorname{Rm}_{g_t^*}| g_t^* \leq \frac{1}{32} g_0^*$ for all $t \geq A'$.

Proof. This is essentially the content of [Guz08, Theorem 2.7], which is based on work of Heber and Lauret [Heb98, Lau01]. If n = 3, the case of interest for this paper, then the argument is much simpler. Up to isomorphism, there are only two 3-dimensional simply connected Lie groups: \mathbb{R}^2 and Nil. The case $M' = \mathbb{R}^2$ is trivially true and the case M' = Nil follows from a simple computation, see for example [IJ92].

Fix A', C' according to the Claim and suppose that the lemma was false for A := 16C'A' + 1 and C := 16C'. Choose counterexamples $(M_i, (g_{i,t})_{t \in [1,T_i)})$ for a sequence $\epsilon_i \to 0$. By parabolic rescaling, we may assume that $\sup_{M_i} |\operatorname{Rm}_{g_{i,0}}| = 1$. By applying the maximum principle to $|\operatorname{Rm}|$, we obtain a $\tau \in (0, 1]$ such that

(2.10)
$$|\operatorname{Rm}_{g_{i,t}}| < 2, \quad \operatorname{diam}(M, g_{i,t}) < 2 \operatorname{diam}(M, g_{i,0}) \quad \text{for all} \quad t \in [0, \tau].$$

Choose $T^* \leq \infty$ maximal with the property that for any $T' < T^*$ there is a subsequence such that we have $T' < T_i$ and $\sup_{M_i,t \in [0,T']} |\operatorname{Rm}_{g_{i,t}}| < C(T')$ for some uniform $C(T') < \infty$. By a simple distance-distortion estimate, we have $\sup_{t \in [0,T']} \operatorname{diam}(M, g_{i,t}) \to 0$. So, after passing to a diagonal subsequence, the universal covers of the flows $(M_i, (g_{i,t})_{t \in (0,T^*)})$, pointed at arbitrary points, converge to a maximal Ricci

flow of the form $(M^*, (g_t^*)_{t \in (0,T^*)})$, which is invariant under a transitive action of a nilpotent group; see [Guz08] for details. By the Claim we have $T^* = \infty$. Set $K_{\tau}^{\infty} := \sup_{M^*} |\operatorname{Rm}_{g_{\tau}^*}| \leq 2$.

Case 1: $K^{\infty}_{\tau} = 0$ In this case $(M^*, (g^*_t)_{t \in [\tau, T^*)})$ is flat and we obtain a contradiction for large i.

Case 2: $K_{\tau}^{\infty} \leq (16C')^{-1}$ Consider the time-shifted flow $(M^*, (g_{t-\tau}^*)_{t\geq 0})$. Rescaling this flow parabolically by the factor K_{τ}^{∞} yields a Ricci flow that satisfies the assumptions of the Claim. Assertion (1) of the Claim provides geometric bounds, which imply that the original flow $(M^*, (g_t^*)_{t\geq 0})$ satisfies

(2.11)
$$|\operatorname{Rm}_{g_t^*}| \le C' K_{\tau}^{\infty}, \qquad |\operatorname{Rm}_{g_t^*}| g_t^* \le C' K_{\tau}^{\infty} g_{\tau}^*$$

for all $t \geq \tau$. Let us now argue that Assertions (1)–(4) of the lemma hold for large i, which will give us the desired contradiction. Assertion (1) holds since $T^* = \infty$. Assertion (2) holds for $t \in [0, \tau]$ due to (2.10), which implies that $(M, g_{i,t})$ is 8ϵ -almost-flat. To see Assertion (2) for $t \geq \tau$, we use the second bound in (2.11) to deduce that for large i the almost-flatness increases by at most a factor of 2C' between the times τ and t. Next, note that by (2.10) we get that $(M, g_{i,\tau})$ is even $4K^{\infty}_{\tau}\epsilon$ -almost-flat for large i, so by the same argument as before, we obtain that $(M, g_{i,t})$ is even $8C'K^{\infty}_{\tau}\epsilon$ -almost flat. Since $8C'K^{\infty}_{\tau} \leq \frac{1}{2}$, this implies Assertion (3) for large i. Assertion (4) follows from the first bound in (2.11) for large i since $C'K^{\infty}_{\tau} \leq \frac{1}{16}$.

Case 3: $K_{\tau}^{\infty} > (16C')^{-1}$ The argument is similar to that in Case 2. Assertions (1) and (2) of the lemma follow via the previous argument, since they did not depend on the bound for K_{τ}^{∞} . To see the remaining assertions, we apply the Claim as in Case 2, but use Assertion (2), to obtain that

(2.12)
$$|\operatorname{Rm}_{g_t^*}| \le \frac{1}{8} K_{\tau}^{\infty} \le \frac{1}{4}, \qquad |\operatorname{Rm}_{g_t^*}| g_t^* \le \frac{1}{32} K^{\infty} g_{\tau}^*$$

for $t \geq \tau + A'(K_{\tau}^{\infty})^{-1}$. Note that by the choice of A, these bounds hold for t = A. As in the previous case, we find that $(M, g_{i,\tau})$ is 8ϵ -almost flat and the second bound in (2.12) implies that for large i the almost-flatness decreases by a factor of at most $\frac{1}{16}$ between the times τ and A. This implies Assertion (3). Assertion (4) follows directly from the first bound in (2.12) for large i.

2.4. Improving almost Nil-metrics. In the following, let X be a closed 3-manifold modeled on Nil. We will show that the metrics obtained in Theorem 2.6(4) can be canonically improved to Nil-structures. The following lemma may be compared with [BK17, Remarks 3.4, 6.2].

Lemma 2.13. There is an $\epsilon_0(X) > 0$ with the following property. Consider the subset $\mathcal{U}_{\epsilon_0} \subset \operatorname{Met}(X)$ of ϵ_0 -almost-flat metrics. There is a continuous map $\Psi : \mathcal{U}_{\epsilon_0} \to \operatorname{Met}_{\operatorname{Nil}}(X)$ such that if g is a deformation of a metric $g^* \in \operatorname{Met}_{\operatorname{Nil}}(X)$ by the Ricci flow, then $\Psi(g) = g^*$.

Proof. Fix some $g \in \mathcal{U}_{\epsilon_0}$. We provide a construction for the metric $\Psi(g) \in \operatorname{Met}_{\operatorname{Nil}}(X)$, which depends continuously on g. By replacing g with $\sup_X |\operatorname{Rm}_q| g$, we may assume

that $\sup_X |\operatorname{Rm}_g| = 1$. Next, we may evolve g via the Ricci flow for some uniform time, using Theorem 2.8, to obtain a metric $g' \in \mathcal{U}_{\epsilon_0}$ with

(2.14)
$$|\nabla^m \operatorname{Rm}_{g'}| \le C_m,$$

for some uniform constants $C_m < \infty$. It is clear that g' depends continuously on g.

For notational simplicity we replace q with q'.

Let $\pi: (\widehat{X}, \widehat{g}) \to (X, g)$ be the finite normal covering corresponding to the translation subgroup of $\pi_1(X) \subset \text{Isom}(\text{Nil})$ and denote by $G \curvearrowright \widehat{X}$ the action by the finite deck-transformation group. Identify $H^1(\widehat{X};\mathbb{R})\cong\mathbb{R}^2$ with the space \mathcal{H}^1 of harmonic 1-forms via de Rham cohomology. Consider the inner product (\cdot, \cdot) on \mathcal{H}^1 defined by

$$(\alpha_1, \alpha_2) := \frac{1}{\operatorname{vol}(\widehat{X}, \widehat{g})} \int_{\widehat{X}} \langle \alpha_1, \alpha_2 \rangle \, d\widehat{g}, \qquad \alpha_1, \alpha_2 \in \mathcal{H}^1.$$

Let (Y^2, g_Y) be the flat torus obtained by the quotient

$$(\mathcal{H}^1)^*/H_1(X;\mathbb{Z}) \cong H_1(X;\mathbb{R})/H_1(X;\mathbb{Z}),$$

equipped with the affine metric induced by (\cdot, \cdot) . We now construct a map $\phi : \widehat{X} \to Y$ as follows. Fix some $p \in \hat{X}$. For any $q \in \hat{X}$ consider a 1-chain $\gamma \subset \hat{X}$ with $\partial \gamma = q - p$, which is unique up to a representative of $H_1(\widehat{X};\mathbb{Z})$. Consider the element $h \in (\mathcal{H}^1)^*$ with the property that $h(\alpha) = \alpha(\gamma)$ for any $\alpha \in \mathcal{H}^1$ and define $\phi(q)$ to be the class of h in $(\mathcal{H}^1)^*/H_1(\widehat{X};\mathbb{Z}).$

(1) $\phi: \widehat{X} \to Y$ is smooth and its differential is given by Claim.

$$d\phi_q: T_q\widehat{X} \longrightarrow T_{\phi(q)}Y \cong (\mathcal{H}^1)^*, \qquad v \longmapsto (\alpha \longmapsto \alpha(v))$$

- (2) ϕ induces an isomorphism $H_1(\widehat{X}; \mathbb{Z}) \to H_1(Y; \mathbb{Z})$.
- (3) There is an isometric action $G \curvearrowright Y$ for which ϕ is equivariant.
- (4) If $\epsilon_0 \leq \overline{\epsilon}_0(\widehat{X})$, then ϕ is a submersion whose fibers are circles. (5) If $(\widehat{X}, \lambda^{-2}\widehat{g}) = \operatorname{Nil}/\widehat{\Gamma}$ for some $\lambda > 0$, then ϕ lifts to the abelianization fibration.

Proof. Assertions (1), (2) are clear by construction. For Assertion (3) note that a different choice of basepoint p leads to a map of the form $\phi' = \psi \circ \phi$ for some isometry $\psi: (Y, q_Y) \to (Y, q_Y).$

To see the first part of Assertion (4) we argue by contradiction. So assume that for a sequence $\epsilon_{0,i} \to 0$ there are metrics \hat{g}_i such that none of the induced maps $\phi_i: (\widehat{X}, \widehat{g}_i) \to (Y_i, g_{Y_i})$ are submersions. By (2.14) we have diam $(\widehat{X}, \widehat{g}_i) \to 0$. By Assertion (1) there must be non-zero harmonic 1-forms α_i on $(\widehat{X}, \widehat{g}_i)$ that vanish at some point $q_i \in \widehat{X}$. Without loss of generality, we may assume that $\sup_{\widehat{X}} |\alpha_i| = 1$. Now consider the pullbacks $\tilde{\alpha}_i$, \tilde{g}_i of g_i and α_i via the exponential map based at q_i . Due to standard gradient estimates and the curvature bounds, we obtain a uniform bound of the form $|\nabla \widetilde{\alpha}_i| \leq C$ in a fixed ball around the origin. So $|\nabla \alpha_i| \leq C$ on X for large *i*. This, however, contradicts the fact that $\sup_{\widehat{X}} |\alpha_i| = 1$ and $|(\alpha_i)_{q_i}| = 0$ for large *i*. Thus we may assume that ϕ is a submersion; the fact that the fibers of ϕ are connected follows from Assertion (2), for example, via the long exact homotopy sequence.

For Assertion (5) note that any constant 1-form on \mathbb{R}^2 lifts to a harmonic 1-form on (Nil, $\lambda^2 g_{\text{Nil}}$) via the abelianization map Nil $\rightarrow \mathbb{R}^2$. Any such lift descends to a harmonic form on $(\widehat{X}, \widehat{g})$. Combining this with Assertion (1) implies Assertion (5). \Box

Consider now the S¹-fibers of ϕ . For any $q \in \widehat{X}$ let $\ell(q)$ be the length of the S¹-fiber through q. These fibers represent a generator of the center in $\pi_1(\hat{X})$. Fixing such a generator determines a unique orientation on the fibers. Let now V be the uniquely defined vector field that is tangent to these fibers, satisfies $|V| = \ell$ and is positively oriented. Then the flow of V induces a principal S^1 -bundle structure on \widehat{X} . We obtain a principal connection θ on this bundle by averaging $\widehat{q}(\ell^{-1}V, \cdot)$ via the S¹-action. Denote its curvature 2-form by $\omega \in \Omega^2(Y)$. Let $\omega' \in \Omega^2(Y)$ be the parallel 2-form cohomologous to ω , and let $\theta' = \theta + \phi^* \overline{\theta}$, where $\overline{\theta}$ is the unique element of $\Omega^1(Y)$ that is L^2 -orthogonal to $\ker(d:\Omega^1(Y)\to\Omega^2(Y))$ and satisfies $d\overline{\theta}=\omega'-\omega$. Let $\overline{U}_1, \overline{U}_2$ be a parallel orthonormal frame on Y, and for a > 0 we let \widehat{g}_a be the Riemannian metric on \widehat{X} such that $U_1, U_2, [U_1, U_2]$ are orthonormal, where U_1, U_2 are horizontal lifts with respect to the connection θ' of $a\overline{U}_1, a\overline{U}_2$, respectively. Let $\overline{a} > 0$ be the unique choice of a such that the volume of $\hat{g}_{\overline{a}}$ equals the order of the normal covering $\widehat{X} \to X$. Note that $\widehat{g}_{\overline{a}}$ is invariant under the action of the deck group of the covering $\widehat{X} \to X$, and therefore it descends to a metric on X, which we declare to be $\Psi(q).$

By construction and the Claim, $\Psi(g)$ depends continuously on g. To see the last statement, observe that $(\widehat{X}, \widehat{g}^*)$ is isometric to a quotient of Nil by a lattice $\widehat{\Gamma} \subset$ Isom(Nil); in the following we identify $(\widehat{X}, \widehat{g}^*) = \operatorname{Nil}/\widehat{\Gamma}$. The Ricci flow $(g_{\operatorname{Nil},t})_{t\geq 0}$ starting from g_{Nil} preserves the symmetries of g_{Nil} and descends to a flow on $\operatorname{Nil}/\widehat{\Gamma}$. Due to the preservation of symmetries, the left-invariant vector fields X_1, X_2, X_3 on Nil from Subsection 2.1 remain orthogonal and satisfy $g_{\operatorname{Nil},t}(X_1, X_1) = g_{\operatorname{Nil},t}(X_2, X_2)$. So by the discussion in Subsection 2.1, we obtain that $g_{\operatorname{Nil},t} = \lambda_t^2 \psi_t^* g_{\operatorname{Nil}}$ for some family of Carnot dilations ψ_t and scalars $\lambda_t > 0$. Combining this with Assertion (5) of the Claim, we obtain that the map $\phi : \operatorname{Nil}/\widehat{\Gamma} \to \mathbb{R}^2/\widehat{\Gamma}$, constructed with respect to any $g_{\operatorname{Nil},t}$, is the standard Seifert fibration, which lifts to the abelianization map Nil $\to \mathbb{R}^2$. Following the construction succeeding the Claim shows that $\Psi(g) = g^*$.

3. Proof of Theorem 1.1

The proof of Theorem 1.1 is the same as the proof of the corresponding theorems for spherical space forms and hyperbolic manifolds given in [BK17], apart from some minor changes, which we now explain. Section 3 of [BK17] shows that if X is a spherical space form, then we may assign to every $g \in Met(X)$ a partially defined metric (W_g, \check{g}) with sectional curvature $\equiv 1$, in a continuous manner. In our case, the corresponding result is:

Lemma 3.1. Let X be a compact, non-Haken manifold modeled on Nil, and pick $g_X \in Met_{Nil}(X)$. Then for every $g \in Met(X)$ there is a partially defined metric (W_q, \check{g}) on X (as defined in [BK17, Definition 2.3]) such that:

- (1) (W_g, \check{g}) is isometric to $(X \setminus S_g, g_X)$ for some finite (possibly empty) subset $S_g \subset X$, where the cardinality of S_g is bounded above by a continuous function of g (in the C^{∞} topology).
- (2) If $g \in Met_{Nil}(X)$ then $(W_g, \check{g}) = (X, g)$.
- (3) The assignment $g \mapsto (W_g, \check{g})$ is continuous.

Proof. Pick $g \in Met(X)$, and let \mathcal{M} be a singular Ricci flow with $\mathcal{M}_t = (X, g)$.

For every $t_1, t_2 \in [0, \infty)$, let $C_{t_1, t_2} \subset C_{t_1}$ be the set of points in C_{t_1} that survive until time t_2 , i.e. the points for which the time $(t_2 - t_1)$ -flow of the time vector field ∂_t is defined. Then C_{t_1, t_2} is an open subset of C_{t_1} , and the time $(t_2 - t_1)$ -flow of ∂_t defines a smooth map $\Phi_{t_1, t_2} : C_{t_1, t_2} \to \mathcal{M}_{t_2}$, which is a diffeomorphism onto its image.

Now let $T = T(g, \epsilon_0(X))$, where $\epsilon_0(X)$ is as in Lemma 2.13, and $T(g, \epsilon_0(X))$ is as in Theorem 2.6(4). Then by Theorem 2.6(4) the time-T slice \mathcal{M}_T satisfies the hypotheses of Lemma 2.13; we let $\widehat{g} \in \operatorname{Met}_{\operatorname{Nil}}(\mathcal{M}_T)$ be the Nil metric supplied by that lemma. We then define $(W_q, \check{g}) = (\Phi_{T,0}(C_{T,0}), (\Phi_{T,0})_*\widehat{g}).$

Properties (1)–(3) now follow as in the spherical case.

Sections 4 and 5 of [BK17] now carry over after replacing $Met_{K=1}(X)$ by $Met_{Nil}(X)$, and the Thurston geometry S^3 by Nil. Instead of [BK17, Lemma 4.3] we use:

Lemma 3.2 (Extending Nil metrics over a ball). In the following, we let S^2 and D^3 denote the unit sphere and unit disk in \mathbb{R}^3 , respectively, and we let $N_r(S^2)$ denote the metric r-neighborhood of $S^2 \subset \mathbb{R}^3$.

Suppose $m \ge 0$, $\rho > 0$ and:

- (i) $h_{m+1}: D^{m+1} \to \operatorname{Met}_{\operatorname{Nil}}(N_{\rho}(S^2) \cap D^3)$ is a continuous map such that for all $p \in D^{m+1}$, the Riemannian manifold $(N_{\rho}(S^2) \cap D^3, h_{m+1}(p))$ isometrically embeds in Nil. Here $\operatorname{Met}_{\operatorname{Nil}}(N_{\rho}(S^2) \cap D^3)$ is equipped with the $C^{\infty}_{\operatorname{loc}}$ -topology.
- (ii) $\hat{h}_m : S^m \to \operatorname{Met}_{\operatorname{Nil}}(D^3)$ is a continuous map such that for every $p \in S^m$ we have $\hat{h}_m(p) = h_{m+1}(p)$ on $N_\rho(S^2) \cap D^3$, and $(D^3, h_m(p))$ isometrically embeds in Nil.

Then, after shrinking ρ if necessary, there is a continuous map $\hat{h}_{m+1} : D^{m+1} \to \text{Met}_{\text{Nil}}(D^3)$ such that:

(a) $\hat{h}_{m+1}(p) = h_{m+1}(p) \text{ on } N_{\rho}(S^2) \cap D^3 \text{ for all } p \in D^{m+1}.$ (b) $\hat{h}_{m+1}(p) = h_m(p) \text{ for all } p \in S^m.$ (c) If for some $p \in D^{m+1}$ there is a metric $g' \in \operatorname{Met}_{\operatorname{Nil}}(D^3)$ and some $\rho' > 0$ such that $(N_{\rho'}(S^2) \cap D^3, g')$ is isometric to $(N_{\rho'}(S^2) \cap D^3, h_{m+1}(p))$, then (D^3, g') is isometric to $(D^3, \widehat{h}_{m+1}(p))$ and thus the volumes of both metrics are the same.

Proof. The proof is the same as that of [BK17, Lemma 4.3], except for the first step. Pick $x \in S^2, x' \in N$ il and consider the orthonormal basis $e'_1 := (X_1)_{x'}, e'_2 := (X_2)_{x'}, e'_3 := (X_3)_{x'} \in T_{x'}$ Nil, where X_1, X_2, X_3 denote the left-invariant vector fields from Subsection 2.1. Similarly, for any $p \in D^{m+1}$ let $f_1(p) \in T_x \mathbb{R}^3$ such that there is a local $h_{m+1}(p)$ -isometric Nil-action near x and left-invariant, positively oriented orthonormal frame E_1, E_2, E_3 with $E_3 = [E_1, E_2]$ such that $f_3(p) = (E_3)_p$. This property characterizes $f_3(p)$ uniquely and thus $f_3 : D^{m+1} \to T_x \mathbb{R}^3$ is continuous. Since D^{m+1} is contractible, we can now find $f_1, f_2 : D^{m+1} \to T_x \mathbb{R}^3$ such that $f_1(p), f_2(p), f_3(p)$ form a positively oriented $h_{m+1}(p)$ -orthonormal basis for each $p \in D^{m+1}$. It follows that there are unique isometric embeddings $\psi_{m+1}(p) : (N_\rho(S^2) \cap D^3, h_{m+1}(p)) \to Nil,$ $\widehat{\psi}_m(p) : (D^3, \widehat{h}_m(p)) \to Nil$ sending $f_1(p), f_2(p), f_3(p)$ to e'_1, e'_2, e'_3 . The remainder of the argument is the same as in [BK17, Lemma 4.3].

Assertion (c), which is new, follows easily from the uniqueness of isometric embeddings. $\hfill \Box$

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